



# Towards a Common Architecture Framework for ITS

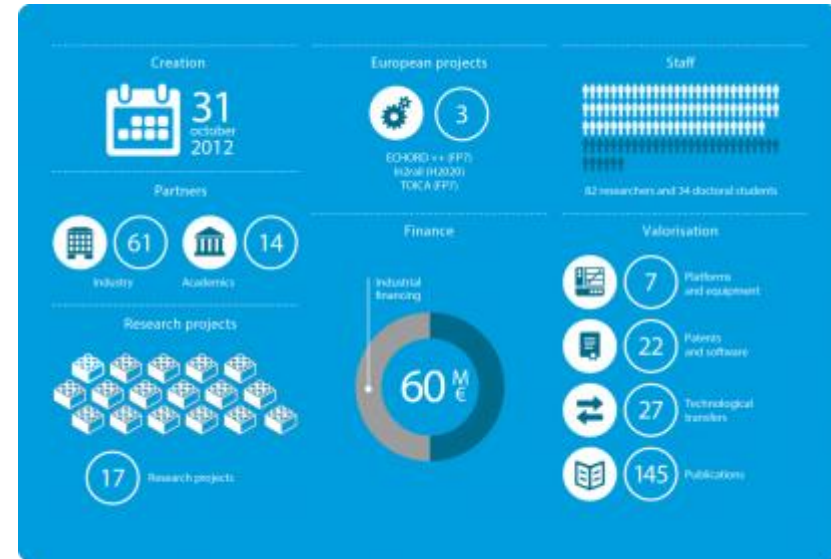
Antonio Kung – Trialog

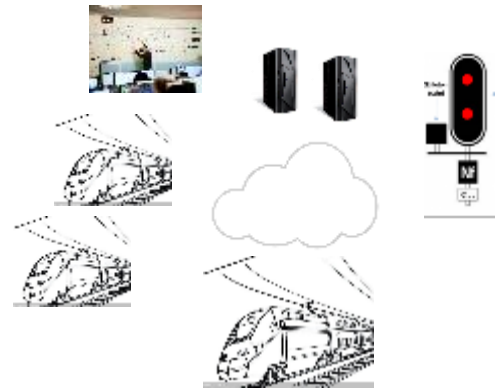
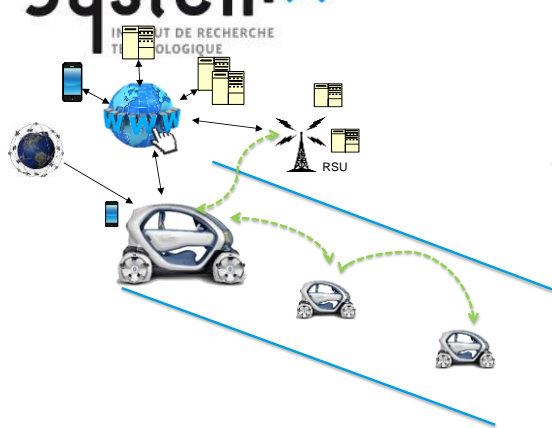
With the participation of

Witold Klaudel – Project leader (Renault), Antoine Boulanger (PSA), Cyril Grépet (Trialog), Christophe Jouvray (Valeo), Laura Rodriguez (Airbus), Benjamin Venelle (Valeo).



- ◆ **SystemX – French Institute for technology research**
  - ◆ Creation: 2012
  - ◆ Focus: Digital engineering of complex system
  - ◆ Approach: Industry collaboration
- ◆ **CTI – Cybersecurity of Intelligent Transport**
  - ◆ One project of SystemX
  - ◆ June 2016 – 4 years.
- ◆ **Trialog**
  - ◆ SME focusing on engineering of complex system, member of CTI





### New functions

- Driving: assistance, automation, cooperative decisions
- Concierge service, diagnosis, remote update / repair, e-call
- Internet connectivity and on-board services

### New security threats

- Drastic increase in attack surfaces
- **Direct impact on safety**
- Complexity of preparation of the attacks but simplicity of their execution, knowledge accessibility
- Cybercrime in organized crime and terrorism

### Privacy protection

- Privacy regulation compliance
- Privacy-by-design and citizen empowerment

New responsibilities and regulatory constraints

Application domains: aeronautic, automotive, railways



## ◆ Objective: Addressing the security of intelligent transports

- ◆ Three industries with “similar” architecture and safety concerns
- ◆ Promote a “common” architecture and practices for the 3 domains

