|  |  |  |  |
| --- | --- | --- | --- |
|  | **Radiocommunication Study Groups** | |  |
| **INTERNATIONAL TELECOMMUNICATION UNION** | |  | |
|  | |  | |
| Source: Document 5A/TEMP/125 | | **Annex 30 to**  **Document 5A/298-E** | |
| **18 November 2016** | |
| **English only** | |
| Annex 30 to Working Party 5A Chairman’s Report | | | |
| WORKING DOCUMENT TOWARD A PRELIMINARY  DRAFT NEW REPORT ITU-R M.[ITS USAGE] | | | |
| Intelligent transport systems (ITS) usage in ITU Member States | | | |

(Question ITU-R 205-5/5)

TABLE OF CONTENTS

[1 Scope 4](#_Toc463513006)

[2 Background 4](#_Toc463513007)

[3 Related documents 4](#_Toc463513008)

[4 List of acronyms and abbreviations 4](#_Toc463513009)

[5 Overview of ITS radio communication and automotive radar 5](#_Toc463513010)

[5.1 ITS radiocommunication 6](#_Toc463513011)

[5.1.1 Terms and definitions 7](#_Toc463513012)

[5.1.2 Technical characteristics 7](#_Toc463513013)

[5.2 Automotive radar 8](#_Toc463513014)

[5.2.1 Terms and definitions 8](#_Toc463513015)

[5.2.2 Technical characteristics 8](#_Toc463513016)

[6 [Legacy] ITS radio communication - ETC 9](#_Toc463513017)

[6.1 Overview 9](#_Toc463513018)

[6.3 Frequency usage 9](#_Toc463513019)

[6.4 Standardization 9](#_Toc463513020)

[6.5 Applications 10](#_Toc463513021)

[6.6 Region 1 11](#_Toc463513022)

[6.6.1 Frequency usage 14](#_Toc463513023)

[6.6.2 Standardization 15](#_Toc463513024)

[6.7 Region 2 16](#_Toc463513025)

[6.7.1 Frequency usage 16](#_Toc463513026)

[6.7.2 Standardization 16](#_Toc463513027)

[6.8 Region 3 16](#_Toc463513028)

[6.8.1 Frequency usage 20](#_Toc463513029)

[6.8.2 Standardization 22](#_Toc463513030)

[7 Advanced ITS radio communication 24](#_Toc463513031)

[7.1 Overview 24](#_Toc463513032)

[7.2 Technical characteristics 26](#_Toc463513033)

[7.3 Frequency usage 30](#_Toc463513034)

[7.4 Standardization 33](#_Toc463513035)

[7.5 Applications](#_Toc463513036) 35

[7.6 Region 1 41](#_Toc463513037)

[7.6.1 Frequency usage 41](#_Toc463513038)

[7.6.2 Standardization 41](#_Toc463513039)

[7.7 Region 2 41](#_Toc463513040)

[7.7.1 Frequency usage 42](#_Toc463513041)

[7.7.2 Standardization 42](#_Toc463513042)

[7.8 Region 3 42](#_Toc463513043)

[7.8.1 Frequency usage 42](#_Toc463513044)

[7.8.2 Standardization 42](#_Toc463513045)

[8 Millimetre-wave automotive radar 43](#_Toc463513047)

[8.1 Overview 43](#_Toc463513048)

[8.2 Technical characteristics 43](#_Toc463513049)

[8.3 Frequency usage 45](#_Toc463513050)

[8.4 Standardization 46](#_Toc463513051)

[8.5 Applications 46](#_Toc463513052)

[8.6 Region 1 46](#_Toc463513053)

[8.6.1 Frequency usage 46](#_Toc463513054)

[8.6.2 Standardization 47](#_Toc463513055)

[8.7 Region 2 47](#_Toc463513056)

[8.7.1 Frequency usage 47](#_Toc463513057)

[8.7.2 Standardization 47](#_Toc463513058)

[8.8 Region 3 48](#_Toc463513059)

[8.8.1 Frequency usage 48](#_Toc463513060)

[8.8.2 Standardization 49](#_Toc463513061)

[9 Conclusions 51](#_Toc463513062)

*[Editor’s note: All the texts may be addressed in future contributions to this document.]*

*[Editor’s note: Renumbering is required for the figures and tables.]*

# 1 Scope

This report addresses the usages of Intelligent Transport System (ITS) radio communication applications, such as vehicle to infrastructure, vehicle to vehicle, vehicle to pedestrian communications for traffic safety related and traffic efficiency applications as well as electronic tolling systems and automotive radars for collision avoidance in ITU Member states.

# 2 Background

*[Editor’s note: Text described on relationship with WRC-19 Agenda Item 1.12 to be added.]*

Asia-Pacific Telecommunity (APT) already published an APT Report on “The usage of intelligent transport systems in APT Countries” [Revision 2 ([APT/AWG/REP-18](http://www.aptsec.org/sites/default/files/2016/09/AWG-20-TMP-44_ITS_USAGE_Consolidated_R2_clear.docx)) which APT contributed to WP 5A in November 2016 (Document [5A/248](http://www.itu.int/md/R15-WP5A-C-0248/en))].

# 3 Related documents

ITU-R Recommendations:

ITU-R M.1890 Intelligent transport systems – Guidelines and objectives

ITU-R M.1452 Millimetre wave radiocommunication systems for Intelligent Transport Systems applications

ITU-R M.1453 Intelligent Transport Systems – dedicated short-range communications at 5.8 GHz

ITU-R M.2057 Systems characteristics of automotive radars operating in the frequency band 76-81 GHz for intelligent transport systems applications

ITU-R Report:

ITU-R M.2228 Advanced intelligent transport systems (ITS) radiocommunication

ITU-R M.2322 Systems characteristics and compatibility of automotive radars operating in the frequency band 77.5-78 GHz for sharing studies

ITU-R Handbook:

Land Mobile (including Wireless Access) - Volume 4:   
 Intelligent Transport Systems

# 4 List of acronyms and abbreviations

3GPP The 3rd Generation Partnership Project

APT Asia-Pacific Telecommunity

ARIB Association of Radio Industries and Businesses

ATIS Alliance for Telecommunications Industry Solutions

AWG APT Wireless Group

C-ITS Cooperative ITS communication

C2C- CC CAR-to-CAR Communication Consortium

CAMP Crash Avoidance Metric Partnership

CCSA China Communications Standards Association

CEN European Committee for Standardization

CEPT European Conference of Postal and Telecommunications Administrations

ECC Electronic Communications Committee

ETSI European Telecommunications Standards Institute

FCC Federal Communications Commission

IEEE Institute of Electrical and Electronics Engineers

IMDA Infocomm Media Development Authority

ISO International Organization for Standardization

ITS Intelligent Transport Systems

LTE Long Term Evolution

RLAN Radio Local Area Network

RSS Radio Standards Specification

TIA Telecommunications Industry Association

TSAC Telecommunications Standards Advisory Committee

TTA Telecommunication Technology Association

V2I Vehicle to Infrastructure

V2N Vehicle to Network

V2P Vehicle to Pedestrians

V2V Vehicle to Vehicle

V2X Vehicle to Infrastructure/Vehicle/Network/Pedestrians and others

WAVE Wireless Access in Vehicular Environments

WLAN Wireless Local Area Network

# 5 Overview of ITS radio communication and automotive radar

Since several decades ago, traffic congestion has been increasing all over the world as a result of increased motorization, urbanization, population growth, and changes in population density. Congestion reduces efficiency of transportation infrastructure and increases travel time, air pollution, and fuel consumption. Interest in ITS comes from the problems caused by traffic congestion and a synergy of new information technology for simulation, real-time control, and communications networks. Namely, ITS is systems to support transportation of goods and humans with information and communication technologies in order to efficiently and safely use the transport infrastructure and transport means (cars, trains, planes, ships)[1].

Figure 1

Communication technologies and services for ITS[2]



ITS have been standardized and studied in various standards development organizations. As an international level, ITU-R, ISO TC 204, and IEEE are working on developing the standards, recommendations and reports.

In Asia-Pacific, AWG is working as a regional level as well as ARIB, TTA, IMDA TSAC and other standard organizations in each countries and regions. In Europe, ETSI TC ITS and CEN TC278 are working as a regional level.

This report identifies current and planned usage of ITS technologies, frequency bands, status of applications and deployment in ITU Member States.

The major deployed ITS systems in the world were classified as electronic toll collection, automotive radar, and vehicle information & communication. In this report, we described applications overview, established standards, frequency plan, and implication in each ITS system.

## 5.1 ITS radio communication

Electronic toll collection allows for the manual in-lane toll collection process to be automated in such a way that drivers do not have to stop and pay cash at a toll booth. ETC systems improve traffic flow at toll plazas, and the level of pollution by reducing fuel consumption. In addition, allowing traffic to pass through the gate without stopping can increase road capacity by three or four times and relieve traffic congestion at the tollgate. It is also expected that ETC systems will reduce the operating costs of toll roads by replacing manual toll collection.

Since 1994, Vehicle Information and Communication System (VICS) has been using in Japan for delivering traffic and travel information to road vehicle drivers.

Nowadays, to extend beyond the existing ITS applications and to achieve traffic safety enhancement and reduce the environmental impact by the transportation sector, vehicle-to-vehicle (V2V), vehicle-to-infrastructure (V2I), infrastructure-to-vehicle (I2V) communications are studied. According to this progress, ITU-R WP 5A has developed report on advanced ITS radiocommunication[3]. In the report, legacy ITS and advanced ITS are classified by its technical characteristics as shown in Table x, Wireless Access in Vehicular Environments (WAVE) and Continuous Access for Land Mobiles (CALM) technologies could be inclusive in advanced ITS category.

### 5.1.1 Terms and definitions

*[Editor´s note: following terms and definitions should be revised in the document according to the following]*

|  |  |
| --- | --- |
| Dedicated Short Range Communication (DSRC) | **Europe:** road tolling and similar applications |
| **North America**: vehicle-to-vehicle and vehicle –to-infrastructure communication based on IEEE 802.11p / WAVE technology in 5.9 GHz, comparable to C-ITS based on IEEE 802.11p / ITS-G5 in Europe. |
| **Japan**: technology for ETC, road tolling and vehicle-to-infrastructure traffic information systems |
| Legacy ITS | * TTT: Transport and Traffic Telematic, mainly in Region 1, also called DSRC in Europe   + CEN DSRC tolling   + HDR DSRC tolling, * ETC: In Japan, Korea and China |
| Advanced ITS | Cooperative ITS (C-ITS) building on ad hoc networks with vehicle-to-vehicle (V2V) and vehicle-to-infrastructure communication (V2I), together called vehicle-to-X (V2X), e.g.   * + V2X (ETSI ITS-G5, IEEE 802.11p) or V2X (ETSI ITS-G5)   + V2X (LTE based V2X)   + V2X (WAVE, IEEE 802.11p) or V2X (WAVE), also called DSRC in US |

The term DSRC has different meanings in the regions. Therefore the term DSRC is not used in this report. Instead all ITS technologies in this document are structured in the legacy ITS (already existing in the market for several years) and advanced ITS (shortly deployed or in deployment phase).

*[Editor´s note: The sentence above requires to review the document according to above definitions.]*

### 5.1.2 Technical characteristics

Table 1

Technical characteristic of legacy ITS and advanced ITS

|  |  |  |
| --- | --- | --- |
| Items | Legacy ITS | Advanced ITS |
| Technologies | TTT  ETC | ETSI ITS-G5, IEEE 802.11p  WAVE, IEEE 802.11p  LTE-V2X |
| Vehicular networking | V2I | V2X includes V2I, V2V, V2N, V2P |
| Radio performance | Radio coverage: Max. 100 m  Data rate: ~ 4 Mbps  Packet size: ~100 bytes | Radio coverage: Max. 1 000 m  Data rate: Max. 27 Mbps  Packet size: Max. 2 kbytes  Latency: within 100 msec  within 1000 msec for V2P |

## 5.2 Automotive radar

Automotive radar facilitates various functions which increase the driver’s safety and convenience.

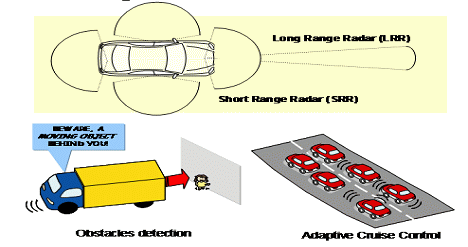
Exact measurement of distance and relative speed of objects in front, beside, or behind the car allows the realization of systems which improve the driver’s ability to perceive objects during bad optical visibility or objects hidden in the blind spot during parking or changing lanes. Radar technology has proved its ability for automotive applications for several years. Automotive radar systems are of two categories according to the applications and frequency band

− Automatic Cruise Control 'long-range radar' (usually operating at 76 GHz band).   
This enables a vehicle to maintain a cruising distance from a vehicle in front.

− Anti-collision 'short-range radar' (usually operating at 24 GHz and 79 GHz bands).   
This is being developed as part of a system to warn the driver of a pending collision, enabling avoiding action to be taken. In the event where collision is inevitable, the vehicle may prepare itself (for example by applying brakes, pre-tensioning seat belts) to minimize injury to passengers and others.

Figure x

Automotive radar



### 5.2.1 Terms and definitions

*[Editor’s note: Text to be added]*

### 5.2.2 Technical characteristics

*[Editor’s note: Text to be added]*

# 6 [Legacy] ITS radiocommunication - ETC

## 6.1 Overview

Electronic toll collection (ETC) allows for the manual in-lane toll collection process to be automated in such a way that drivers do not have to stop and pay cash at a toll booth. ETC systems improve traffic flow at toll plazas, and the level of pollution by reducing fuel consumption. In addition, allowing traffic to pass through the gate without stopping can increase road capacity by three or four times and relieve traffic congestion at the tollgate. It is also expected that ETC systems will reduce the operating costs of toll roads by replacing manual toll collection.

There are many similar words related to ETC. In Europe, Electronic Fee Collection (EFC) is popularly used. They think that EFC covers ETC, Electronic Parking System (EPS), Electronic Road Pricing. Electronic Road Pricing is usually referred to the electronic toll collection scheme adopted in Singapore for purposes of congestion pricing. To avoid confusion, these terminologies need to be clearly defined.

## 6.2 Technical characteristics

DSRC refers to a dedicated short range communication between a roadside infrastructure and vehicles or mobile platforms for ITS applications.

The two major components of DSRC are on-board equipment (OBE) and roadside equipment (RSE).

**On-board equipment (OBE):** OBE is attached near the dashboard or on the windshield of the vehicle, and consists of radiocommunication circuits, an application processing circuit and so on. It usually has a human-machine interface, including switches, displays and buzzer.

**Roadside equipment (RSE):** RSE is installed above or alongside the road and communicates with passing OBE by use of radio signals. RSE consists of radiocommunication circuits, an application processing circuit and so on. It usually has a link to the roadside infrastructure to exchange data.

DSRC systems operate by transmitting radio signals for the exchange of data between vehicle mounted OBE and RSE. This exchange of data demands high reliability and user privacy as it may involve financial and other transactions.

