



Switching planning

Location problem

Theoretically for the set of optimal location (X_E, Y_E) the partial derivatives of the total network cost function, *C*, with regard to X_E and Y_E are equal to zero : $\begin{bmatrix} C/\P X_E = 0 \\ \P C/\P Y_E = 0 \end{bmatrix}$ for E = 1, 2, ... NEX

Different methods for solving this 2*E equation system could be employed depending upon the methods of *measuring the distances* in the network

In the most complicated case we get a system of 2**NEX* non-linear equations

If $\partial C/\partial X_E$ and $\partial C/\partial Y_E$ are expanded into Taylor-series this leads to a system of 2*NEX linear equations in ΔX_F and ΔY_F , which can easily be solved by *standard methods*

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Switching planning Location problem - distance measurement methods Mean distance from exchange to grid element : (x_2, y_2) The mean distance from to the rectangle can then be found from: (x, y) (X_E, Y_E) $D = \frac{1}{area} \int_{X_E}^{X_2} \int_{Y_E}^{Y_2} d(X_E, Y_E, x, y) dx dy$ L, (x1, y1) 📕 (X_E , Y_E) along the hypotenuse : along the cathetie : $D(X_E, Y_E, x, y) = \sqrt{(X_E - x)^2 \cdot L_x^2 + (Y_E - y)^2 \cdot L_y^2}$ $D(X_{E}, Y_{E}, x, y) = |X_{E} - x| + |Y_{E} - y|$ Network Planning Strategy for evolving Network Architectures Session 4.2- 4

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Simplified method for location optimization

Based on the access network $\cos S_i$ only :

 $S_j = \sum_i sub(i, j) \cdot C_s(D_E) \qquad for(i, j) \in E$

For optimal locations (X_E, Y_E) the partial derivatives of the cost function $C = S_j$ with regard to X_E and Y_E are equal to zero :

 $\frac{\partial C/\partial X_E = 0}{\partial C/\partial Y_E = 0}$ for $E = 1, 2, \dots NEX$

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For a case with one location only for X_E we get:

$$\P C / \P X_E = \sum_{(i,j) \in E} [sub(i,j) \cdot C_c(D_E) \cdot \P D_E / \P X_E]$$

the partial derivative depends only on the distance

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Switching planning *Simplified Method for location optimization* With simplified distance method along the cathetie : $D(X_{E},Y_{E},i,j) = |X_{E} - j| + |Y_{E} - i|$ $We get : \qquad PC/PX_{E} = \sum_{(i,j)\in E} sub(i,j) \cdot C_{c}(D_{E}) \cdot \left\{ \begin{array}{c} -1 & if & j \ge X_{E} \\ 1 & if & X_{E} \ge j \end{array} \right\}$ $Thus : \qquad \sum_{(i,j)<x} sub(i,j) \cdot C_{c}(D_{E}) \cdot (+1) + \sum_{(i,j)>x} sub(i,j) \cdot C_{c}(D_{E}) \cdot (-1) = 0$ $Cr : \qquad \sum_{(i,j)<x} sub(i,j) \cdot C_{c}(D_{E}) = \sum_{(i,j)>x} sub(i,j) \cdot C_{c}(D_{E})$ $Thus : \qquad \sum_{(i,j)<x} sub(i,j) \cdot C_{c}(D_{E}) = \sum_{(i,j)>x} sub(i,j) \cdot C_{c}(D_{E})$

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Switching planning

Boundaries problem

Boundary optimization is finding service/exchange area boundaries in such a way that total network costs is minimized

The cost of connecting one subscriber at location (x, y), belonging to traffic zone K, to an exchange/node E at (X_E, Y_E) can thus be expressed as :

 $C(E) = C_{j}(K,E) + C_{b}(E) + D_{E} \cdot C_{s}(D_{E}) + C_{f}$

It depends of the cost of connecting the subscriber, the average exchange cost per subscriber, the backbone network cost of any subscriber

The decision for the boundary can be made simply by comparison for every grid/node element (i,j) – the value C(E) is calculated for every exchange /node E and the lowest C(E) then determines E

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Transmission planning

Optimization of ring/mesh protected transport networks

Two types of nodes could be distinguished in the network :

- traffic access nodes
 - represent the abstract traffic entry points (e.g. local exchange)
- transmission nodes
 - represent the actual network nodes (e.g. ADMs or DXCs)

Requirements to the topology for protection -

ring or mesh topologies, multi-ring structures, hybrid ring-mesh topologies
different protection schemes: path protection, link protection, path diversity

In the optimization methods are solved combinatorial problems usually with heuristic algorithms and based on the shortest path approach

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