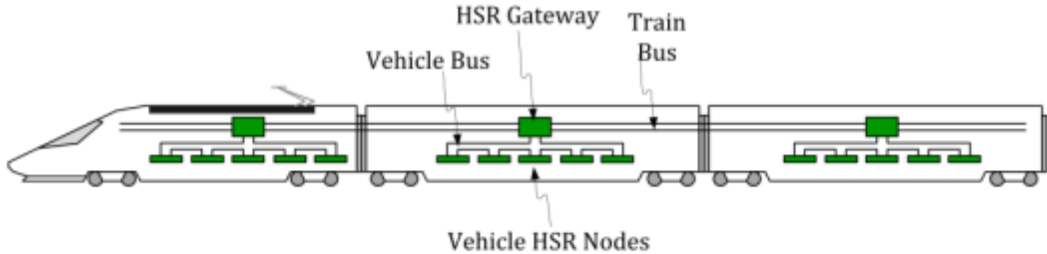


Small and medium-sized enterprises



National agencies

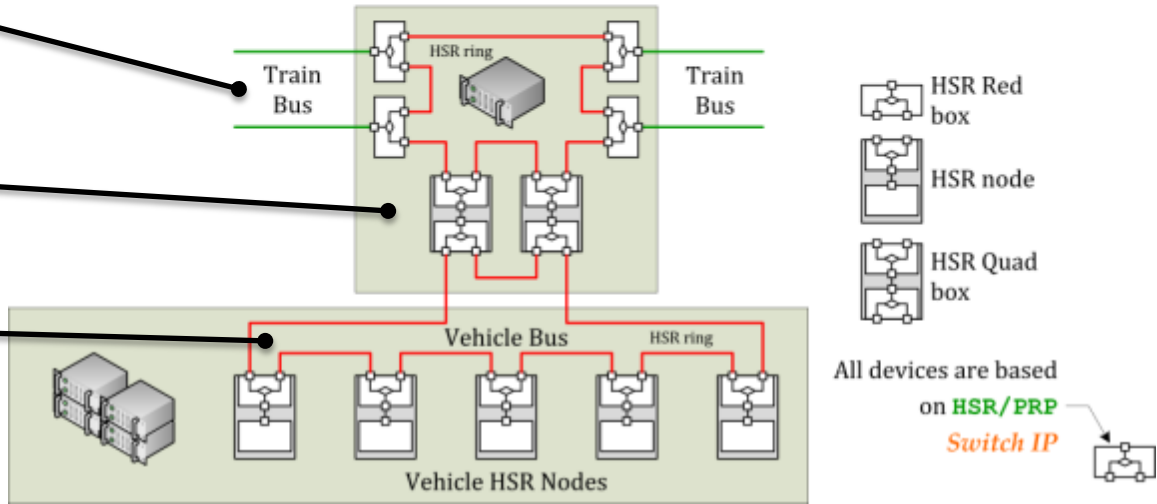
# Current transport architectures



High-speed backbone

Network gateways

Dedicated networks



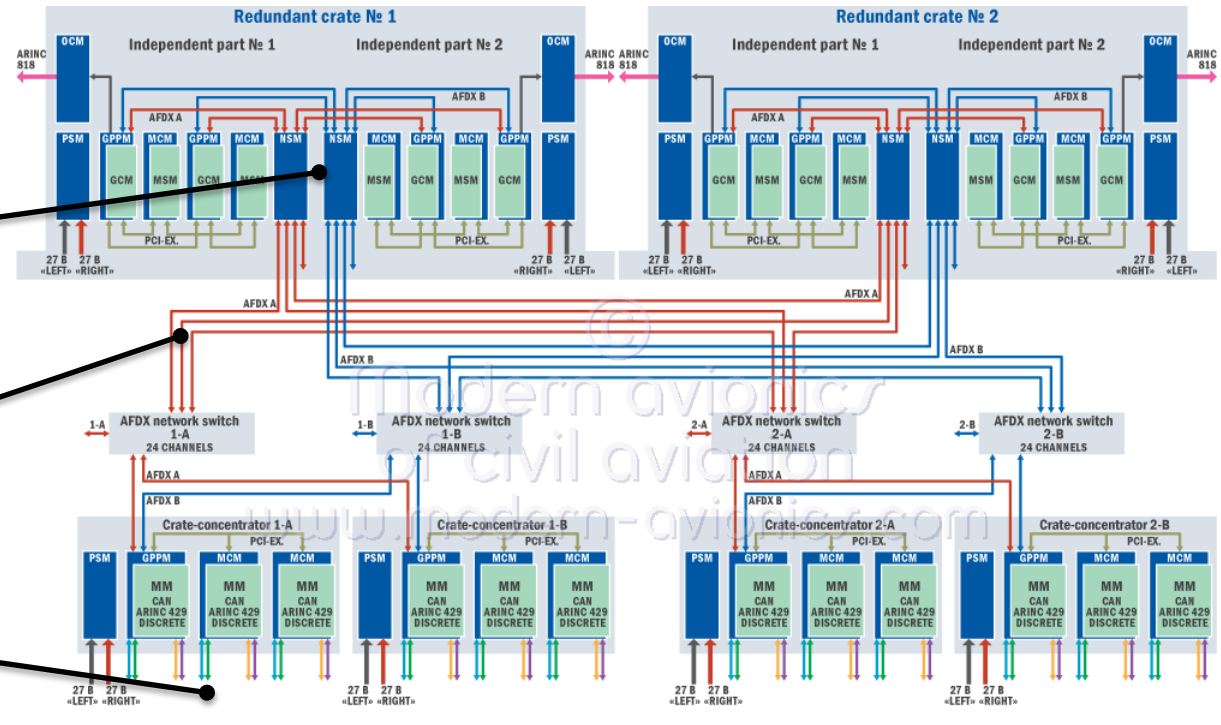
Courtesy soc-e.com

# Current transport architecture

Network gateways

High-speed backbone

Dedicated networks



<b>GPPM</b>	GENERAL-PURPOSE PROCESSOR MODULE	<b>PSM</b>	POWER SUPPLY MODULE		AFDX A		ARINC 429
<b>NSM</b>	AFDX NETWORK SWITCH MODULE	<b>GCM, MSM</b>	DEDICATED MEZZANINE MODULES		AFDX B		0 B / DISCONNECTION
<b>MCM</b>	PNC/XMC UNIFIED MEZZANINE CARRIER MODULE	<b>MM</b>	DEDICATED MEZZANINE MODULE (CAN, ARINC-429, DISCRETE)		CAN		27 B / DISCONNECTION
<b>OCM</b>	OPTICAL CONVERTER MODULE						