## 6.3 Frequency usage

*[Editor’s note: Text to be added]*

## 6.4 Standardization

Table [X]

Global Standard on ETC

|  |  |  |
| --- | --- | --- |
| SDO | Standard No. | Standard Title |
| ITU | ITU-R M.1453-2 | Intelligent transport systems – dedicated short range communications at 5.8 GHz |

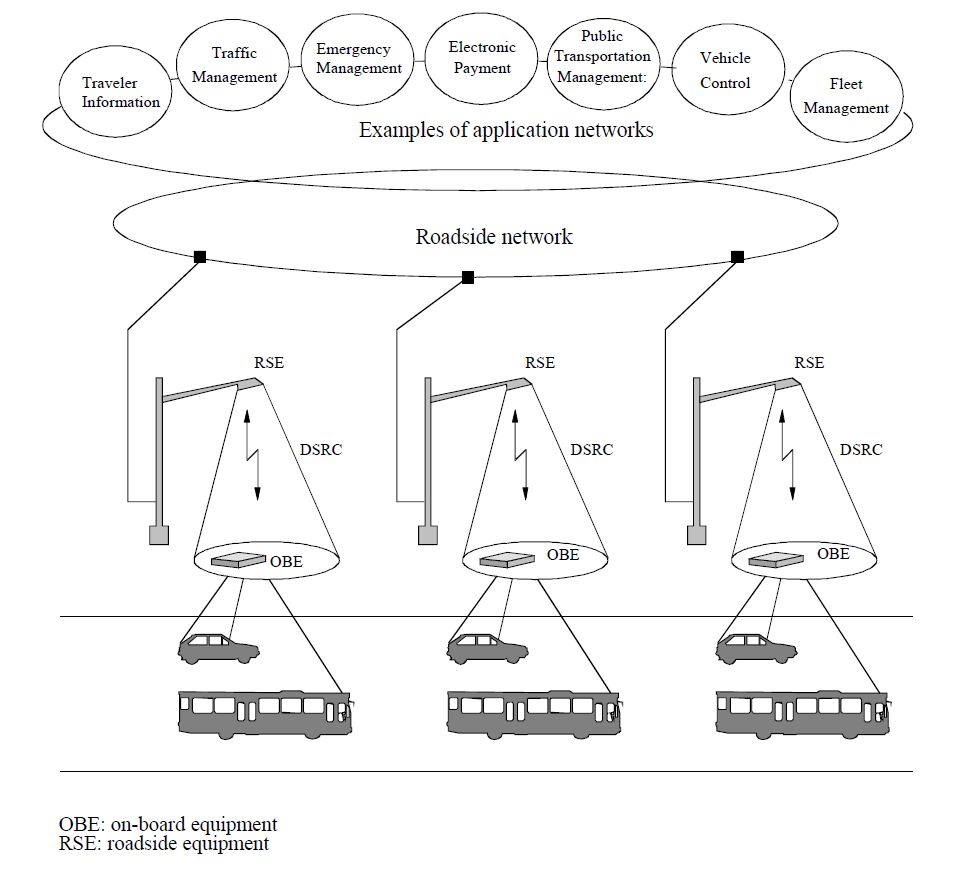
Dedicated Short Range Communication (DSRC) refers to any short-range radiocommunication technology from a roadside infrastructure to a vehicle or a mobile platform [4]. Although DSRC can be applied to various application of ITS (e.g. parking payment, gas (fuel) payment, in-vehicle signing, traffic information, etc.), ETC is the most typical one. Table [X] shows the established DSRC standards.

## 6.5 Applications

DSRC is the use of non-voice radio techniques to transfer data over short distances between roadside and mobile radio units to perform operations related to the improvement of traffic flow, traffic safety and other intelligent transport service applications in a variety of public and commercial environments. DSRC services include vehicle control systems, traffic management systems, traveller information systems, public transportation systems, fleet management systems, emergency management systems and electronic payment services.

Figure [X]

Interrelation of DSRC with ITS communication networks



## 6.6 Region 1

In 1992, the CEPT (European Conference of Postal and Telecommunications Administrations) – ERC (European Radio communications Committee) agreed on ERC Decision (92)02 designating frequency bands for the development of a fully Integrated Road Transport system in order to improve all aspects of road transport. It was decided to designate the frequency band 5 795‑5 805 MHz on a European basis, with an additional sub-band 5 805-5 815 MHz on a national basis, to meet the requirements of multilane road junctions. The frequency bands were foreseen for initial road-to-vehicle systems, in particular for road toll systems for which requirements had emerged in a number of European countries at that time. In 2002, the Electronic Communications Committee (ECC) withdrew ERC Decision (92)02 and replaced it by ECC Decision (02)01, entering in force on 15 March 2002.

Based on the ECC Decision, standards for DSRC for ITS applications have been developed by European Committee for Standardization (CEN) and European Telecommunications Standards Institute (ETSI). A standard for the Physical Layer using Microwaves at 5.8 GHz (CEN EN 12253) describes radiocommunication and RF parameter values necessary for co-existence and interoperability of DSRC systems. This standard forms part of the DSRC family of standards consisting of four standards covering the protocol layers 1, 2 and 7 of the Open Systems Interconnection (OSI) protocol stacks and profiles for RTTT (Road Transport and Traffic Telematics) applications. All these CEN standards were approved and published in 2003 and 2004.

The harmonized ETSI standard EN 300 674-2: “Dedicated Short Range Communication (DSRC) transmission equipment (500 kbit/s / 250 kbit/s) operating in the 5.8 GHz Industrial, Scientific and Medical (ISM) band” was approved and published in 2004. This standard contains general and environmental test conditions, methods of measurements and parameter limits.

The use of this harmonized ETSI standard gives a presumption of conformity to article 3 of the Directive 1999/5/EC of the European Parliament and of the (R&TTE Directive).

***[****Editor´s Note: The following technical characteristics will be included in section 6.1 overview at a later stage]****]***

**Technical characteristics**

(1) Passive Backscatter Method

European DSRC systems adopt the passive backscatter (transponder) method. This method does not have an internal oscillator for generating a 5.8 GHz band radio carrier signal in the on board equipment (OBE), so it relies on the 5.8 GHz oscillator of the roadside unit with which it communicates. A detailed explanation is given in Figure 4.3 with a typical functional block diagram.

As the passive transponder does not have a carrier signal oscillator, when transmitting from the OBE, the roadside unit has to emit an unmodulated carrier signal continuously. The OBE receives this signal, which is fed to the transmission circuit and makes it its own carrier signal (B). The transmission data from the main processing unit modulates the output of the sub-carrier signal oscillator C and mixes it with the carrier signal from the receiver. Resultant sideband signals carrying transmission data with different frequencies (carrier signal frequency plus/minus sub carrier frequency) from the carrier signal are transmitted with the carrier signal. The sub-carrier modulation method is utilized to extend the communication zone through reduction of the carrier phase noise and to reduce the re-use distance of RSE in passive transponder system. The modulated signal from the RSE is detected in the detector and processed by the main processing unit as receiving data. The communication zone of the passive (transponder) system is very small, typically up to 10 or 20 meters in front of the RSE. To extend the communication zone to some degree, additional radio frequency amplifier D may be inserted into the transmission circuit of the transponder.

One of the significant features of the passive backscatter method is a narrow communication zone, typically up to 10 or 20 meters in front of the RSE. This characteristic, i.e. communications can only take place at a precise point, is particularly important to correctly locate the vehicle. There are many applications utilizing this characteristic such as Electronic Toll Collection (ETC), Automatic Vehicle Identification (AVI) etc. Another feature of the passive backscatter method is that the structure of the OBE is simple and results in low manufacturing costs.

Figure [X]

Typical configuration of OBE in passive backscatter method

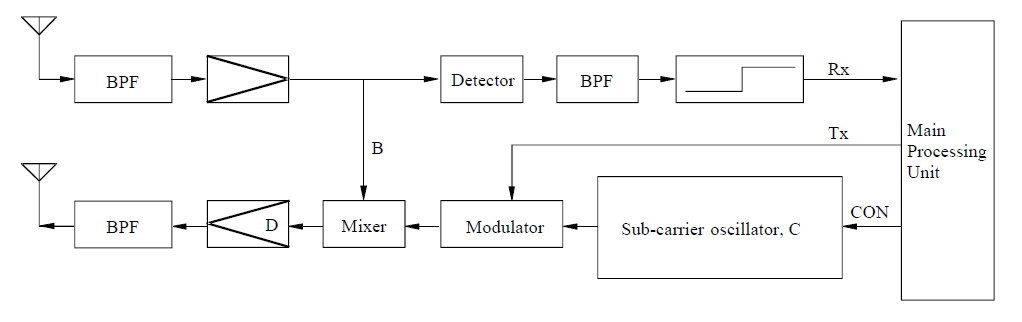


Figure [X] shows the RSE and OBE transmission timing chart and Figure [X] shows the RSE and OBE transmission spectrum in passive backscatter method.

Figure [X]

Transmission timing chart in passive backscatter method

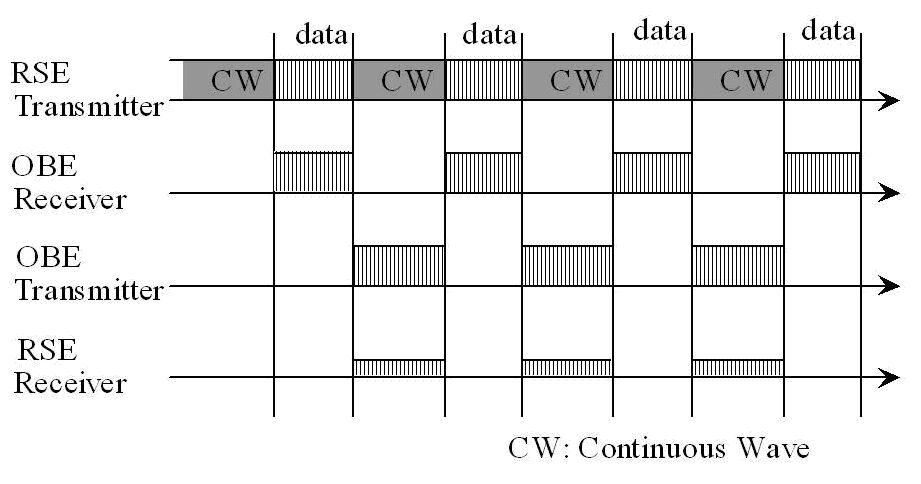
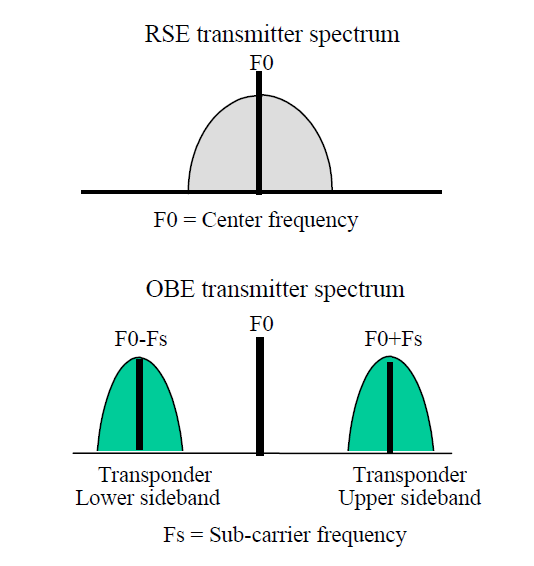


FIGURE [X]

RSE and OBE transmission spectrum in passive backscatter method



(2) Technical Characteristics of the European Backscatter Method

Technical characteristics of the European backscatter (transponder) method are shown in Table [X] which is an excerpt from Recommendation ITU-R M.1453-2. The Recommendation incorporates the “Medium data rate” European standard (CEN EN 12253) as well as the “High data rate” Italian standard into a single Recommendation.

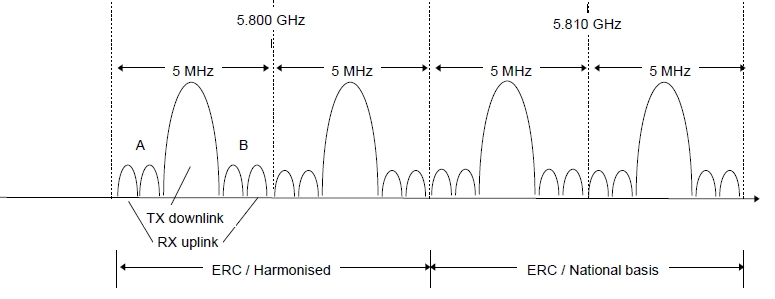
In the European DSRC standard, the OBE supports two kinds of sub-carrier frequencies (1.5 MHz and 2.0 MHz). Selection of sub-carrier frequency depends on the profile indicated by the RSE. (1.5 MHz is recommended). Frequency spectrum of “Medium data rate” European standard is shown in Figure [X].

In the case of “High data Rate” Italian standard, the OBE uplink sub-carrier frequency is 10.7 MHz, resulting in higher uplink data transmission speed.

Frequency spectrum of the “High data rate” Italian standard is shown in Figure [X].

Figure [X]

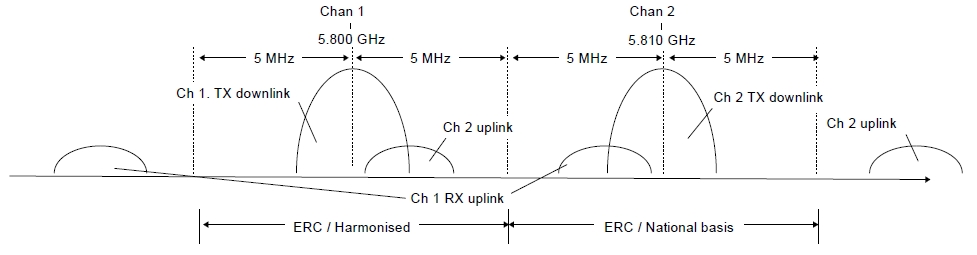
Frequency spectrum of “Medium data rate” European standard



(RAST6(98)29　“Intelligent Transportation System – An ETSI View”)

Figure [X]

Frequency spectrum of “High data rate” Italian standard



(RAST6(98)29　“Intelligent Transportation System - An ETSI View”)

Table [X]

Characteristics of backscatter (transponder) method

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| Item | Technical characteristic | | | |
| Medium data rate | | High data rate | |
| Carrier frequencies | | 5.8 GHz band for downlink | | 5.8 GHz band for downlink | |
| Sub-carrier frequencies | | 1.5 MHz/2 MHz (uplink) | | 10.7 MHz (uplink) | |
| RF carrier spacing (channel separation) | | 5 MHz | | 10 MHz | |
| Allowable occupied bandwidth | | Less than 5 MHz/channel | | Less than 10 MHz/channel | |
| Modulation method | | ASK (downlink carrier) PSK (uplink sub-carrier) | | ASK (downlink carrier) PSK (uplink sub-carrier) | |
| Data transmission speed (bit rate) | | 500 kbit/s (downlink) 250 kbit/s (uplink) | | 1 Mbit/s (downlink) 1 Mbit/s (uplink) | |
| Data coding | | FM0 (downlink) NRZI (uplink) | |  | |
| Communication type | | Transponder type | | Transponder type | |
| Maximum e.i.r.p.(1) | | ≤ +33 dBm (downlink) ≤ –24 dBm (uplink: single sideband) | | ≤ +39 dBm (downlink) ≤ –14 dBm (uplink: single sideband) | |
| (1) ERC Recommendation 70-03 specifies values of 2 W e.i.r.p. for active and 8 W e.i.r.p. for passive systems. | | | | | |