Courtesy modern-avionics.com



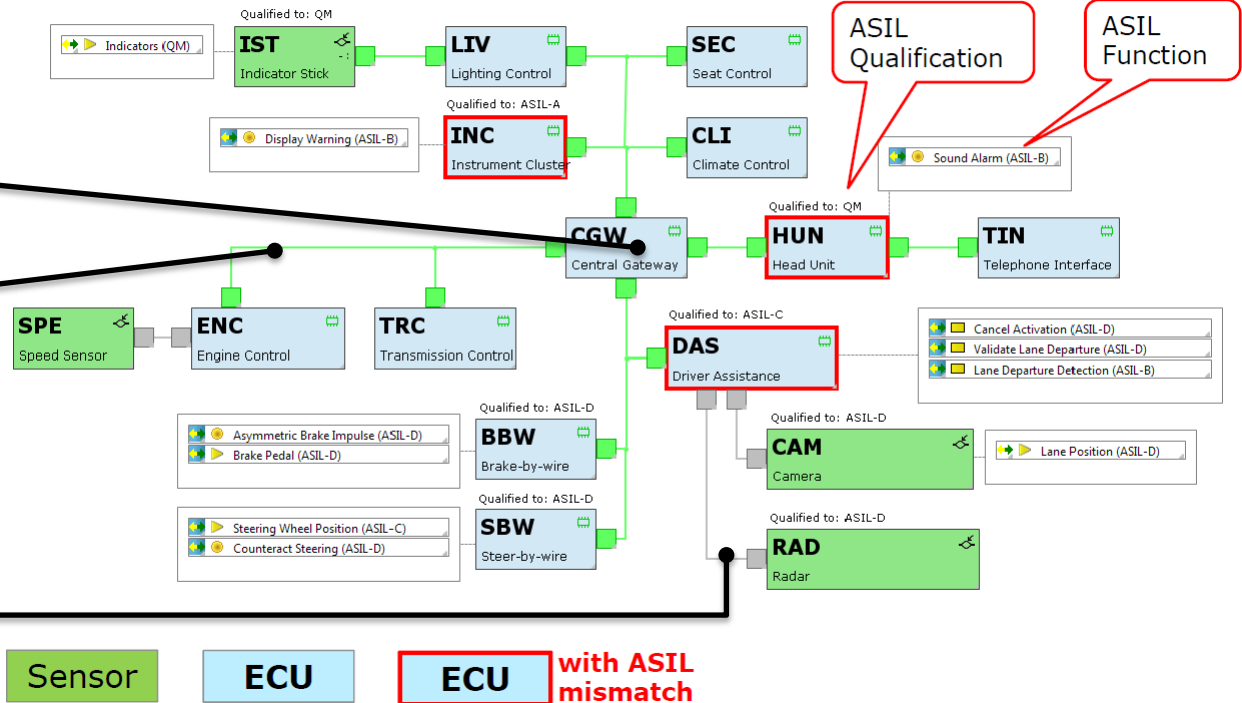
# Current transport architecture

## Lane Departure Warning

Network gateways

Dedicated networks

High-speed backbone



*Courtesy vector.com*



Controllers	Avionic & Flight systems	Core Vehicle Services	CBTC signaling, ...
	Mission & Payload	Infotainment	Passenger information, ...
Radios	UAV to command center	Vehicle to Infrastructure (V2I)	Train to Supervision/Maintenance
	UAV fleet cooperation	Vehicle to Vehicle (V2V)	Train to Infrastructure Signaling
Sensors	Altimeter, Airspeed, Sonar, ...	Camera, LIDAR, ...	Signaling balises, ...
	GPS, VOR/ILS, DME, ...	Galileo, GPS, ...	Odometer, beacons, ...
Networks	ARINC 429 & MIL-STD-1553 ↓	CAN, LIN, Flexray ↓	
	Ethernet (AFDX)	Ethernet (BroadR-Reach)	Ethernet (PRP & HSR)



# Similar attacks for all domains

## Lessons learned

- ◆ **2011 – CIA's drone hijacked by Iran**

- ◆ Lockheed Martin RQ-170 Sentinel
- ◆ GPS spoofing to force drone to land



[https://en.wikipedia.org/wiki/Iran-U.S.\\_RQ-170\\_incident](https://en.wikipedia.org/wiki/Iran-U.S._RQ-170_incident)

- ◆ **2012 – Fatal UAV crash in South Korea**

- ◆ Schiebel S-100 Camcopter
- ◆ GPS jamming (from North Korea ?)



<https://www.suasnews.com/2012/05/schiebel-s-100-crash-kills-engineer-in-south-korea/>

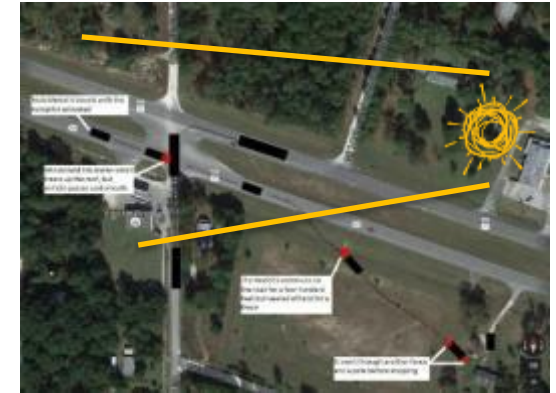


Sensors can be fooled or jammed  
Enforce sensor fusion against fault injection

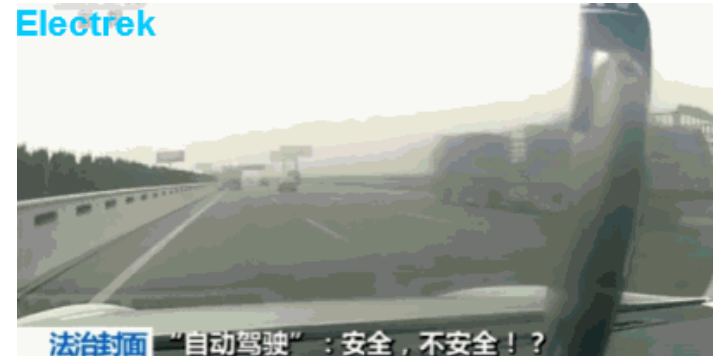


## Main perception means

- ◆ 2015 – LiDAR can be fooled by fake echoes
- ◆ 2016 – Fatal Tesla accidents in China and Florida
  - ◆ Obstacle misdetection (China)
  - ◆ Blind camera (Florida)



<https://electrek.co/2016/07/01/understanding-fatal-tesla-accident-autopilot-nhtsa-probe/>



<https://electrek.co/2016/09/14/another-fatal-tesla-autopilot-crash-emerges-model-s-hits-a-streetsweeper-truck-caught-on-dashcam/>



Authenticate onboard devices to vehicle



### ◆ 2016 – Remote attack on Tesla

- ◆ 0-day in the communication unit
- ◆ Direct access to vehicle internals

### ◆ 2016 – Tesla's remote control

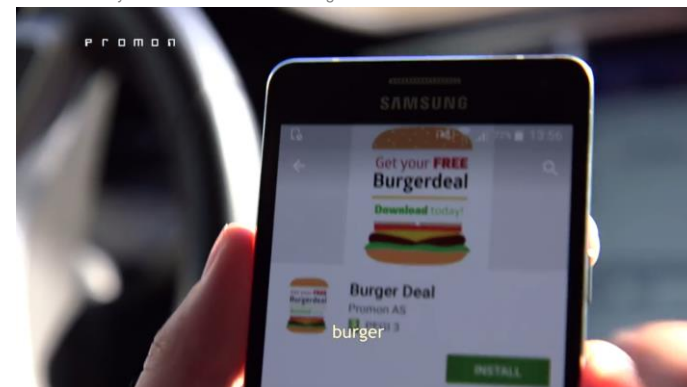
- ◆ Rogue wifi hotspot at restaurant
- ◆ Free burger if you install this app
- ◆ Malicious app drives Tesla's app



Isolate vehicle internals from exposed devices  
Enforce network control & authentication



<http://keenlab.tencent.com/en/2016/09/19/Keen-Security-Lab-of-Tencent-Car-Hacking-Research-Remote-Attack-to-Tesla-Cars/>



<https://promon.co/blog/tesla-cars-can-be-stolen-by-hacking-the-app/>



- ◆ **2015 – Remote attack on Jeep**
  - ◆ Anonymous access to infotainment
  - ◆ Malicious update of a critical controller



[http://www.ioactive.com/pdfs/IOActive\\_Remote\\_Car\\_Hacking.pdf](http://www.ioactive.com/pdfs/IOActive_Remote_Car_Hacking.pdf)

- ◆ **2016 – 1.4M of car were recalled by GM**
  - ◆ 0-day in IVI systems of Chrysler, Dodge, Jeep and Ram
  - ◆ Estimated time: 5 years
  - ◆ Connected cars by 2022: 203M



Speeding up security fix delivery to reduce exposure  
Isolation btw privileged and less privileged ECUs



<http://www.allpar.com/corporate/tech/firmware-updates.html>

# Achieved Work

Common use cases

Taxonomy of topics

Principles on on architecture

◆ **Use case viewpoints**

- ◆ Main IOT perception means
- ◆ Main communication channels
- ◆ Main embedded devices
- ◆ On-board storage and shared services

[2] **Common description of use cases and threats**

◆ **Identification of threats for each viewpoints**

◆ **Identification of principles for mitigation**



Robustness of the system against sensors



- ◆ Camera, LIDAR, ...
- ◆ Galileo, GPS, ...