### 6.6.1 Frequency usage

TABLE [X]

Frequency usage for ETC in Europe

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| Country | Frequency Band | Technology/ Standard | Service | Deployment or plan Year |
| Europe | 5 795-5 805 MHz  [5 805-5 815 MHz] | DSRC | Electronic Toll Collection | Enacted in [19XX] |

### 6.6.2 Standardization

TABLE [X]

Standard for ETC in Europe

|  |  |  |
| --- | --- | --- |
| SDO | Standard No. | Standard Title |
| ETSI | EN 300 674 | Road Transport and Traffic Telematics (RTTT); Dedicated Short Range Communication (DSRC) transmission equipment (500 kbit/s / 250 kbit/s) operating in the 5,8 GHz Industrial, Scientific and Medical (ISM) band |
| ETSI EN 300 674-2-1 | Transport and Traffic Telematics (TTT); Dedicated Short Range Communication (DSRC) transmission equipment (500 kbit/s / 250 kbit/s) operating in the 5.8 GHz Industrial, Scientific and Medical (ISM) band; Part 2: Harmonised Standard covering the essential requirements of article 3.2 of the Directive 2014/53/EU; Sub-part 1: Road Side Units (RSU) |
| ETSI EN 300 674-2-2 | Transport and Traffic Telematics (TTT); Dedicated Short Range Communication (DSRC) transmission equipment (500 kbit/s / 250 kbit/s) operating in the 5.8 GHz Industrial, Scientific and Medical (ISM) band; Part 2: Harmonised Standard covering the essential requirements of article 3.2 of the Directive 2014/53/EU; Sub-part 2: On-Board Units (OBU) |
| TS 102 486 | Test specifications for DSRC transmission equipment |

***[****Editor´s Note: The following text related to applications to be shifted to Chapter 6.1 with legacy ITS application overview over all three regions****]***

**Applications**

(1) General

A large number of European countries are implementing electronic toll collection (ETC) system based on DSRC technology. ETC applications are considered to be a major driving force that will create the new market for a large number of DSRC equipment which provides the versatile services for other DSRC based applications. In addition to ETC, applications such as access control, parking management and payment, traffic information and emergency warning, freight and fleet management, traffic control etc. are proposed as ITS services in Europe. These applications are expected to be implemented significantly when ETC using DSRC technology becomes widely used.

The European project DELTA (DSRC Electronics Implementation for Transportation and Automotive applications) is aiming to integrate the DSRC communication link as basic equipment in any vehicle. The following list includes such possible future ITS applications.

– In-vehicle Signing to Assist for Safe Driving (Obtaining roadside traffic and travel information)

– Parking Garage Fee Payment

– MP3 Music Download While Fuelling

– Vehicle status for car rental automatic billing

– Software Installation (Service facility installs fleet management software on the vehicle)

– Mission Planning (A fleet operator plans and downloads mission data to the vehicle)

– Floating Car Data (Acquisition of travel-related information via DSRC)

– Multimodal Transport Information (Display of public transport vehicle information)

– Vehicle Control (Adaptive automatic cruise control)

– Service subscription

– Diagnostics (Service technician diagnostics fault via DSRC).

It should be noted, that for many of these services, there are competing technologies e.g. mobile communications with satellite positioning (GNSS). However, the specific characteristics of DSRC such as high data integrity (highly reliability) and low transmission latency (real time) will make it possible for DSRC to be used for most services associated with these applications.

Typical applications utilizing favourable characteristics of passive DSRC are described below. These applications are standardized within the European Committee for Standardization (CEN).

## 6.7 Region 2

*[Editor’s note: Text to be added]*

### 6.7.1 Frequency usage

TABLE [X]

Frequency usage for ETC in North and South America

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| Country | Frequency Band | Technology/ Standard | Service | Deployment or plan Year |
| U.S.A. | 902-928 MHz, | DSRC | Electronic Toll Collection | Enacted in [19XX] |
| Canada | 902-928 MHz | [RSS 137](https://www.ic.gc.ca/eic/site/smt-gst.nsf/vwapj/rss137.pdf/$FILE/rss137.pdf) | Electronic Toll Collection | Enacted in [1999] |
| Mexico | 902-928 MHz | DSRC | Electronic Toll Collection | Enacted in [19XX] |

### 6.7.2 Standardization

Table [X]

Standard for ETC in North and South America

|  |  |  |
| --- | --- | --- |
| SDO | Standard No. | Standard Title |
|  |  |  |
|  |  |

## 6.8 Region 3

***[****Editor´s Note: The following technical characteristics will be included in section 6.1 overview at a later stage]****]***

**Technical characteristics**

(1) Active (transceiver) method

The Japanese DSRC System adopts the active (transceiver) method. For the active (transceiver) method, the on-board equipment (OBE) is equipped with the same functions as roadside equipment (RSE) which is equipped with devices necessary for radiocommunication. More specifically, both RSE and OBE incorporate a 5.8 GHz band carrier frequency oscillator and have the same functionality for radio transmission. Figure [X] shows a typical block diagram for the OBE’s radio circuitry. The upper half of Figure[X] is the receiver, the lower half is the transmitter and the processing unit is to the right. The transmission and reception antennas may be shared. The OBE in the active (transceiver) method receives radio signals from the RSE with the antenna on the upper left. Each signal received passes through each functional block and is processed by the main processing unit as reception data. The transmission signal from the OBE is the 5.8 GHz band carrier signal from oscillator A modulated with transmission data. The signal is sent from the antenna on the bottomleft.

The active (transceiver) method can easily realize small or large communication zones by controlling the directivity of transmission antenna. Figure [X] shows examples of flexible communication zones forming in the typical configuration of the ETC gate. The footprint (communication zone) of an ETC antenna is very small (typically 3 m x 4 m). On the other hand, a large footprint of up to 30 meters in length can be realized by approach antenna for information dissemination. The Bit Error Rate (BER) within the footprints is very low (Less than 10-5). The main feature of the active (transceiver) method is a flexible zone forming, in addition to large volumes of information to be communicated with high reliability. These characteristics are indispensable for various ITS application services using DSRC.

Figure [X]

Typical configuration of OBE in active transceiver [ASK] method

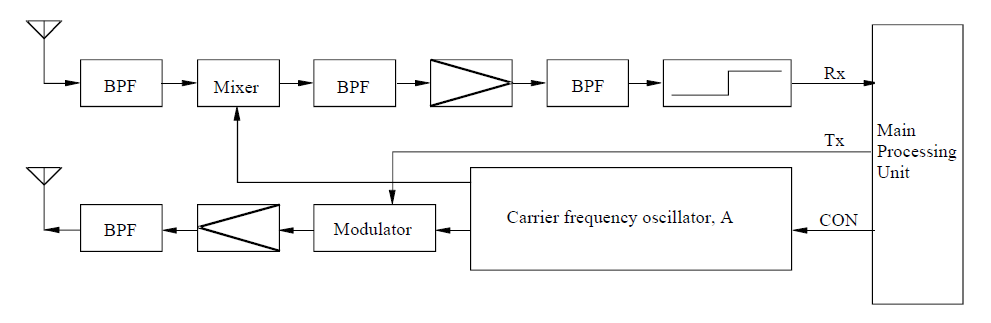
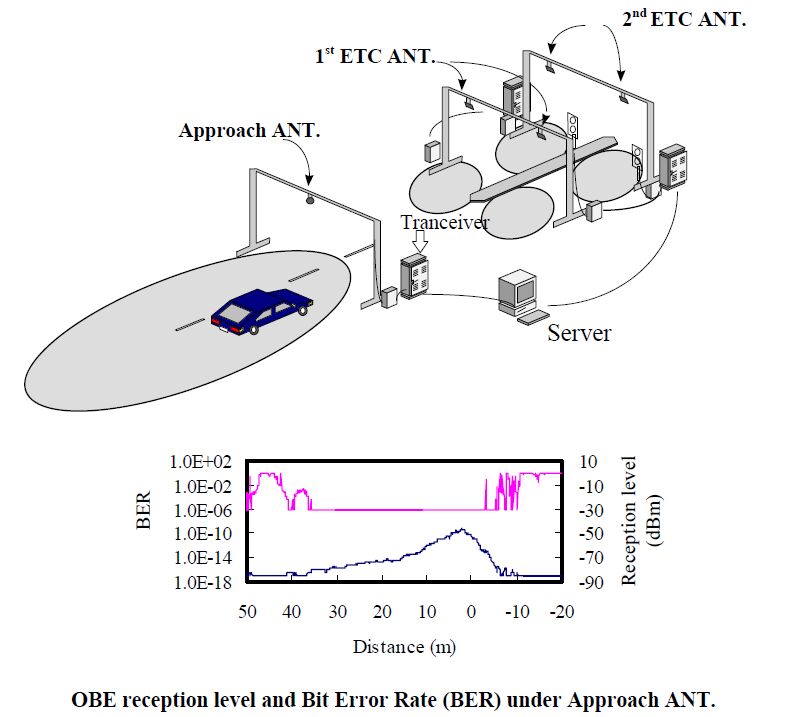


Figure [X]

Examples of DSRC antenna footprints in typical ETC toll gate



(2) Technical Characteristics of the Japanese Active Method

Technical characteristics of the Japanese active (transceiver) method are shown in Table 4.2, which is also an excerpt from Recommendation ITU-R M.1453-2. In this table there are two specifications in RF carrier spacing column. Wide spacing (10 MHz channel separation) is mainly for current ETC application with the ASK (Amplitude Shift Keying) modulation method. Narrow spacing (5 MHz channel separation) is for multi purpose DSRC application services with the ASK and/or QPSK (Quadrature Phase Shift Keying) modulation method. Specifications for the narrow spacing was added in October 2000, when the Japanese Ministry of Posts and Telecommunications (now MIC) revised the radio law according to the proposal of the Telecommunications Technology Council on general purpose DSRC system applications. The revision was proposed to and adopted by the ITU-R as the modified DSRC Recommendation ITU-R M.1453-1 in August 2002.

The maximum communication zone of DSRC is recommended to be within 30 meters to promote effective use of frequencies by reducing the re-use distance of RSE. FDD (Frequency Division Duplex) systems are also adopted to promote effective use of radio frequencies.

Technical characteristics of the Japanese active (transceiver) method are shown in Table 4.2, which is also an excerpt from Recommendation ITU-R M.1453-2. In this table there are two specifications in RF carrier spacing column. Wide spacing (10 MHz channel separation) is mainly for current ETC application with the ASK (Amplitude Shift Keying) modulation method. Narrow spacing (5 MHz channel separation) is for multi purpose DSRC application services with the ASK and/or QPSK (Quadrature Phase Shift Keying) modulation method. Specifications for the narrow spacing was added in October 2000, when the Japanese Ministry of Posts and Telecommunications (now MIC) revised the radio law according to the proposal of the Telecommunications Technology Council on general purpose DSRC system applications. The revision was proposed to and adopted by the ITU-R as the modified DSRC Recommendation ITU-R M.1453-1 in August 2002.

The maximum communication zone of DSRC is recommended to be within 30 meters to promote effective use of frequencies by reducing the re-use distance of RSE. FDD (Frequency Division Duplex) systems are also adopted to promote effective use of radio frequencies.

Table [X]

Characteristics of active (transceiver) method

|  |  |  |
| --- | --- | --- |
| Item | Technical characteristic | |
| Carrier frequencies | 5.8 GHz band for downlink and uplink | |
| RF carrier spacing (channel separation) | 5 MHz |  |
| Allowable occupied bandwidth | Less than 4.4 MHz |  |
| Modulation method | ASK, QPSK |  |
| Data transmission speed (bit rate) | 1 024 kbit/s/ASK, 4 096 kbit/s/QPSK |  |
| Data coding | Manchester coding/ASK, NRZ/QPSK |  |
| Duplex separation | 40 MHz in case of FDD | |
| Communication type | Transceiver type | |
| Maximum e.i.r.p.(1) | ≤ 30 dBm (downlink)  (For a transmission distance of 10 m or less. Power supplied to antenna ≤ 10 dBm) | |
| ≤ 44.7 dBm (downlink)  (For a transmission distance of more than 10 m. Power supplied to antenna ≤ 24.77 dBm) | |
| ≤ 20 dBm (uplink)  (Power supplied to antenna ≤ 10 dBm) | |
| (1) European Radiocommunications Committee (ERC) Recommendation 70-03 specifies values of 2W e.i.r.p. for active and 8 W e.i.r.p. for passive systems. | | |

**(3) Technical characteristics of the Chinese ETC System**

The Chinese ETC System adopts the active (transceiver) method. Both RSE and OBE work in 5.8 GHz band. Two classes are specified in the physical layer. Class A with ASK modulation should meet the basic requirement of ETC application. Class B with FSK modulation should meet the requirement of high speed data transmission. Technical characteristics of downlink and uplink are shown in Table 3 and 4, respectively.

Table 3

Technical characteristics of downlink

|  |  |  |  |
| --- | --- | --- | --- |
| **Item** | | **Class A** | **Class B** |
| Carrier frequencies | Channel 1 | 5.830 GHz | 5.830 GHz |
| Channel 2 | 5.840 GHz | 5.840 GHz |
| Allowable occupied bandwidth | | ≤5 MHz | ≤5 MHz |
| Modulation method | | ASK | FSK |
| Data transmission speed (bit rate) | | 256 kbit/s | 1 Mbit/s |
| Data coding | | FM0 | Manchester |
| e.i.r.p. | | ≤ +33 dBm | ≤ +33 dBm |

Table 4

Technical characteristics of uplink

|  |  |  |  |
| --- | --- | --- | --- |
| **Item** | | **Class A** | **Class B** |
| Carrier frequencies | Channel 1 | 5.790 GHz | 5.790 GHz |
| Channel 2 | 5.800 GHz | 5.800 GHz |
| Allowable occupied bandwidth | | ≤5 MHz | ≤5 MHz |
| Modulation method | | ASK | FSK |
| Data transmission speed (bit rate) | | 512 kbit/s | 1 Mbit/s |
| Data coding | | FM0 | Manchester |
| e.i.r.p. | | ≤ +10 dBm | ≤ +10 dBm |

### 6.8.1 Frequency usage

The usage status of ETC in APT countries is shown in Table 2. Many APT countries adopted ETC in frequency band of 2.4, 5.8, 5.9 and 24 GHz. For ETC in some APT countries, DSRC technology and 5.8 GHz band has been used.