- ◆ Altimeter, airspeed, sonar, ...
- ◆ GPS, VOR/ILS, DME, ...



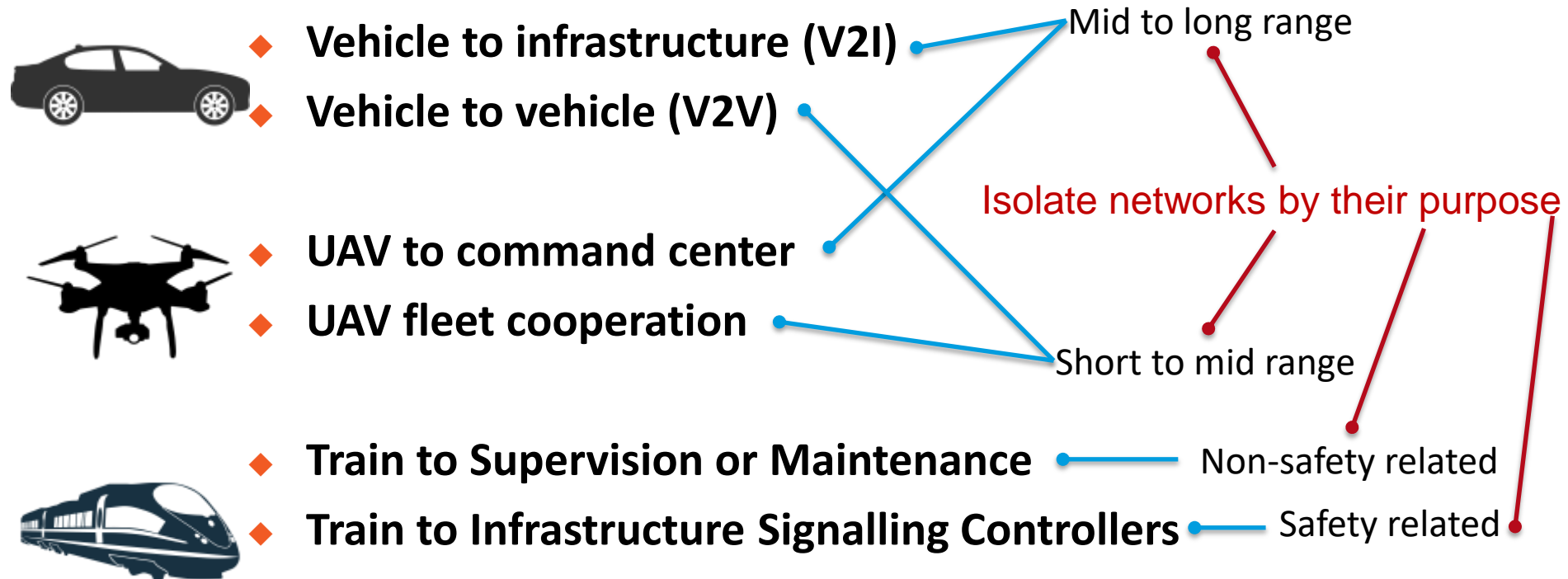
- ◆ Balise reader
- ◆ Odometer

Environment analysis

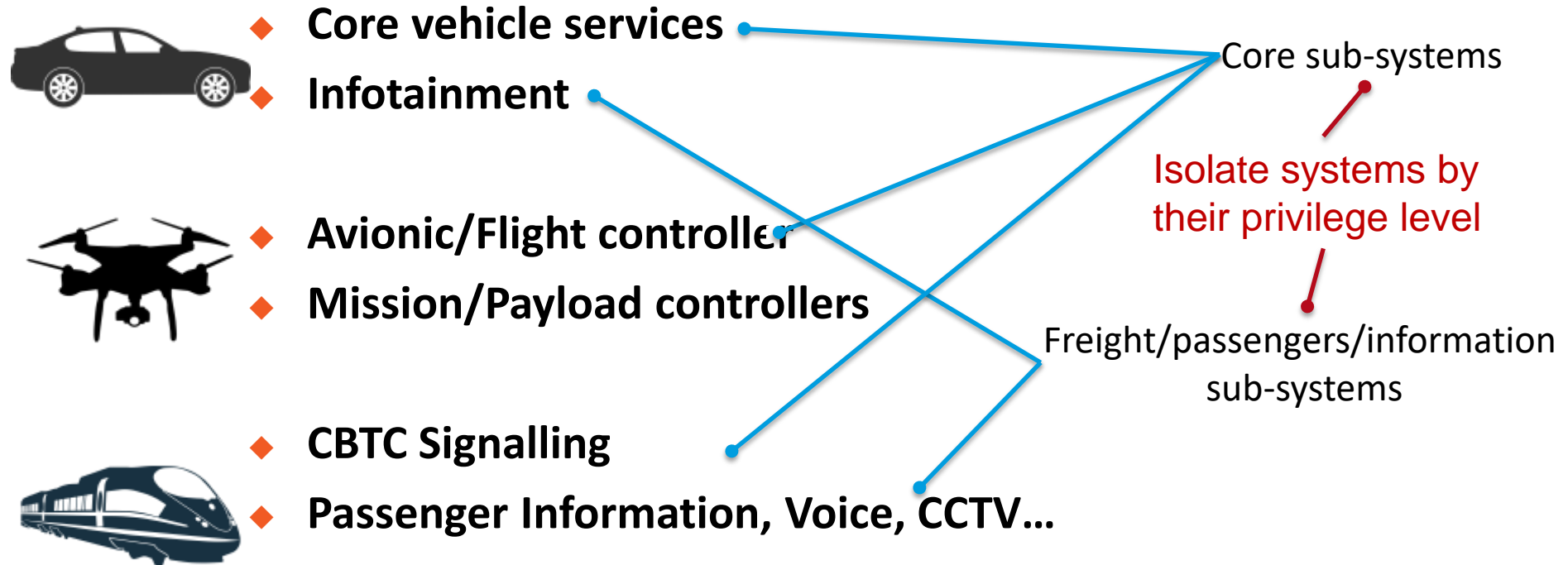
Protect system from rogue sensors

Positioning system





Robustness of the system against malicious freight/passenger



Mitigates with system failures & 0-days



- ◆ **Event data recorder (EDR) & system logs**
- ◆ **Update over the air (OTA)**



- ◆ **Flight data recorder (FDR)**
- ◆ **UAV recall for updates (??)**



- ◆ **Event data recorder (EDR)**
- ◆ **System logs remote download**
- ◆ **Update over the air (OTA)**

Forensic & diagnosis

Update management policy

## ◆ Certified/non-certified isolation



- ◆ No access to certified controllers
- ◆ Legal constraint for aeronautic systems

## ◆ Safety/non-safety isolation



- ◆ Controller segregation by their safety level
- ◆ Legal constraint for railway systems

## ◆ Critical/non-critical isolation



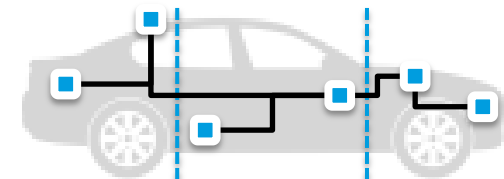
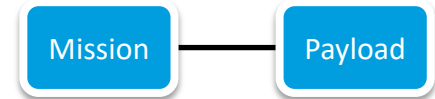
- ◆ ECU distribution by their criticality level (natural)

Main embedded services

Certified

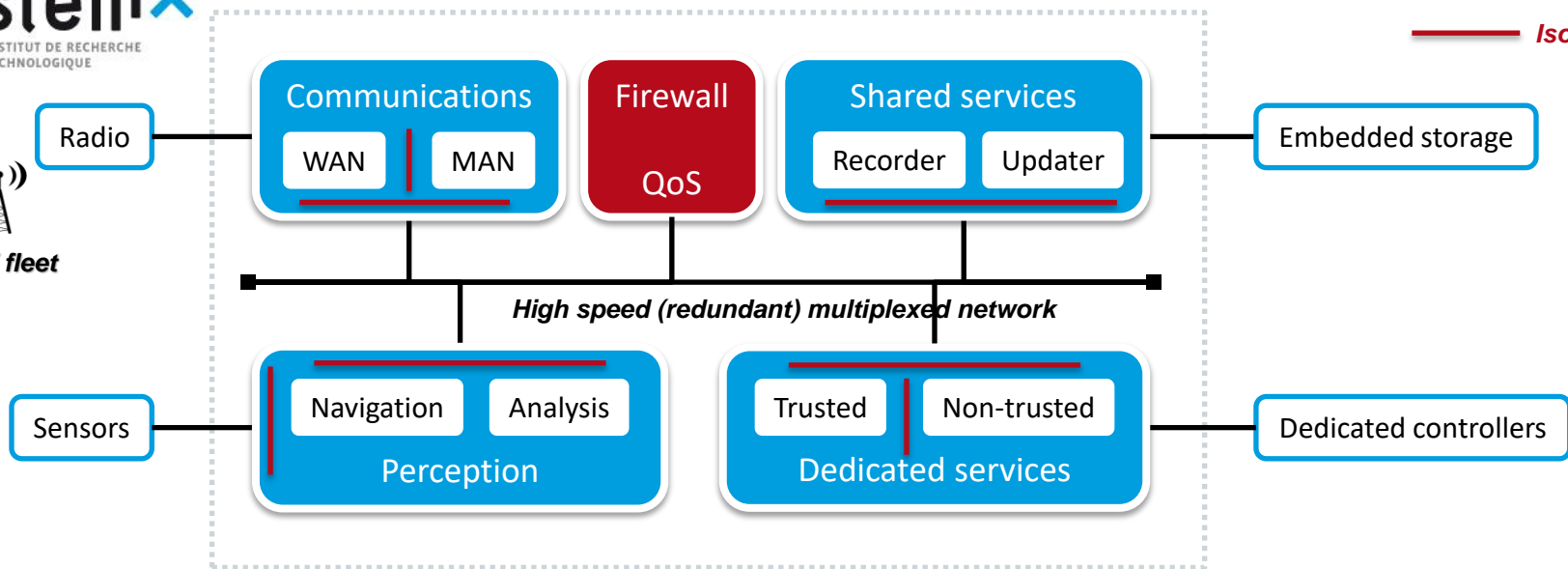
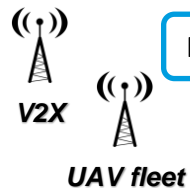


Non-certified



Non-critical

Critical



- ◆ **Internal work**

- Architecture
- Demonstration

- ◆ **Community work**

- ◆ Contribution 1 (now):
  - ◆ Towards common use case template
  - ◆ Towards common architecture framework
- ◆ Contribution 2 (in the future):
  - ◆ Towards common cybersecurity process

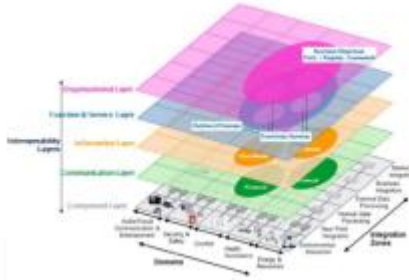
# Community Work

Towards common use case template

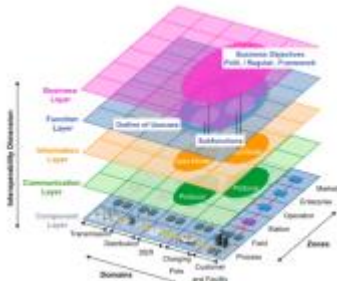
Towards common architecture framework

◆ **Home and building architecture model (HBAM)**

- ◆ <http://www.corenetix.com/downloads/german-standardization-roadmap-smart-home---building--version-2-0-data.pdf>

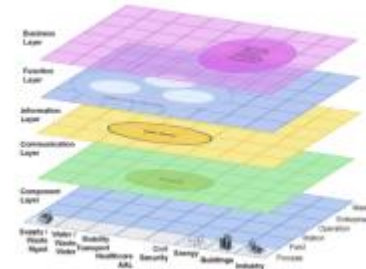


◆ **Electric mobility architecture model (EMAM)**



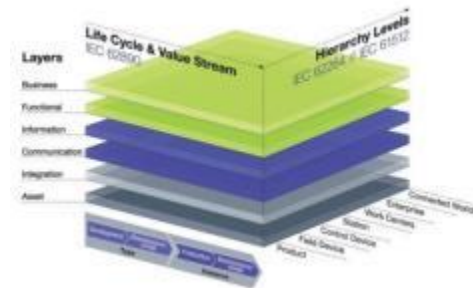
◆ **Smart City Infrastructure architecture model (SCIAM)**

- ◆ <https://www.dke.de/resource/blob/778248/d2afdaf62551586a54b3270ef78d2632/the-german-standardization-roadmap-smart-city-version-1-0-data.pdf>