Table [X]

Frequency usage for ETC in Asia-Pacific

| Country | Frequency Band | Technology/ Standard | Application | Deployment or plan Year |
| --- | --- | --- | --- | --- |
| Australia | 5,725-5,795 MHz,  5,815-5,875 MHz,  24-24.25 GHz | - | Electronic tolling | - |
| China | 5,725-5,850 MHz | DSRC | ETC (Electronic Toll Collection) | Enacted in 2003 |
| Hong Kong | 2,400–2,4835 MHz | Exemption from Licensing Order | Electronic toll collection services | 1998 |
| Japan | 5,770-5,850 MHz | ETC (Electronic Toll Collection) | Collect highway toll (Communication) | Enacted in 1997 |
| DSRC  (Dedicated Short Range Communication) | -Collect highway toll -Provide various information (Communication, Broadcast) | Enacted in 2001  (Revised 2008) |
| Korea | 5,795-5,815 MHz | DSRC/  TTA Standard  (TTAS.KO-06.0025/R1) | ETC (Electronic Toll Collection)  BIS(Bus Information System) | 2006  (Highpass Tolling) |
| Singapore | 2,350-2,483.5 MHz | - | Electronic Road Pricing (ERP) Systems | 1998 |
| 5,855-5,925 MHz | DSRC  (Dedicated Short Range Communication) | Next Generation Electronic Road Pricing (ERP) Systems | 2020 (estimated) |
| Thailand | 5.470-5.850 GHz | Compliance Standard:  ETSI EN 300 440-1 or FCC Part 15.247 or  FCC Part 15.249 | RFID (e.g. Electronic Toll Collection) | 2008 |

### 6.8.2 Standardization

Table [X]

Standard for ETC in Asia-Pacific

|  |  |  |
| --- | --- | --- |
| SDO | Standard No. | Standard Title |
| TTA | TTAS.KO-06.0025/R1 | Standard of DSRC Radio Communication between Road-side Equipment and On-board Equipment in 5.8 GHz band |
| TTAS.KO-06.0052/R1 | Test specification for DSRC L2 at 5.8GHz |
| TTAS.KO-06.0053/R1 | Test specification for DSRC L7 at 5.8GHz |
| ARIB | STD-T75 | Dedicated Short Range Communication (DSRC) System |
| SAC (Standardization Administration of China) | GB/T 20851.1-2007 | Electrical toll collection – Dedicated short range communication – Part 1: Physical layer |
| GB/T 20851.2-2007 | Electrical toll collection – Dedicated short range communication – Part 2: Data link layer |
| GB/T 20851.3-2007 | Electrical toll collection – Dedicated short range communication – Part 3: Application layer |
| GB/T 20851.4-2007 | Electrical toll collection – Dedicated short range communication – Part 4: Equipment application |
| GB/T 20851.5-2007 | Electrical toll collection – Dedicated short range communication – Part 5: Test methods of the main parameters in physical layer |
| IMDATSAC | IMDA TS DSRC | Technical Specification for Dedicated Short-Range Communications in Intelligent Transportation Systems |

*[Editor´s Note: The following text referring to applications to be shifted to Chapter 6.1 with legacy ITS application overview over all three regions***]**

Applications

As in Europe, Electronic toll collection (ETC) using DSRC is a forerunner of ITS applications in Japan. ETC service in Japan started in March 2001 and by the end of March 2003, the service covered approximately 900 toll gates through which 90% of expressway users pass. This indicates that the service was deployed nationwide in approximately two years. As of the end of March 2004, the number of toll gates increased to 1 300 and as of December 2005, the number of OBEs (ETC subscribers) reached ten million.

The rapid increase in ETC subscribers provides for favourable conditions for various applications to be served by DSRC technology using the same OBE (On board equipment). Research and development are underway through cooperation between the public and industries to develop multiple-purpose on-board equipment that realizes a variety of DSRC services.

Figure [X]

DSRC multiple applications being studied in Japan

1

The following nine application fields are being studied in Japan to extend applications in the vehicle. (Refer to Figure [X]):

(1) Parking lot management

(2) Gas filling station

(3) Convenience store

(4) Drive-through

(5) Logistics management

(6) Pedestrian support

(7) Specific region entry charging (Zone tolling)

(8) Information providing: semi-stationary state

(9) Information providing: high speed

# 7 Advanced ITS radio communication

## 7.1 Overview

Since 1994, Vehicle Information and Communication System (VICS) was used in Japan for delivering traffic and travel information to road vehicle drivers.

Nowadays, to extend beyond the existing ITS applications and to enhance traffic safety and reduce the environmental impact by the transportation sector, vehicle-to-vehicle (V2V), vehicle‑to‑infrastructure (V2I), infrastructure-to-vehicle (I2V), vehicle-to-network (V2N), vehicle‑to-pedestrian (V2P) communications are studied. According to this progress, ITU-R WP 5A has developed report on advanced ITS radiocommunications [8]. In the report, legacy ITS and advanced ITS are classified by its technical characteristics as shown in table 6. V2X (WAVE), V2X (ETSI ITS-G5) and V2X (LTE based V2X) technologies could be inclusive in advanced ITS category.

WAVE is a dedicated mobile radiocommunication system for providing non-voice communications among vehicles that travel on roads, rails, or other dedicated facilities; as well as between those vehicles and the transportation infrastructure. WAVE is therefore a fundamental technology for ITS communications, helping link roads, traffic and vehicles covered by ITS deployment with coordinated, interoperable information technology. This particular wireless technology could be transformational to the evolution of transportation systems, since it provides very localized, low latency communications capabilities on a peer-to-peer basis. These capabilities are intended to support the planned, as well as the still unforeseen, data needs of the evolving, more automated, future transportation system. WAVE systems specifically utilize the broadcast mode of operations as the primary means to support public benefits; and also communicate using two-way communications between vehicles and infrastructure, including the ability to provide lower priority messages related to the specific units involved in a variety of public and private transportation environments.

WAVE is being pursued in the United States “to improve traveler safety, decrease traffic congestion, facilitate the reduction of air pollution, and help to conserve vital fossil fuels”6, and as a particular focus in the United States, to reduce highway fatalities7. Although not yet widely deployed, the United States has developed multiple applications, a number of which have been tested in large-scale field tests or operated in model deployments[[1]](#footnote-1). This progress has provided the United States with extensive knowledge of these applications that contribute to transportation safety, mobility and environmental stewardship in the context of advanced ITS. The WAVE ITS applications are designed to perform operations related to the improvement of traffic safety and traffic flow, as well as other intelligent transport service applications, including enhancing transportation systems efficiencies and operations (for example, facilitating roadway freight movements or transportation management during emergency responses). The main points of focus for the US deployment of advanced ITS applications using WAVE communications include: nationwide interoperability; long-term technical stability; voluntary industry standards; and support for public benefits.

Cooperative ITS communication (C-ITS) has to be based on standardized and interoperable wireless ad-hoc communication systems. The interoperability has to be guaranteed at least in the different worldwide regions. This interoperability requirement does not imply the use of exactly the same system in all regions, e.g. C-ITS in Europe in 5.9 GHz is mainly based on IEEE 802.11p and ETSI ITS-G5, whereas the US implementation in 5.9 GHz is based on the slightly different IEEE 802.11p and WAVE system as described above. For these technologies the standards are finished, intensive testing and validation has taken place, first implementations done and deployment is planned. [Other systems e.g. based on LTE-direct are in an early development stage.] Most of the actual discussed systems are based on a well-established access layer (PHY-layer and MAC-layer) standardised by IEEE802 as IEEE802.11p, which is part of the IEEE802.11-2012 set of standards.

In the majority of regions, a frequency band in the range between 5 850-5 925 MHz (up to 75 MHz bandwidth) has been chosen/picked as the main band of operation for the upcoming traffic-safety related C-ITS. In addition, the frequency band 63 GHz to 64 GHz has been designated for traffic safety related applications under the Mobile Service in CEPT.

Worldwide a broad range of standardisation organisation are involved in the standardisation of C‑ITS. The main actors with a strong support from the Automotive Industry are the US activities around IEEE/WAVE/SAE and the European activities around ETSI TC ITS. These activities are backed by industry consortia CAMP (Crash Avoidance Metric Partnership) in the US and the C2C‑CC (CAR-to-CAR Communication Consortium) in Europe.

The C2C-CC as an industry driven, non-profit association of 16 European vehicle manufacturers, 37 suppliers and 28 research organisations, dedicated to realise cooperative road traffic and herewith increase traffic safety, efficiency and driving comfort. The C2C-CC plays an important role in the development of European standards for C-ITS and cooperates closely on C-ITS with the CAMP consortium in the US. To align and harmonising the C-ITS roll-out in vehicles and traffic infrastructure in Europe by 2019 the consortium engages in the Amsterdam Group. This is a strategic alliance of the CAR 2 CAR Communication Consortium, the ASECAP (Association of operators of toll road infrastructures), CEDR (Conference of European Directors of Roads) and POLIS (European Cities and Regions Networking for Innovative Transport Solutions). Furthermore, the consortium actively contributes to the work of the C-ITS Deployment Platform organised by the European Commission.

The C2C-CC participated in the initial design of vehicle-to-vehicle communications technologies through the publication of a manifesto. It also helps validating the C-ITS systems by getting involved in FOT (Field operational tests) and ongoing cross-border C-ITS corridor projects and focusing on interoperability testing.

In 2007 the CAR 2 CAR Communication Consortium published the Manifesto on its website[[2]](#footnote-2). The document built the basis for the first interoperability demonstration shown 2008 at the Opel testside in Dudenhofen.

The document describes the C-ITS scenarios for improving safety and traffic efficiency as well as using the communication system for infotainment and other purposes. From the scenarios, the system prerequisites and constraints are derived and the system architecture developed. The architecture describes the communication principles, the individual components, the layers’ architecture and related protocols. The further chapters describe the applications, the radio and communication system as well as data security and privacy.

This document specifies the standard profile that enables interoperability of C-ITS units. The first Basic System Profile (BSP) version was released for C2C-CC internal usage by end of 2014. The latest revised BSP version will be published by sharing it with the Basic Members of the consortium by May 2016. It contains a system specification complemented by a selection of standards and parameters. It allows to test the aspects that are going to be used by “day one” applications.

3GPP is actively developing the specifications to enable the use of LTE mobile networks to provide connectivity between vehicles, roadside infrastructure and pedestrians inside and around the connected vehicles. The feasibility studies on LTE based communication have been recently completed and published in Technical Reports. Vehicle-to-vehicle (V2V), vehicle-to-pedestrians (V2P), and vehicle-to-infrastructure (V2I) use cases and system requirements are identified in. Operational scenarios, evaluation methodologies and required radio access enhancements are identified in. Work has started in the relevant working groups to specify the vehicle-to-everything (V2X) system and radio access requirements, where both PC5 (device-to-device direct link) and Uu (link between base station and device) are included, in 3GPP Release 14. The 3GPP study targets at supporting LTEbased V2X transmission in existing mobile allocations up to 6 GHz. [The initial set of V2V core specifications will be available by September 2016, and performance requirements will be available by March 2017. V2X core and performance specifications will follow by March 2017 and September 2017, respectively. 3GPP is also looking at continuously evolving the V2X services in its coming releases including 5G; therefore, further enhancement is also being studied in Rel-15.]

China started to develop trials of LTE based V2X communication technology (LTE-V2X) to verify road safety and non-road safety applications from 2015.

## 7.2 Technical characteristics

Table [X]

Technical characteristic of Advanced ITS

|  |  |  |  |
| --- | --- | --- | --- |
| Items | V2X (WAVE) | V2X (ETSI ITS-G5) | V2X (LTE based V2X) |
| Technologies | WAVE,  IEEE 802.11p | ETSI ITS-G5  IEEE 802.11p | LTE based V2X  3GPP tbd |
| Vehicular networking | V2V, V2I, V2P | V2V, V2I, V2P | V2V, V2N, V2I, V2P |
| Radio performance | Radio coverage: Max. 1 000 m  Data rate: Max. 27 Mbps  Packet size: Max. 2 kbytes  Latency : within 100 msec | Radio coverage: Max. 1 000 m  Data rate: Max. 27 Mbps  Packet size: Max. 2 kbytes  Latency : within 100 msec | Radio coverage: Max. 1 000 m  Data rate: Max. 27 Mbps  Packet size: Max. 2 kbytes  Latency : within 100 msec  within 1000 msec for V2N |

Figure [X]

Vehicle information & Communication (V2V, V2I, I2V)



### 7.2.1 V2X (WAVE)

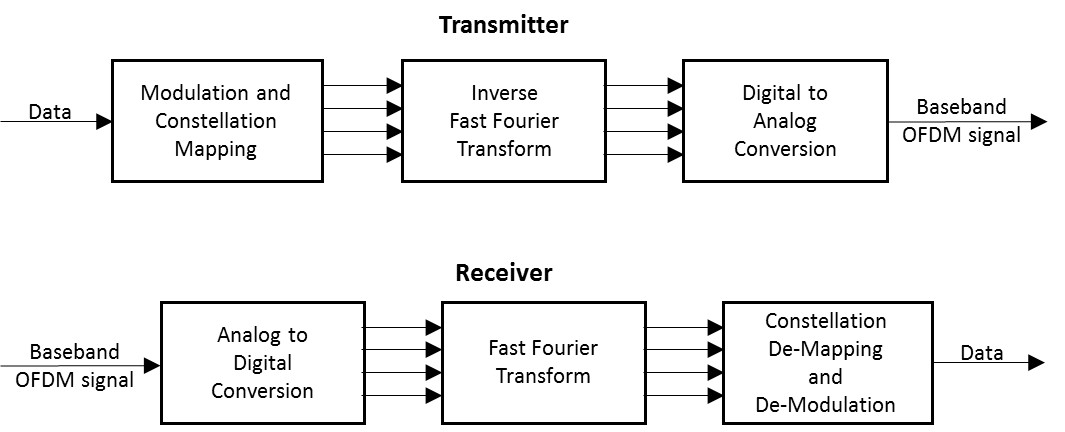
*On-board equipment (OBE)*: The OBE consists of communications and processing equipment installed in vehicles to enable WAVE communications with other vehicles and infrastructure, and support WAVE-enabled applications. OBEs may be most effective when integrated into the vehicle and able to interface with other on-board equipment such as the vehicle’s sensor suite, anti-lock braking system, and other subsystems, allowing it to complement these existing systems.

*Roadside unit (WAVE RSU)*: A WAVE RSU is installed above or alongside the road or other infrastructure and communicates with passing OBEs by the use of radio signals. An RSU consists of radio communication circuits, an application processing circuit and related equipment. It usually has data linkages to traffic management centers (TMCs) and to other roadside equipment (such as traffic signal controllers), as well as to the Internet to exchange data and to maintain security credential information.

The WAVE systems operate by transmitting radio signals for the exchange of data among vehicle-mounted OBEs, and between OBEs and infrastructure-based RSUs. By adhering to requirements set by industry standards, these systems accomplish a data exchange that ensures that data is interoperable across a wide range of device and application manufacturers. Interoperability is key to support the rapid, standardized adoption of applications that deliver critical safety related, system and operational efficiencies, and other public benefits.

Much of the information to complete the following tables comes from Std 802.11-2012[[3]](#footnote-3).

The modulation used for WAVE is ‘half-clocked’ OFDM on 10 MHz channels. Below are basic OFDM transmitter and receiver block diagrams:

Transmitter and Receiver[[4]](#footnote-4)

Adjacent and Next-Adjacent Channel Rejection Receiver Characteristics[[5]](#footnote-5)

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Modulation** | **Coding Rate** | **Receiver Performance (dB)** | | **Optional Enhanced Receiver Performance (dB)** | |
| **Adjacent Channel Rejection** | **Next Adjacent Channel Rejection** | **Adjacent Channel Rejection** | **Next Adjacent Channel Rejection** |
| BPSK | 1/2 | 16 | 32 | 28 | 42 |
| BPSK | 3/4 | 15 | 31 | 27 | 41 |
| QPSK | 1/2 | 13 | 29 | 25 | 39 |
| QPSK | 3/4 | 11 | 27 | 23 | 37 |
| 16-QAM | 1/2 | 8 | 24 | 20 | 34 |
| 16-QAM | 3/4 | 4 | 20 | 16 | 30 |
| 64-QAM | 2/3 | 0 | 16 | 12 | 26 |
| 64-QAM | 3/4 | -1 | 15 | 11 | 25 |

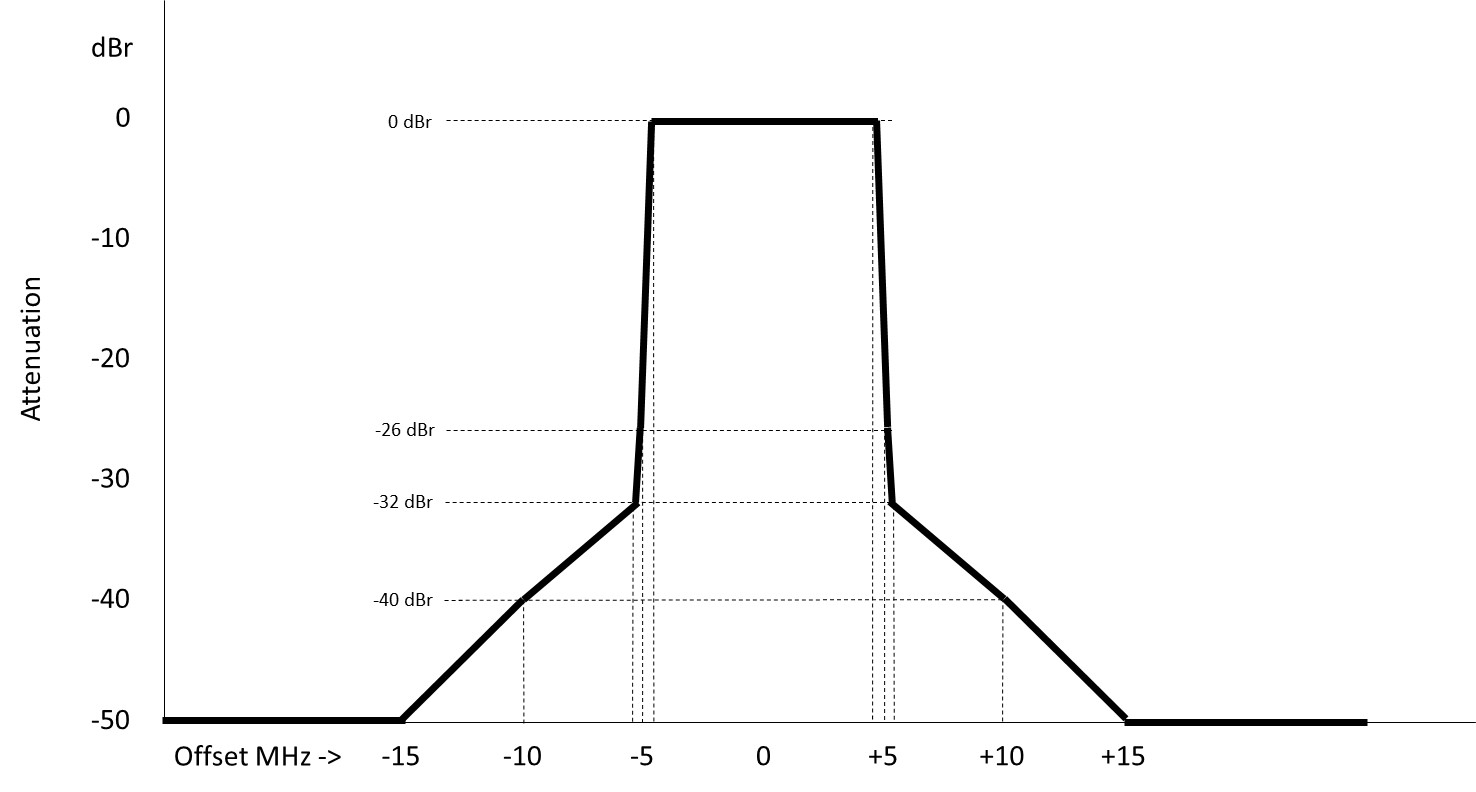
Maximum STA transmit power classification for the 5.85–5.925 GHz band in the United States[[6]](#footnote-6)

|  |  |  |
| --- | --- | --- |
| **STA transmit power classification** | **Maximum STA transmit power**  **(mW)** | **Maximum permitted EIRP**  **(dBm)** |
| A | 1 | 23 |
| B | 10 | 33 |
| C | 100 | 33 |
| D | 760  Note that for this class higher power is permitted as long as the power level is reduced to this level at the antenna input and the emission mask specifications are met. | 33 for nongovernment  44.8 for government |

Spectrum mask data for 10 MHz channel spacing4

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **STA transmit power class** | **Permitted power spectral density, dBr** | | | | |
| **± 4.5 MHz offset (±f1)** | **± 5.0 MHz offset (±f2)** | **± 5.5 MHz offset (±f3)** | **± 10 MHz offset (±f4)** | **± 15 MHz offset (±f5)** |
| Class A | 0 | –10 | –20 | –28 | –40 |
| Class B | 0 | –16 | –20 | –28 | –40 |
| Class C | 0 | –26 | –32 | –40 | –50 |
| Class D | 0 | –35 | –45 | –55 | –65 |

Transmit spectrum mask for 10 MHz OBE transmission (Class C typical)[[7]](#footnote-7)



### 7.2.2 V2X (ETSI ITS-G5)

**[Editor’s note: Text to be added]**

### 7.2.3 V2X (LTE based V2X)

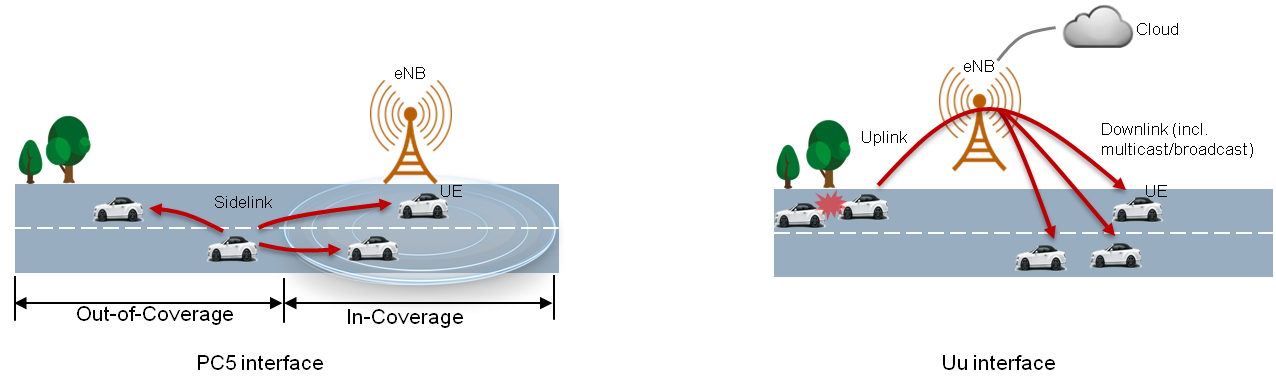
V2X (LTE based V2X) as one enabling technology of advanced ITS, is based on LTE system, and supports both telematics and road safety related applications.

3GPP is working on development of V2X (LTE based V2X) technical specifications, and CCSA is also working on standardization studies of V2X (LTE based V2X) technology with enhancements according to Chinese traffic circumstances.

The general architecture of LTE based V2X can be found in Figure [X], LTE based V2X consists of Uu interface via cellular network, and PC5 interface via direct link for communication between vehicle to vehicles (V2V), vehicle to pedestrian (V2P), vehicle to infrastructures (V2I), and vehicle to network (V2N). LTE based V2X could be operated under the coverage of cellular network, which is called as “in coverage” scenario (IC), as the services are controlled by network. Meanwhile, the “out of coverage” scenario (OoC) is also supported by LTE based V2X, considering the V2X road safety related applications, which should be supported regardless of network deployment.

Figure [X]

Two interfaces of LTE-based V2X



The typical telematics applications can be supported via the Uu interface. For road safety related applications, both PC5 and Uu interfaces are able to support the LTE-V2X in order to meet the associated service requirements with more efficiently and reliably.

[The PC5 interface is designed based on the existing LTE Device-to-Device (D2D) communication technology with more enhancements in resource allocation, physical layer structure, and synchronization, in order to meet the V2X transmission requirements. SC-FDMA and multiple (re)transmissions are inherited from LTE D2D. Multiple (re)transmissions can ensure the reception performance and reliability. Furthermore, both of the centralized and distributed resource allocation mechanisms are supported for V2X communication. The centralized resource assignment is valid within network coverage, eNB could provide dynamic scheduling or semi-persistent scheduling base on traffic circumstances. For the distributed resource mechanisms, it could be supported regardless the network control, and a detailed sensing with semi-persistent transmission mechanism is specified in order to decrease the potential transmission collision and keep high reliability. From the synchronization perspective, LTE-V2X rely on a precise external synchronization signal Three kinds of synchronization references are supported using an external GNSS module, eNB or another vehicle. For the out-of-coverage scenario, GNSS case has a higher synchronization priority in order to obtain a good system performance.

For the Uu interface, the road safety related V2X messages can be transmitted to the cellular network via Uu uplink and be forwarded to the vehicles, which and individually operate components via Uu downlink. To accommodate the broadcast nature of V2X messages, the SC‑PTM (Single Cell Point To Multipoint) and MBSFN (Multicast-Broadcast Single-Frequency Network) technologies are both investigated and supported in LTE-V2X with necessary enhancements.]

## 7.3 Frequency usage

Among APT countries, Japan is using 760 MHz band and studying 5.8 GHz band for V2V and V2I communication to transmit safety related information. Also, Korea assigned 5.855~5.925 GHz for C-ITS (V2V and V2I communications) in 2016. China is also studying spectrum related aspects on V2X (LTE based V2X) communication technology in 5.9 GHz band, where V2X communication includesV2V, V2I, V2P, V2N applications. ITS spectrum study is under developing in multiple standard organizations in China, where the study includes ITS use cases, spectrum need, and coexistence study with incumbent services, the outcome will be developed in the end of 2016.

On the other hand, Europe plans to use of the 5.855~5.925 GHz frequency band for C-ITS (V2V and V2I communication) according to the ECC decision in 2008, and the U.S. use the frequency band 5.850~5.925 GHz for the WAVE providing ITS applications with specific channels for safety. For interoperability and global harmonization, some APT countries are (e.g. Australia, Singapore) also considering these band for cooperative ITS systems.

Regards these activities, in Australia, the investigation has carefully examined the constraints created by existing and future service coordination requirements. These include, for example, the fixed-satellite service concerns over the unknown compounding effects of aggregated roadside and on board units which could constructively interfere with the FSS, and/or raise the overall noise floor within which the FSS operates. Moreover, the need to protect intelligent transport systems may severely limit the deployment of future FSS earth stations in the band 5 850-5 925 MHz. While studies have indicated these impacts will be minimal, mitigation and appropriate licensing strategies are under consideration.

### 7.3.1 V2X (WAVE)

WAVE is being pursued in the United States “to improve traveler safety, decrease traffic congestion, facilitate the reduction of air pollution, and help to conserve vital fossil fuels”[[8]](#footnote-8), and as a particular focus in the United States, to reduce highway fatalities[[9]](#footnote-9). In order to address the need for advanced ITS to provide these public benefits, a number of applications have been developed, with more still under development, to leverage the unique short range characteristics of WAVE. These applications include communications among vehicles and other mobile end users, as well as between mobile users and roadside infrastructure.

WAVE applications may have access to each of the seven 10 MHz channels on a dynamic assignment basis under the direction of the control channel as shown in the following table, but do not use the 20 MHz combined channels, designated as Channels 175 and 181 in the table. This band plan provides dedicated channels for crash-imminent safety-related (Channel 172) and high-powered public safety-related (Channel 184) applications[[10]](#footnote-10), as well as flexible assignment of other service channels through the control channel mechanism to support the wide range of advanced ITS WAVE applications. Many applications will only partially use a particular assignable channel at a particular time and location, permitting sharing among WAVE applications on individual assignable service channels.

Safety-related applications which are not pre-assigned to the dedicated channels typically use the control channel to transmit very short, infrequent messages, or else use WAVE Service Announcements (WSA) on the control channel to indicate a service channel upon which to communicate, if those messages are less dependent upon having very low latency. Lower priority messages typically use WSAs on the control channel to be assigned to a service channel which is not fully occupied by safety-related communications at that location at that time. This flexible designation of application messages to different service channels in various locations facilitates spectral efficiency and reduces interference among WAVE applications.

Band Plan for WAVE in the United States[[11]](#footnote-11)

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| 5.850 GHz |  |  | |  |  | | 5.925 GHz |
|  | | CH175 | |  | CH181 | |  |
| 5 850-5 855  reserve 5 MHz | CH172  service 10 MHz | CH174  service 10 MHz | CH176  service 10 MHz | CH178  control 10 MHz | CH180  service 10 MHz | CH182  service 10 MHz | CH184  service 10 MHz |

Note – This band plan may need to be revised if regulatory changes occur as a result of ongoing regulatory proceedings in the United States.