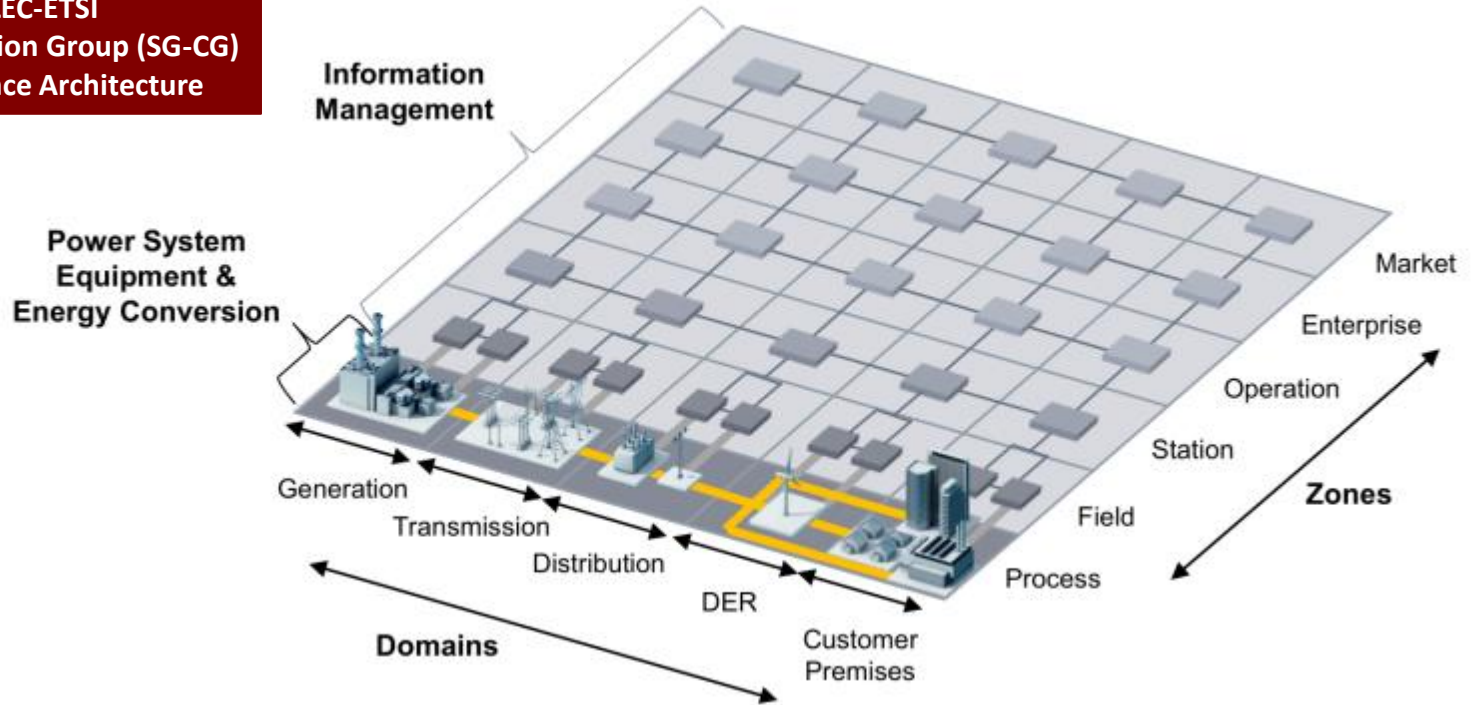
◆ **Reference Architecture Model Industry 4.0 (RAMI)**

- ◆ <https://www.zvei.org/en/subjects/industry-4-0/the-reference-architectural-model-rami-40-and-the-industrie-40-component/>