### 7.3.2 V2X (ETSI ITS-G5)

**[Editor’s note: Text to be added]**

## 7.4 Standardization

Table [X]

Global Standards and technical specifications on Advanced ITS radiocommunication

| SDO | Standard No. | Title |
| --- | --- | --- |
| ITU | ITU-R M.1890 | Intelligent transport systems - Guidelines and objectives |
| Report ITU-R M.2228 | Advanced intelligent transport systems (ITS) radiocommunications |
| ITU-R M.2084 | Radio interface standards of vehicle-to-vehicle and vehicle-to-infrastructure communication for intelligent transport systems applications |
| ETSI | [TR 102 638](http://webapp.etsi.org/WorkProgram/Frame_WorkItemList.asp?SearchPage=TRUE&butExpertSearch=++Search++&qETSI_STANDARD_TYPE=&qETSI_NUMBER=102+638&qTB_ID=&qINCLUDE_SUB_TB=True&includeNonActiveTB=FALSE&qWKI_REFERENCE=&qTITLE=&qSCOPE=&qCURRENT_STATE_CODE=&qSTOP_FLG=N&qSTART_CURRENT_STATUS_CODE=&qEND_CURRENT_STATUS_CODE=&qFROM_MIL_DAY=&qFROM_MIL_MONTH=&qFROM_MIL_YEAR=&qTO_MIL_DAY=&qTO_MIL_MONTH=&qTO_MIL_YEAR=&qOPERATOR_TS=&qRAPTR_NAME=&qRAPTR_ORGANISATION=&qKEYWORD_BOOLEAN=OR&qKEYWORD=&qPROJECT_BOOLEAN=OR&qPROJECT_CODE=&includeSubProjectCode=FALSE&qSTF_List=&qDIRECTIVE=&qMandate_List=&qSORT=HIGHVERSION&qREPORT_TYPE=SUMMARY&optDisplay=10&titleType=all) | Intelligent Transport Systems (ITS); Vehicular Communications; Basic Set of Applications; Definitions |
| [TS 102 637 series](http://webapp.etsi.org/WorkProgram/Frame_WorkItemList.asp?SearchPage=TRUE&butExpertSearch=++Search++&qETSI_STANDARD_TYPE=%27TS%27&qETSI_NUMBER=102+637&qTB_ID=&qINCLUDE_SUB_TB=True&includeNonActiveTB=FALSE&qWKI_REFERENCE=&qTITLE=&qSCOPE=&qCURRENT_STATE_CODE=&qSTOP_FLG=N&qSTART_CURRENT_STATUS_CODE=&qEND_CURRENT_STATUS_CODE=&qFROM_MIL_DAY=&qFROM_MIL_MONTH=&qFROM_MIL_YEAR=&qTO_MIL_DAY=&qTO_MIL_MONTH=&qTO_MIL_YEAR=&qOPERATOR_TS=&qRAPTR_NAME=&qRAPTR_ORGANISATION=&qKEYWORD_BOOLEAN=OR&qKEYWORD=&qPROJECT_BOOLEAN=OR&qPROJECT_CODE=&includeSubProjectCode=FALSE&qSTF_List=&qDIRECTIVE=&qMandate_List=&qSORT=HIGHVERSION&qREPORT_TYPE=SUMMARY&optDisplay=10&titleType=all) | Intelligent Transport Systems (ITS); Vehicular Communications; Basic Set of Applications |
| [EN 302 637-2](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=37126&curItemNr=1&totalNrItems=1&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=302+637-2&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN) | ITS-Vehicular Communications; Basic Set of Applications; Part 2: Specification of Cooperative Awareness Basic Service. |
| [EN 302 637-3](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=37127&curItemNr=1&totalNrItems=1&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=302+637-3&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | ITS-Vehicular Communications; Basic Set of Applications; Part 3: Specifications of Decentralized Environmental Notification Basic Service. |
| [EN 302 665](http://webapp.etsi.org/WorkProgram/Frame_WorkItemList.asp?SearchPage=TRUE&butExpertSearch=++Search++&qETSI_STANDARD_TYPE=&qETSI_NUMBER=302+665&qTB_ID=&qINCLUDE_SUB_TB=True&includeNonActiveTB=FALSE&qWKI_REFERENCE=&qTITLE=&qSCOPE=&qCURRENT_STATE_CODE=&qSTOP_FLG=N&qSTART_CURRENT_STATUS_CODE=&qEND_CURRENT_STATUS_CODE=&qFROM_MIL_DAY=&qFROM_MIL_MONTH=&qFROM_MIL_YEAR=&qTO_MIL_DAY=&qTO_MIL_MONTH=&qTO_MIL_YEAR=&qOPERATOR_TS=&qRAPTR_NAME=&qRAPTR_ORGANISATION=&qKEYWORD_BOOLEAN=OR&qKEYWORD=&qPROJECT_BOOLEAN=OR&qPROJECT_CODE=&includeSubProjectCode=FALSE&qSTF_List=&qDIRECTIVE=&qMandate_List=&qSORT=HIGHVERSION&qREPORT_TYPE=SUMMARY&optDisplay=10&titleType=all) | Intelligent Transport Systems (ITS); Communications Architecture |
| [TS 102 636 series](http://webapp.etsi.org/WorkProgram/Frame_WorkItemList.asp?SearchPage=TRUE&butExpertSearch=++Search++&qETSI_STANDARD_TYPE=&qETSI_NUMBER=102+636&qTB_ID=&qINCLUDE_SUB_TB=True&includeNonActiveTB=FALSE&qWKI_REFERENCE=&qTITLE=&qSCOPE=&qCURRENT_STATE_CODE=&qSTOP_FLG=N&qSTART_CURRENT_STATUS_CODE=&qEND_CURRENT_STATUS_CODE=&qFROM_MIL_DAY=&qFROM_MIL_MONTH=&qFROM_MIL_YEAR=&qTO_MIL_DAY=&qTO_MIL_MONTH=&qTO_MIL_YEAR=&qOPERATOR_TS=&qRAPTR_NAME=&qRAPTR_ORGANISATION=&qKEYWORD_BOOLEAN=OR&qKEYWORD=&qPROJECT_BOOLEAN=OR&qPROJECT_CODE=&includeSubProjectCode=FALSE&qSTF_List=&qDIRECTIVE=&qMandate_List=&qSORT=HIGHVERSION&qREPORT_TYPE=SUMMARY&optDisplay=10&titleType=all) | Intelligent Transport Systems (ITS); Vehicular Communications; GeoNetworking; |
| [EN 302 636-4-1](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=38232&curItemNr=1&totalNrItems=1&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=302+636-4-1&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | Intelligent Transport Systems (ITS); Vehicular Communications; GeoNetworking; Part 4: Geographical Addressing and Forwarding for Point‑to-Point and Point-to-Multipoint Communications; Sub-Part 1: Media-Independent Functionality. |
| [TR 101 607](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=39332&curItemNr=1&totalNrItems=1&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=101+607&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | Intelligent Transport Systems (ITS); Cooperative ITS (C-ITS); Release 1 |
| [TS 102 894-2](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=43353&curItemNr=2&totalNrItems=3&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=102+894-2&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | ITS-Users and applications requirements; Part 2: Applications and facilities layer common data dictionary. Dictionary of definitions used by other ETSI TC ITS standards. |
| [TS 102 890-3](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=35130&curItemNr=1&totalNrItems=1&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=102+890-3&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | ITS – Facilities layer function; facility position and time management. |
| [EN 302 895](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=31914&curItemNr=1&totalNrItems=1&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=302+895&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | Intelligent Transport Systems (ITS); Vehicular Communications; Basic Set of Applications; Local Dynamic Map (LDM) |
| [TS 101 556-1](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=35131&curItemNr=1&totalNrItems=1&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=101+556-1&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | Intelligent Transport Systems (ITS); I2V Applications; Electric Vehicle Charging Spot Notification Specification |
| [TS 101 556-2](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=38839&curItemNr=1&totalNrItems=1&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=101+556-2&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | Intelligent Transport Systems (ITS); Infrastructure to Vehicle Communication; Part 2: Communication system specification to support application requirements for Tyre Information System (TIS) and Tyre Pressure Gauge (TPG) interoperability |
| [TS 101 539-1](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=35112&curItemNr=1&totalNrItems=1&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=101+539-1&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | ITS – V2X Applications; Part 1: Road Hazard Signalling (RHS) application requirements |
| [TS 101 539-3](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=35136&curItemNr=1&totalNrItems=1&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=101+539-3&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | ITS – V2X Applications; Part 3: Longitudinal Collision Risk Warning (LCRW) application requirement specification. |
| [TS 102 792](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=44131&curItemNr=1&totalNrItems=2&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=102+792&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | Intelligent Transport Systems (ITS); Mitigation techniques to avoid interference between European CEN Dedicated Short Range Communication (CEN DSRC) tolling equipment and Intelligent Transport Systems (ITS) operating in the 5 GHz frequency range. |
| [ETSI EN 302 571](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=43780&curItemNr=1&totalNrItems=3&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=302+571&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | Intelligent Transport Systems (ITS); Radiocommunications equipment operating in the 5 855 5 925 MHz frequency band; Harmonised Standard covering the essential requirements of article 3.2 of Directive 2014/53/EU  The update of this standard is actually in the EN approval process and should be available until the end of 2016 |
| [ETSI EN 302 686](https://portal.etsi.org/webapp/WorkProgram/Report_WorkItem.asp?WKI_ID=20587&curItemNr=1&totalNrItems=2&optDisplay=10&qSORT=HIGHVERSION&qETSI_ALL=TRUE&SearchPage=TRUE&qETSI_NUMBER=302+686&qINCLUDE_SUB_TB=True&qINCLUDE_MOVED_ON=&qSTOP_FLG=&qKEYWORD_BOOLEAN=&qCLUSTER_BOOLEAN=&qFREQUENCIES_BOOLEAN=&qSTOPPING_OUTDATED=&butSimple=Search&includeNonActiveTB=FALSE&includeSubProjectCode=&qREPORT_TYPE=SUMMARY) | Intelligent Transport Systems (ITS); Radiocommunications equipment operating in the 63 GHz to 64 GHz frequency band; Harmonised Standard covering the essential requirements of article 3.2 of the Directive 2014/53/EU  This standard is under revision and a final draft of the new release should be available until the end of the year 2016 |
| [ES 202 663](http://webapp.etsi.org/WorkProgram/Frame_WorkItemList.asp?SearchPage=TRUE&butExpertSearch=++Search++&qETSI_STANDARD_TYPE=&qETSI_NUMBER=202+663+&qTB_ID=&qINCLUDE_SUB_TB=True&includeNonActiveTB=FALSE&qWKI_REFERENCE=&qTITLE=&qSCOPE=&qCURRENT_STATE_CODE=&qSTOP_FLG=N&qSTART_CURRENT_STATUS_CODE=&qEND_CURRENT_STATUS_CODE=&qFROM_MIL_DAY=&qFROM_MIL_MONTH=&qFROM_MIL_YEAR=&qTO_MIL_DAY=&qTO_MIL_MONTH=&qTO_MIL_YEAR=&qOPERATOR_TS=&qRAPTR_NAME=&qRAPTR_ORGANISATION=&qKEYWORD_BOOLEAN=OR&qKEYWORD=&qPROJECT_BOOLEAN=OR&qPROJECT_CODE=&includeSubProjectCode=FALSE&qSTF_List=&qDIRECTIVE=&qMandate_List=&qSORT=HIGHVERSION&qREPORT_TYPE=SUMMARY&optDisplay=10&titleType=all) | Intelligent Transport Systems (ITS); European profile standard for the physical and medium access control layer of Intelligent Transport Systems operating in the 5 GHz frequency band |
| IEEE | IEEE 802.11-2012 | Wireless LAN Medium Access Control (MAC) and Physical Layer (PHY) Specifications |
| IEEE 1609 | Family of Standards for Wireless Access in Vehicular Environments (WAVE) |
| - IEEE 1609.0-2012 - IEEE Guide for WAVE – Architecture |
| - IEEE 1609.2 -2016- IEEE Standard for WAVE - Security Services for Applications and Management Messages |
| - IEEE 1609.3 -2016 – IEEE Standard for WAVE - Networking Services |
| - IEEE 1609.3 -2010/Cor 1-2012 – IEEE Standard for WAVE – Networking Services Corrigendum 1: Miscellaneous Corrections |
| - IEEE 1609.3 -2010/Cor 2-2014 – IEEE Standard for WAVE – Networking Services Corrigendum 2: Correct identified errors |
| - IEEE 1609.4 -2016- IEEE Standard for WAVE - Multi-Channel Operations |
| - IEEE 1609.4-2010/Cor 1-2014 – IEEE Standard for WAVE – Multi-channel Operation – Corrigendum 1: Correct identified errors |
| - IEEE 1609.11-2010 – IEEE Standard for WAVE – Over-the-Air Electronic Payment Data Exchange Protocol for ITS |
| - IEEE 1609.12-2016 – IEEE Standard for WAVE – Identifier Allocations |
| SAE | J2735-2009 | Dedicated Short Range Communications (DSRC) Message Set Dictionary |
| 3GPP | [Technical reports] | TR 22.885 Study on LTE support for Vehicle to Everything (V2X) services, 3GPP  TR 36.885 Study on LTE-based V2X services, 3GPP |

## 7.5 Applications

*[Editor’s note: Text to be added]*

The following application examples are taken from US Department of Transportation’s Connected Vehicle Reference Implementation Architecture (CVRIA)[[12]](#footnote-12), which also provides further definitions and reference implementation information. In general, the WAVE ITS applications in the United States may be grouped into general categories that apply to transportation operations on a day‑to‑day basis, although there are no strict boundaries between the categories and overlaps among categories are common. There is also a category for core services that are the foundation for data exchange, interoperability, security, and privacy. The following subsections provide application examples within a selection of these categories.

#### 7.5.1 V2V Safety-Related Applications

These are applications with a primary focus of enhancing safety through vehicle-to-vehicle communications to address the prevention of imminent crashes, and/or mitigation of the injuries and damages that might result if a crash cannot be prevented. Since this category represents a major focus of the United States WAVE ITS development and deployment, there tend to be a large number of these applications, and they are typically in later stages of deployment than applications in the other categories.

This is not a complete listing of V2V safety-related applications in the United States, since others are also being deployed, and continuing innovation is expected.

##### 7.5.1.1 Blind Spot Warning + Lane Change Warning11

This application has been operated in model deployments to warn the driver of the vehicle during a lane change attempt if the blind-spot zone into which the vehicle intends to switch is, or will soon be, occupied by another vehicle.

##### 7.5.1.2 Control Loss Warning11

This application is being developed to enable a vehicle to broadcast a self-generated, control loss event to surrounding vehicles.

##### 7.5.1.3 Do Not Pass Warning11

Has been operated in model deployments to warn the driver of the vehicle when a slower moving vehicle, ahead and in the same lane, cannot be safely passed.

##### 7.5.1.4 Emergency Electronic Brake Light11

Has been operated in model deployments to enable a vehicle to broadcast a self-generated emergency brake event to surrounding vehicles.

##### 7.5.1.5 Emergency Vehicle Alert11

Has been developed and is planned for operation in pilot deployment to alert the driver about the location of and the movement of public safety vehicles responding to an incident so the driver does not interfere with the emergency response.

##### 7.5.1.6 Forward Collision Warning11

Has been operated in model deployments to warn the driver of the vehicle in case of an impending rear-end collision with another vehicle ahead in traffic.

##### 7.5.1.7 Intersection Movement Assist11

Has been operated in model deployments to warn the driver of a vehicle when it is not safe to enter an intersection due to high collision probability with other vehicles at stop sign controlled and uncontrolled intersections.

##### 7.5.1.8 Motorcycle Approaching Indication11

This application is intended to warn the driver of a vehicle that a motorcycle is approaching.

##### 7.5.1.9 Situational Awareness11

Has been developed and is planned for installation and operation in pilot deployment to determine if the road conditions measured by other vehicles represent a potential safety hazard for the vehicle containing the application.

#### 7.5.2 V2I Safety-Related Applications

The applications in this category are targeted toward enhancing roadway safety through vehicle‑to/from-infrastructure communications. The following examples of the V2I safety related applications provide a view of the diversity possible within this category. As in the safety related category examples, the following is not a complete listing of such applications in the United States.

##### 7.5.2.1 Curve Speed Warning11

Has been operated in model deployments to allow a connected vehicle to receive information that it is approaching a curve along with the recommended speed for the curve.

##### 7.5.2.2 Emergency Vehicle Preemption11

Has been operated in model deployments to provide a very high level of priority for emergency first responder vehicles to facilitate safe and efficient movement through intersections.

##### 7.5.2.3 Enhanced Maintenance Decision Support System11

Is being developed to incorporate the additional information that can come from collecting road weather data from connected vehicles into existing Maintenance Decision Support System (MDSS) capabilities to generate improved plans and recommendations to maintenance personnel.