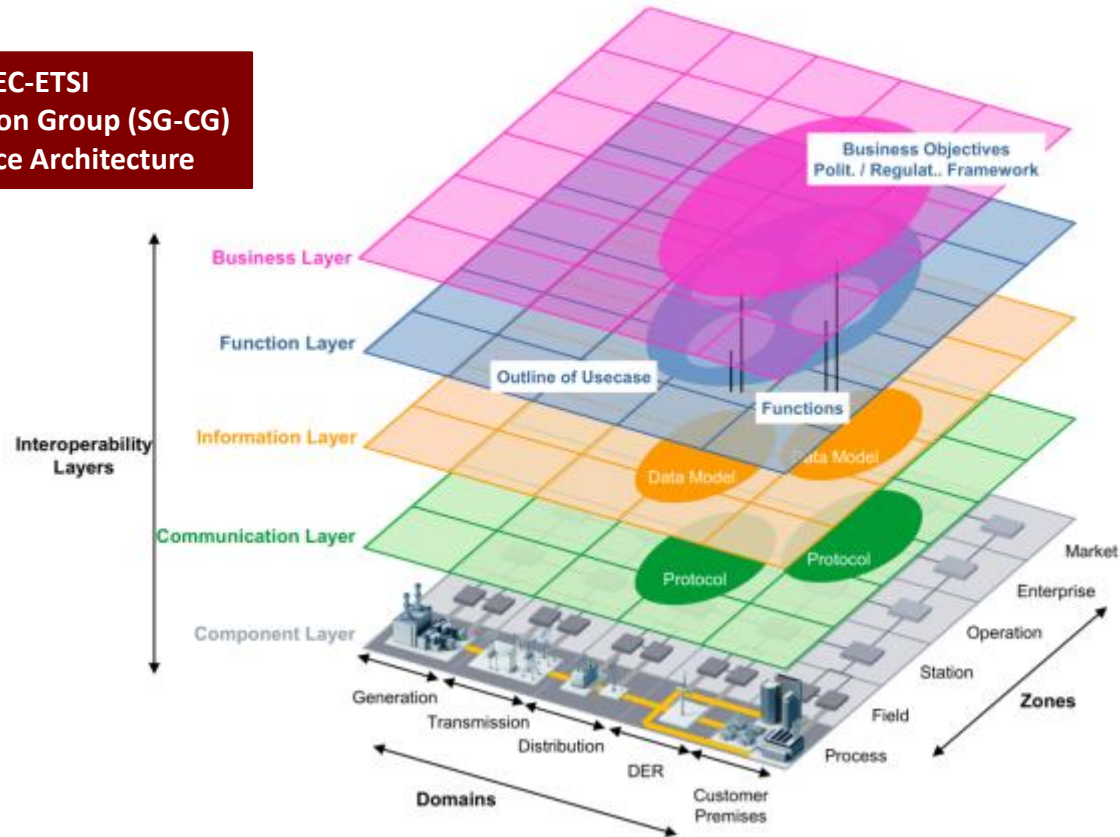




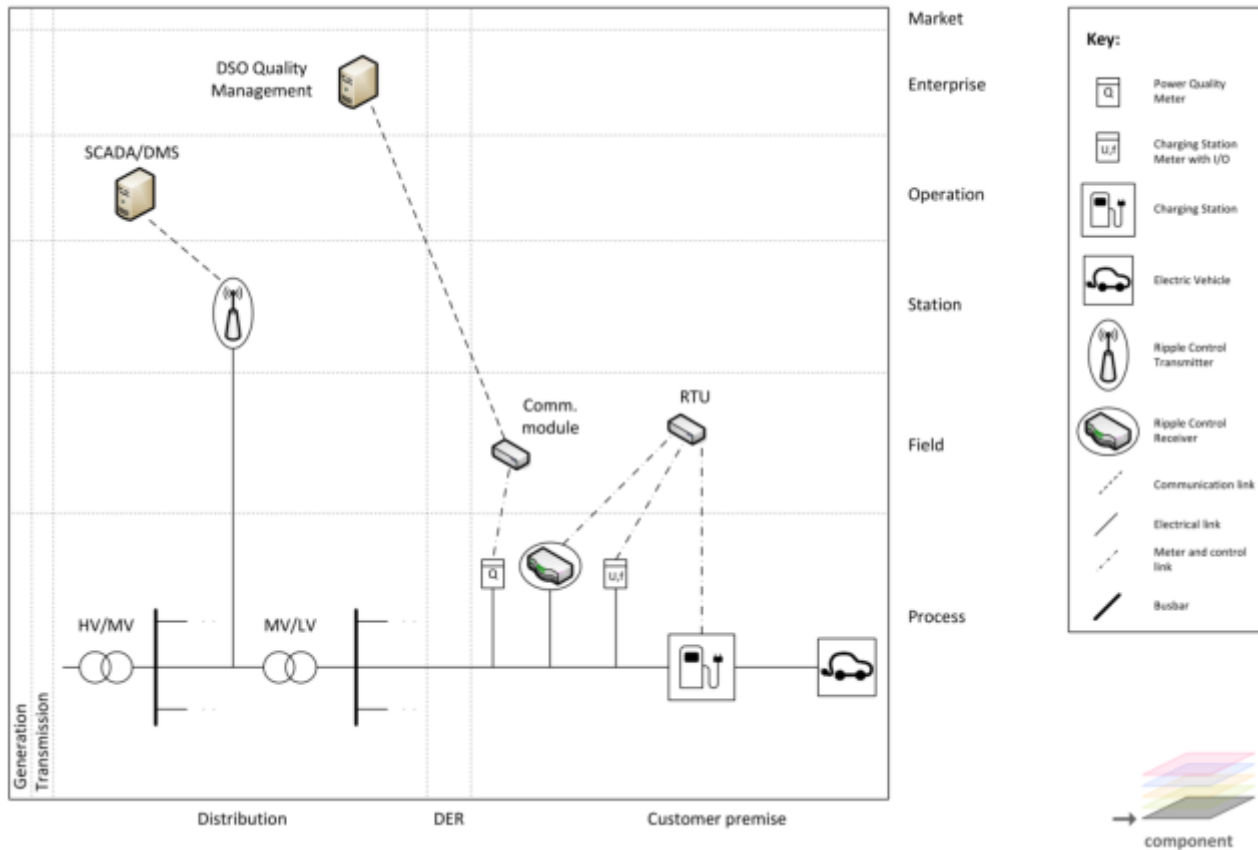
**CEN-CENELEC-ETSI**  
**Smart Grid Coordination Group (SG-CG)**  
**Smart Grid Reference Architecture**



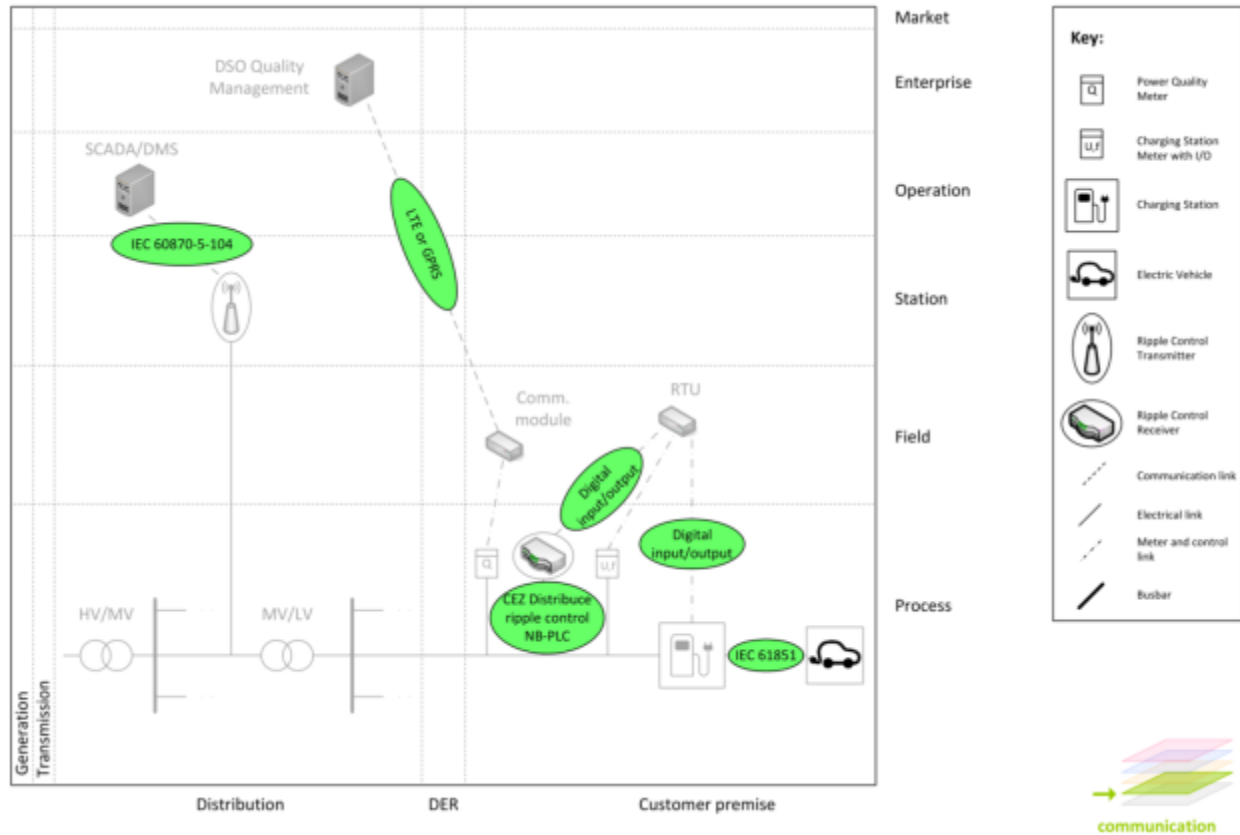
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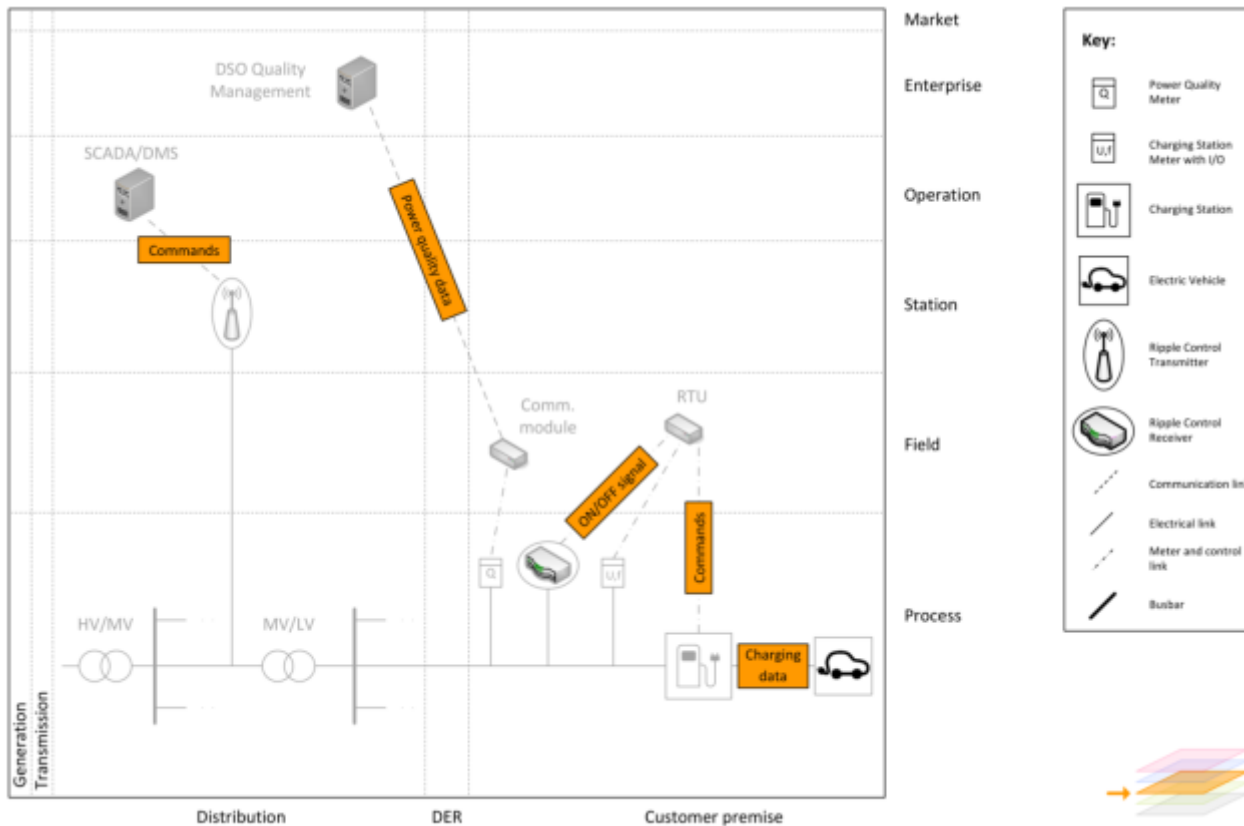
# Example of EV charging component plane