##### 7.5.2.4 Incident Scene Work Zone Alerts for Drivers and Workers11

Has been operated in model deployments to provide warnings and alerts relating to incident zone operations. One aspect of the application is an in-vehicle messaging system that provides drivers with merging and speed guidance around an incident. Another aspect is providing in-vehicle incident scene alerts to drivers and on-scene workers.

##### 7.5.2.5 In-Vehicle Signage11

Has been operated in model deployments to augment regulatory, warning, and informational signs and signals by providing information directly to drivers through in-vehicle devices.

##### 7.5.2.6 Oversize Vehicle Warning11

Has been developed to use external measurements taken by the roadside infrastructure, and transmitted to the vehicle, to support in-vehicle determination of whether an alert/warning is necessary.

##### 7.5.2.7 Pedestrian in Signalized Crosswalk Warning11

Has been developed and is planned for operation in pilot deployment to provide to the connected vehicle information from the infrastructure that indicates the possible presence of pedestrians in a crosswalk at a signalized intersection.

##### 7.5.2.8 Railroad Crossing Violation Warning11

Is being developed to alert and/or warn drivers who are approaching an at-grade railroad crossing if they are on a crash-imminent trajectory to collide with a crossing or approaching train.

##### 7.5.2.9 Red Light Violation Warning11

Has been operated in field tests and is planned for operation in pilot deployment to enable a connected vehicle approaching an instrumented signalized intersection to receive information regarding the signal timing and geometry of the intersection.

##### 7.5.2.10 Reduced Speed Zone Warning / Lane Closure11

Has been developed and is planned for operation in pilot deployment ~~Is being deployed~~ to provide connected vehicles which are approaching a reduced speed zone with information on the zone's posted speed limit and/or if the lane is closed or shifted.

##### 7.5.2.11 Restricted Lane Warnings11

Are being developed to provide the connected vehicle with travel lane restrictions, such as if the lane is restricted to high occupancy vehicles, transit, or public safety vehicles, or has defined eco‑lane criteria.

##### 7.5.2.12 Roadside Lighting11

This application is being developed to use the presence of vehicles based on V2I communications as an input to control of roadside lighting systems.

##### 7.5.2.13 Stop Sign Gap Assist11

Is being developed to improve safety at non-signalized intersections by helping drivers on a minor road stopped at an intersection understand the state of activities associated with that intersection by providing a warning of unsafe gaps on the major road.

##### 7.5.2.14 Stop Sign Violation Warning11

Is being developed to improve safety at intersections with posted stop signs by providing warnings to the driver approaching an unsignalized intersection.

##### 7.5.2.15 Transit Vehicle at Station/Stop Warnings11

Is being developed to inform nearby vehicles of the presence of a transit vehicle at a station or stop and to indicate the intention of the transit vehicle in terms of pulling into or out of a station/stop.

##### 7.5.2.16 Vehicle Turning Right in Front of a Transit Vehicle11

Has been operated in model deployments to determine the movement of vehicles near to a transit vehicle stopped at a transit stop and provide an indication to the transit vehicle operator that a nearby vehicle is pulling in front of the transit vehicle to make a right turn.

#### 7.5.3 Transportation System Efficiency and Operations Applications

These applications are designed to improve the flow of traffic and generally support the efficient operation of the transportation system. The following subsections provide selected examples of mobility applications.

##### 7.5.3.1 Cooperative Adaptive Cruise Control11

Is being developed to provide an evolutionary advancement of conventional cruise control systems and adaptive cruise control (ACC) systems by utilizing V2V communication to automatically synchronize the movements of many vehicles within a platoon.

##### 7.5.3.2 Intelligent Traffic Signal System11

Has been operated in model deployments to use both vehicle location and movement information from connected vehicles as well as infrastructure measurement of non-equipped vehicles to improve the operations of traffic signal control systems.

##### 7.5.3.3 Intermittent Bus Lanes11

Is being developed to provide dedicated bus lanes during peak demand times to enhance transit operations mobility.

##### 7.5.3.4 Pedestrian Mobility11

Has been developed and is planned for operation in pilot deployment to integrate traffic and pedestrian information from roadside or intersection detectors and new forms of data from wirelessly connected, pedestrian (or bicyclist) carried mobile devices (nomadic devices) to provide input to dynamic pedestrian signals or to inform pedestrians when to cross and how to remain aligned with the crosswalk based on real-time Signal Phase and Timing (SPaT) and MAP information.

##### 7.5.3.5 Performance Monitoring and Planning11

Has been operated in model deployments to use information collected from connected vehicles to support operational functions, including performance monitoring, transportation planning, condition monitoring, safety analyses, and research.

##### 7.5.3.6 Speed Harmonization11

Is being developed to determine speed recommendations based on traffic conditions and weather information. Recommendations can be regulatory (e.g. variable speed limits) or advisory in order to change traffic speed on links that approach areas of traffic congestion that affect flow.

##### 7.5.3.7 Transit Signal Priority11

Has been operated in model deployments to use V2I communications to allow a transit vehicle to request a priority at one or a series of intersections.

##### 7.5.3.8 Variable Speed Limits for Weather-Responsive Traffic Management11

Is being developed to provide real-time, location-specific information on appropriate speeds for current conditions and to warn drivers of imminent road conditions.

##### 7.5.3.9 Vehicle Data for Traffic Operations11

Is being developed to use information obtained from vehicles in the network to support traffic operations, including incident detection and the implementation of localized operational strategies.

#### 7.5.4 Environment Applications

The environment category includes applications that are designed to support environmental sustainability for the transportation system. From protecting the air quality within a sensitive zone, to ensuring the smallest environmental footprint for a connected vehicle to pass through an intersection, the example environment applications presented below illustrate the wide range of opportunities to use ITS technology to reduce the environmental impact of the transportation system.

##### 7.5.4.1 Eco-Approach and Departure at Signalized Intersections11

Has been developed to use wireless data communications sent from a roadside equipment (RSU) unit to connected vehicles to encourage "green" approaches to and departures from signalized intersections.

##### 7.5.4.2 Eco-Speed Harmonization11

Is being developed to determine eco-speed limits based on traffic conditions, weather information, greenhouse gas emissions, and criteria pollutant information.

##### 7.5.4.3 Low Emissions Zone Management11

Is being developed to support the operation of a low emissions zone that is responsive to real-time traffic and environmental conditions. Low emissions zones are geographic areas that seek to restrict or deter access by specific categories of high-polluting vehicles into the area to improve the air quality within the geographic area.

**7.5.5**  **Core Services**

DSRC applications rely upon a set of core services that support the cooperative and interoperable nature of the independently-operated applications and technologies that communicate and share information as well as independently authenticate devices before accepting data.

##### 7.5.5.1 Core Authorization11

Has been operated in model deployments to manage the authorization mechanisms to define roles, responsibilities and permissions for other connected vehicle applications. This allows system administrators to establish operational environments where different connected vehicle system users may have different capabilities. For instance, certain vehicle elements may be authorized to request signal priority, while those without those permissions would not.

##### 7.5.5.2 Location and Time11

Is being developed to show the external systems and their interfaces to provide accurate location and time to connected vehicle devices and systems.

##### 7.5.5.3 Security and Credentials Management11

Has been operated in model deployments to ensure trusted communications between mobile devices and other mobile devices or roadside devices and to protect data they handle from unauthorized access.

#### 7.5.6 Non-Priority Communications[[13]](#footnote-13), such as E-Commerce and Infotainment

ITS in the 5.9 GHz band might also have numerous commercial applications. Below are a few applications envisioned for ITS in this band.

##### 7.5.6.1 Wireless Advertising*[[14]](#footnote-14)*

The Wireless Advertising application would provide businesses and other entities located near a roadway the opportunity to deliver advertisements to the occupants of a passing vehicle. The application could restrict the recipients of these advertisements to only certain motorists to maximize the relevance of these advertisements to consumers.

##### 7.5.6.2 Vehicle-to-Infrastructure Internet Connection*[[15]](#footnote-15)*

ITS spectrum and technologies could be used to provide Internet access to occupants of a moving vehicle by transmitting data to a network of roadside units or, potentially, using a vehicle-to-vehicle mesh network.

##### 7.5.6.3 Drive-Thru Payments*[[16]](#footnote-16)*

The Drive-Thru Payments application would allow motorists to automatically pay for goods and services purchased from within the vehicle, such as at the “drive-thru” window of a restaurant.

##### 7.5.6.4 Vehicle-to-Vehicle Messaging*[[17]](#footnote-17)*

If an occupant notices any problem (e.g. flat tire, missing gas cap, open trunk, etc.), it can send a message to the corresponding vehicle. The message could be chosen from a list of pre-defined or customized messages.

#### 7.5.7 Other Applications

The main intention of this category is to provide public benefits by supporting the safe and efficient operation of the overall transportation system. The other applications category may also include proprietary or commercial applications, but at a lower priority level.

##### 7.5.7.1 Border Management Systems11

Have been developed to provide international border registration, pre-processing and border inspection capabilities.

##### 7.5.7.2 Electric Charging Stations Management11

Is being developed to provide an exchange of information between vehicle and charging station to manage the charging operation.

##### 7.5.7.3 Integrated Multi-Modal Electronic Payment11

Has been developed to use connected vehicle roadside and vehicle systems to provide the electronic payment capability for toll systems, parking systems, and other areas requiring electronic payments.

##### 7.5.7.4 Road Weather Information for Maintenance and Fleet Management Systems11

This application is being developed to be either a stand-alone application or as an adjunct to the Enhanced-MDSS. The data collected can be used by maintenance or fleet dispatchers to monitor the status of the maintenance operations, or the data can be used as an input to the Enhanced-MDSS application.

##### 7.5.7.5 Smart Roadside Initiative11

Is being developed to improve the efficiency and safety of the Nation's roadways by providing for the exchange of important safety related and operational information regarding commercial vehicles.

## 7.6 Region 1

*[Editor’s note: Text to be added]*

### 7.6.1 Frequency usage

### 7.6.2 Standardization

## 7.7 Region 2

*[Editor’s note: Text to be added]*

### 7.7.1 Frequency usage

### 7.7.2 Standardization

## 7.8 Region 3

### 7.8.1 Frequency usage

Table [X]

Frequency usage on Advanced ITS radiocommunication in Asia-Pacific

| Country | Frequency band | Technology | Application | Status |
| --- | --- | --- | --- | --- |
| Japan | 76-90 MHz  (FM multiplex broadcasting) | VICS (Vehicle Information and Communications System) | Traffic information | Enacted in 1994 |
| 2,499.7 MHz (Radio beacon) |
| 5,770-5,850 MHz | V2V/V2I communication | Safety related information | Guidelines for field experiment in 2007 (revised 2013) |
| 760 MHz band | Enacted in 2011 (revised 2013) |
| Korea | 5.855~5.925 GHz | V2V/V2I communication | Vehicle Safety Related  C-ITS | Enacted in 2016 |
| China | 5.905-5.925 GHz | LTE based V2X | V2X communication | Field  Experiment |
| Singapore | 5.855-5.925 GHz | V2V/V2I | Traffic/Safety Related Information | TBD |

### 7.8.2 Standardization

Table [X]

Standards on Advanced ITS radiocommunication in Asia-Pacific

|  |  |  |
| --- | --- | --- |
| SDO | Standard No. | Standard Title |
| TTA | TTAS.KO-06.0175/R1 | Vehicle Communication System Stage1: Requirements |
| TTAS.KO-06.0193/R1 | Vehicle Communication SystemStage2: Architecture |
| TTAS.KO-06.0216/R1 | Vehicle Communication System Stage3 : PHY/MAC |
| TTAS.KO-06.0234/R1 | Vehicle Communication System State 3 : Networking |
| TTAK.KO-06.0242/R1 | Vehicle Communication System Stage3 : Application Protocol Interface |
| TTAK KO-06.0344 | In-Vehicle Signage System for Vehicle Safety Guidance Stage 1: Requirements |
| TTAK KO-06.0344-Part2 | In-Vehicle Signage System for Vehicle Safety Guidance Stage 2: Data Exchange |
| ARIB | STD-T109 | 700 MHz Band Intelligent Transport Systems |
| CCSA | TBD | TBD |
| IMDA TSAC | IMDA TS DSRC | Technical Specification for Dedicated Short-Range Communications in Intelligent Transportation Systems |

# 8 Millimetre-wave automotive radar

*[Editor´s note: This chapter needs to be updated]*

## 8.1 Overview

Sensor technologies for monitoring and identifying objects near vehicles are the most important safety-related base technologies for developing systems that will accommodate this purpose. Various types of sensors have been studied and developed, and through this research and development, it has become clear that a RADAR (Radio Detection and Ranging) using radio waves is suitable for this objective. An international effort to regulate radar for automotive applications is crucial for ensuring stable radar operations and effective use of frequency resources. In accordance with the Radio Regulation, the 60 GHz (60-61 GHz) and 76 GHz (76-77 GHz) bands were considered suitable for radar system due to the radio wave absorption characteristics in the atmosphere as described above. The 76 GHz band has already been assigned by the Federal Communications Commission (FCC) for automotive radars in the United States of America. The Ministry of Internal Affairs and Communications (MIC) in Japan has assigned the 60 GHz and 76 GHz bands for low power, automotive radars. Furthermore, in accordance with European spectrum requirements for RTTT established in 2002, ETSI has adopted a European standard for low power vehicle radar operating in the 76‑77 GHz band (EN 301 091) in 1998. In 2000, Recommendation ITU-R M.1452 for low power, automotive radar operating in the 60 GHz, and 76 GHz bands was approved and published.

In Europe, Ultra wide band (UWB) short range radar (SRR) operating at 24 GHz (22-29 GHz) is considered to be a key technology for the rapid and cost-effective introduction of many intelligent vehicle safety related systems. In January 2005, the European Commission decided on the time-limited (until 1 July 2013) use of the 24 GHz range radio spectrum band for the ultra-wide band part of short-range vehicle radar equipment. After this deadline SRR equipment is intended to operate in the frequency band 79 GHz (77 - 81 GHz) on a permanent base, see ECC/DEC/(04)03. Applications operating around the 24 GHz band would increasingly suffer significant levels of harmful interference if a certain level of penetration of vehicles using the 24 GHz range radio spectrum band for short-range radars was to be exceeded. According to CEPT (European Conference of Postal and Telecommunications Administrations), the sharing between earth exploration satellite services and short-range vehicle radar could only be feasible on a temporary basis.

## 8.2 Technical characteristics

(1) Low Power Automotive Radar at 60 GHz and 76 GHz

Today the frequency allocation for automotive radar application is in a rebuilding phase. Due to technological and commercial constraints the frequency allocation for these safety related applications has been done in the beginning of the last decade in the range of 24 GHz. In Europe e.g. this allocation has been done as an intermediate solution due to the incompatibility with the Radio Astronomy Service, EESS, the Fixed Service and military applications. Therefore the cut-off date of 1st July 2013 has been defined. In July 2011 the EC extends the cut-off date (with modified technical parameter) until 1st January 2018 to allow the car manufacturer a seamless implementation of the 79 GHz technology. The technological evolution during the last years leads to the fact that with a similar effort a higher performance can be reached today.

(2) High Resolution Automotive Radar at 79 GHz

The industries are trying to seek globally or regionally harmonized frequency allocations for new vehicle radar technologies. The following frequency allocation is under consideration and the relevant study work has been undertaken by ITU-R WP 5A/B:

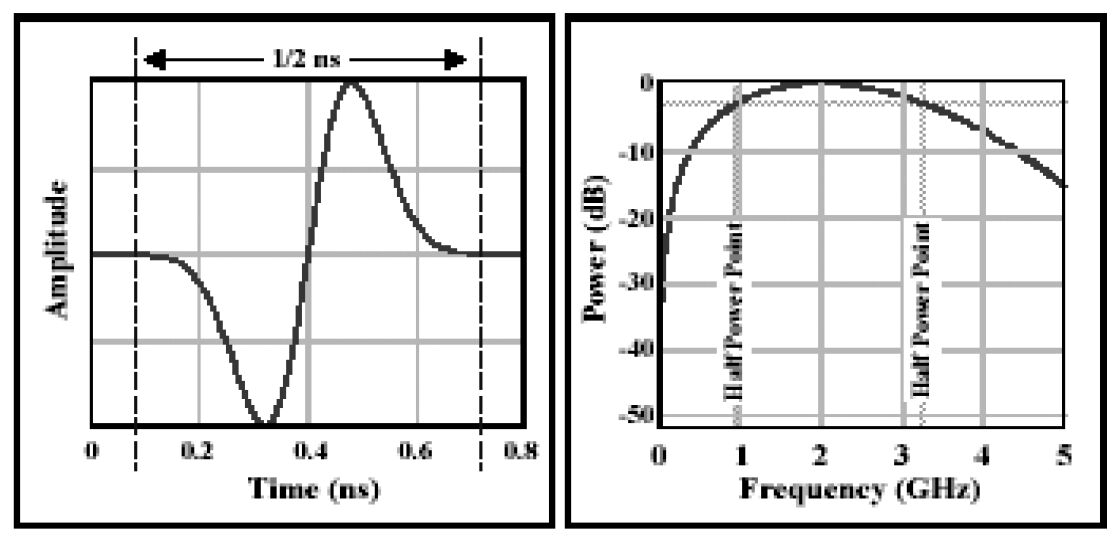
– 77 GHz to 81 GHz Short Range Radar (SRR) < 150 meter (high resolution)

(3) Ultra Wide Band (UWB) Radar

UWB technology employs very narrow or short duration pulses that result in very large or wideband transmission bandwidths (refer to Figure [X], “UWB monocycle time and frequency domains”). Generally UWB is defined as the radio signal whose fractional bandwidth is greater than 20% of the centre frequency or the 10 dB bandwidth occupies 500 MHz or more of spectrum. With appropriate technical standards, UWB devices can operate using spectrum occupied by existing radio services without causing interference, thereby permitting scarce spectrum resources to be used more efficiently.

Figure [X]

UWB monocycle time and frequency domains   
(UWB, "A possible area for standards", GSC 8 Presentation by FCC.)

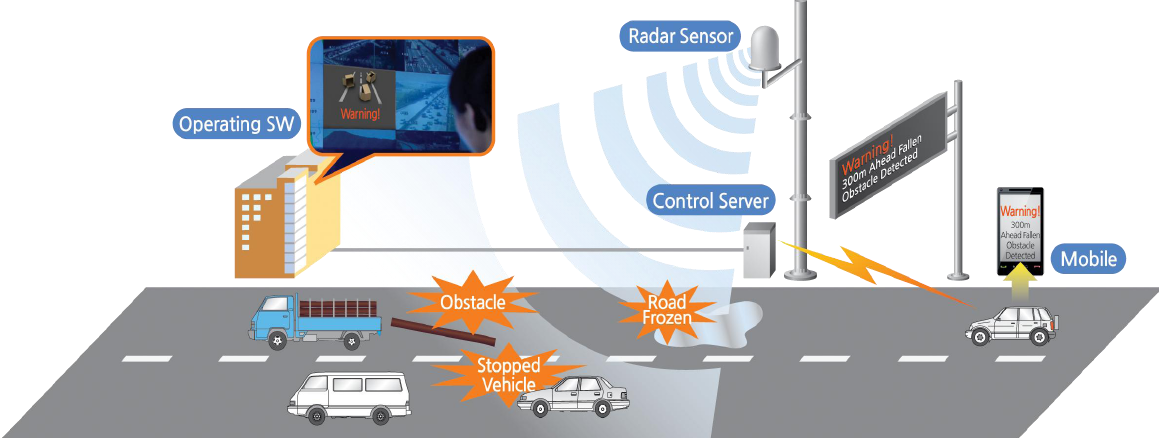


(4) Road radar

Incident detection service deployed in Korea enables drivers in vehicles to receive real-time information for unexpected road situation (obstacle, stopped and wrong way vehicle, frozen-road etc.) through real-time and automatic detection system using radar sensors to prevent unexpected accidents. It also provides traffic information within 1 km from radar sensor. It supports driver in heavy rains and foggy weather to receive real–time information by incident detection system.

FIGURE X

Incident detection service



Characteristics of 34 GHz incident detection radar are given in Table X.:

## 8.3 Frequency usage

Today the frequency allocation for automotive radar application is in a rebuilding phase. Due to technological and commercial constraints the frequency allocation for these safety related applications has been done in the beginning of the last decade in the range of 24 GHz. In Europe e.g. this allocation has been done as an intermediate solution due to the incompatibility with the Radio Astronomy Service, EESS, the Fixed Service and military applications. Therefore the cut-off date of 1st July 2013 has been defined. In July 2011 the EC extends the cut-off date (with modified technical parameter) until 1st January 2018 to allow the car manufacturer a seamless implementation of the 79 GHz technology. The technological evolution during the last years leads to the fact that with a similar effort a higher performance can be reached today.

The industries are trying to seek globally or regionally harmonized frequency allocations for new vehicle radar technologies. The following frequency allocations are under consideration and the relevant study work is undertaken by ITU-R WPs 5A and 5B:

* 76 GHz to 77 GHz Long Range Radar (LRR) > 150 meter
* 77 GHz to 81 GHz Short Range Radar (SRR) < 150 meter (high resolution)

Table [X]

Global frequency usage on millimetre-wave automotive radar

|  | 76 to 77 GHz | | | 77 to 81 GHz | | |
| --- | --- | --- | --- | --- | --- | --- |
|  | Recommendation | Standard | Report/Note | Recommendation | Standard | Report/Notes |
| ITU-R | M.1452-2 |  | SM.2067 | M.1452-2 |  |  |
| M.2057 |  |  | M.2057 |  |  |

## 8.4 Standardization

Table [X]

Global standard on millimetre-wave automotive radar

|  |  |  |
| --- | --- | --- |
| SDO | Standard No. | Standard Title |
| ITU | ITU-R M.1452-2 | Millimetre wave radiocommunication systems for intelligent transport system applications |
| ITU-R M.2057 | Systems characteristics of automotive radars operating in the frequency band 76-81 GHz for intelligent transport systems applications |
| Report: ITU-R M.2322 | Systems Characteristics and Compatibility of Automotive Radars Operating in the 77.5-78 GHz Band for Sharing Studies |

## 8.5 Applications

*[Editor’s note: Text to be added]*

## 8.6 Region 1

*[Editor’s note: Text to be added]*

### 8.6.1 Frequency usage

Table [X]

Frequency usage on millimetre-wave vehicular radar in Europe

|  | 76 to 77 GHz | | | 77 to 81 GHz | | |
| --- | --- | --- | --- | --- | --- | --- |
|  | Regulation | Standard | Report/Notes | Regulation | Standard | Report/Notes |
| Europe  - ECC | -ERC/REC 70-03   Annex 5  -ECC/DEC/(02)01 | ETSI EN 301 091-1 V1.3.3 (2006-11) |  | - 2004/545/EC  -ERC/REC 70-03 Annex 5  -ECC/DEC/(04)03 | ETSI EN 302 264-1 V1.1.1 (2009-06) | - ECC/REP 056  - Partly: CEPT Report 003  - CEPT Report 36 &37 |
| - Russia | SFMC Decision No. 07-20-03-001 Annex 7 |  |  |  |  |  |
| Gulf States | CITC |  |  |  |  |  |

### 8.6.2 Standardization

Table [X]

Standards on millimetre-wave vehicular radar in Europe

|  |  |  |
| --- | --- | --- |
| SDO | Standard No. | Standard Title |
| ETSI | TR 101 983 | Radio equipment to be used in the 76 GHz to 77 GHz band; System Reference Document for Short-Range Radar to be fitted on road infrastructure |
| EN 301 091 parts 1-2 | Short Range Devices; Road Transport and Traffic Telematics (RTTT); Radar equipment operating in the 76 GHz to 77 GHz range; |
| EN 302 288 parts 1-2 | Short Range Devices; Road Transport and Traffic Telematics (RTTT); Short range radar equipment operating in the 24 GHz range; |
| EN 302 264 | Short Range Devices, Road Transport and Traffic Telematics (RTTT); Ultra Wide Band Radar Equipment Operating above 60 GHz |

## 8.7 Region 2

*[Editor’s note: Text to be added]*

### 8.7.1 Frequency usage

Table [X]

Frequency usage on millimetre-wave vehicular radar in North and South America

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
|  | 76 to 77 GHz | | | 77 to 81 GHz | | |
|  | Regulation | Standard | Report/Notes | Regulation | Standard | Report/Notes |
| U.S.A. | FCC Part 15/15.253 |  |  |  |  |  |
| Canada | Spectrum Utilization Policies SP- 47 GHz | [RSS 251](https://www.ic.gc.ca/eic/site/smt-gst.nsf/vwapj/RSS-251-issue1.pdf/$FILE/RSS-251-issue1.pdf) |  |  |  |  |
| Mexico | Cofetel usually accepts FCC regulation |  |  |  |  |  |
| Brazil | ANATE resolution No.506 |  |  |  |  |  |

### 8.7.2 Standardization

Table [X]

Standards on millimetre-wave vehicular radar in North and South America

|  |  |  |
| --- | --- | --- |
| SDO | Standard No. | Standard Title |
|  |  |  |

## 8.8 Region 3

***[****Editor´s Note: The following technical characteristics will be included in section 8.1 overview at a later stage]****]***

**Technical characteristics**

*[Editor’s note: Text to be added]*

(1) Incident detection radar

Characteristics of 34 GHz incident detection radar are given in Table X.

TABLE X

Road radar system

| Characteristic(Parameter) | Value |
| --- | --- |
| **Operational characteristics** | |
| Application/Service | Road Incident Detection System |
| Typical installation | Road Side Pole(or gantry) |
| **Technical Characteristics** | |
| Max. range | 1 000 m |
| Frequency range | 34.275~34.875 GHz |
| Specified bandwidth (typical) | Up to 600 MHz |
| Peak Power (e.i.r.p) | Up to +55 dBm |
| Mean Power (e.i.r.p) | Up to +45 dBm |

### 8.8.1 Frequency usage

In APT countries, frequency bands of 24, 60, 76 and 79 GHz has been used. For global harmonization of ITS, APT countries like Australia are considering European activities which use 79 GHz as a permanent band. Also, Hong Kong is considering the plan to open the 79 GHz band for automotive radar systems utilizing ultra-wideband technology. In March 2010, the Ministry of Internal Affairs and Communications (MIC) in Japan has started a study group in the Information and Communications Council for the introduction of high-resolution radar in the 79 GHz frequency band for national use, and has allocated 78-81 GHz band for high-resolution radar in December 2012. [5]

Table [X]

Frequency usage on millimetre-wave automotive radar in Asia-Pacific

|  | 76 to 77 GHz | | | 77 to 81 GHz | | |
| --- | --- | --- | --- | --- | --- | --- |
|  | Regulation | Standard | Report/Notes | Regulation | Standard | Report/Notes |
| Korea, Republic of | Rules on Radio Equipment (Article **29** Paragraph 9) (2013-01-03)” |  |  |  |  |  |
| China | Technical Specification for Micropower (Short Distance) Radio Equipments, part XIV |  |  |  |  |  |
| Japan |  | ARIB STD-T48 |  |  | ARIB STD-T111 |  |
| Singapore |  | IMDA TS SRD |  |  | IMDA TS UWB |  |
| Taiwan, China | LP002 2005-0324 |  |  |  |  |  |
| Thailand | NTC TS 1011-2549 |  |  |  |  |  |

### 8.8.2 Standardization

TABLE [X]

Standards on millimetre-wave automotive radar in Asia-Pacific

|  |  |  |
| --- | --- | --- |
| SDO | Standard No. | Standard Title |
| ARIB | STD-T111 | 79 GHz Band High-Resolution Radar |

*[Editor´s Note: Applications to be shifted to 8.1 overview].*

Applications

Table [X]

Usage status of automotive radar in Asia-Pacific

| Country | Frequency Band | Technology/ Standard | Service | Deployment or plan Year |
| --- | --- | --- | --- | --- |
| Australia | 22–26.5 GHz |  | Ultra-wideband short-range vehicle radar (UWB SRR) systems for collision avoidance | - |
| 76–77 GHz |  | Long-range vehicle radar (intelligent cruise control) |  |
| China | 76-77 GHz | Radar | Vehicular range radar | Enacted in 2005 |
| 24.25-26.65 GHz | Radar | Vehicular range radar | Enacted in 2012 |
| Hong Kong | 76–77 GHz | Exemption from licensing order | Vehicular radar systems | 2005 |
| Japan | 22-29 GHz | Quasi-millimetre and millimetre wave system | Detect obstacles (Sensor) | Enacted in 2010 |
| 60.5 GHz/76.5 GHz | Enacted in 1997 |
| 78-81 GHz | Enacted in 2012 |
| Korea | 76-77 GHz | Radar | Vehicular collision avoidance radar | 2008 |
| 24.25-26.65 GHz | Radar | Vehicular collision avoidance radar | 2012 |
| Singapore | 76-77 GHz | Radar | Short-range radar systems such as automatic cruise control and collision warning systems for vehicle | 2002 |
| 77-81 GHz | Radar | Vehicular Radar | 2008 |
| Thailand | 5.725-5.875 GHz | - | Radar application | Regulation adopted in 2007 |
| 24.05–24.25 GHz | - | Radar application | Regulation adopted in 2007 |
| 76-81 GHz | - | Radar application | Regulation adopted in 2007 |
| 76-77 GHz | Compliance Standard: FCC Part 15.253 or EN 301 091-1 | Vehicle radar application | Regulation adopted in 2006 |

# 9 Conclusions

*[Editor’s note: Text to be added]*

Intelligent transport systems attract many people’s interest because it could improve the safety of road traffic, ensure smoother traffic, reduce environmental burdens, and stimulate regional economic activity, etc. From the survey results, major deployed ITS systems in APT countries were classified as electronic toll collection, automotive radar, and vehicle information & communication. As the importance of car safety is increasing, cooperative system is widely considered for international deployment. Especially in Europe and North America, frequency band 5.855~5.925 GHz was assigned for cooperative systems and many development project was performed. Radiocommunication technologies for cooperative system will be used to automated driving. Regarding these activities, administrations should study the optimal frequency spectrum for cooperative systems and try to reach regional/international harmonization of spectrum arrangements.

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[3] Report ITU-R M.2228, “Advanced Intelligent Transport Systems (ITS) radiocommunication”

[4] Recommendation ITU-R M.1453, “Intelligent Transport Systems – dedicated short‑range communications at 5.8 GHz”

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