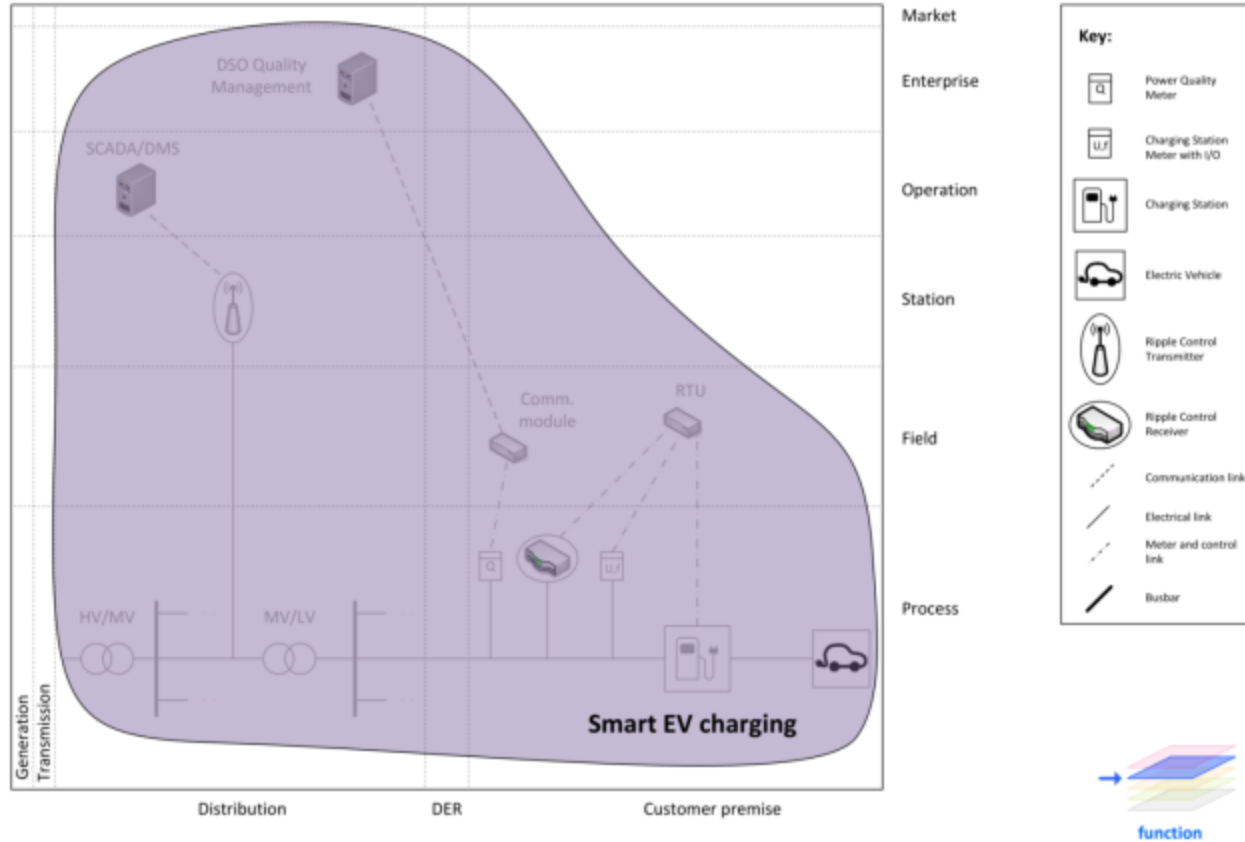


# Example of EV charging (Communication Plane)

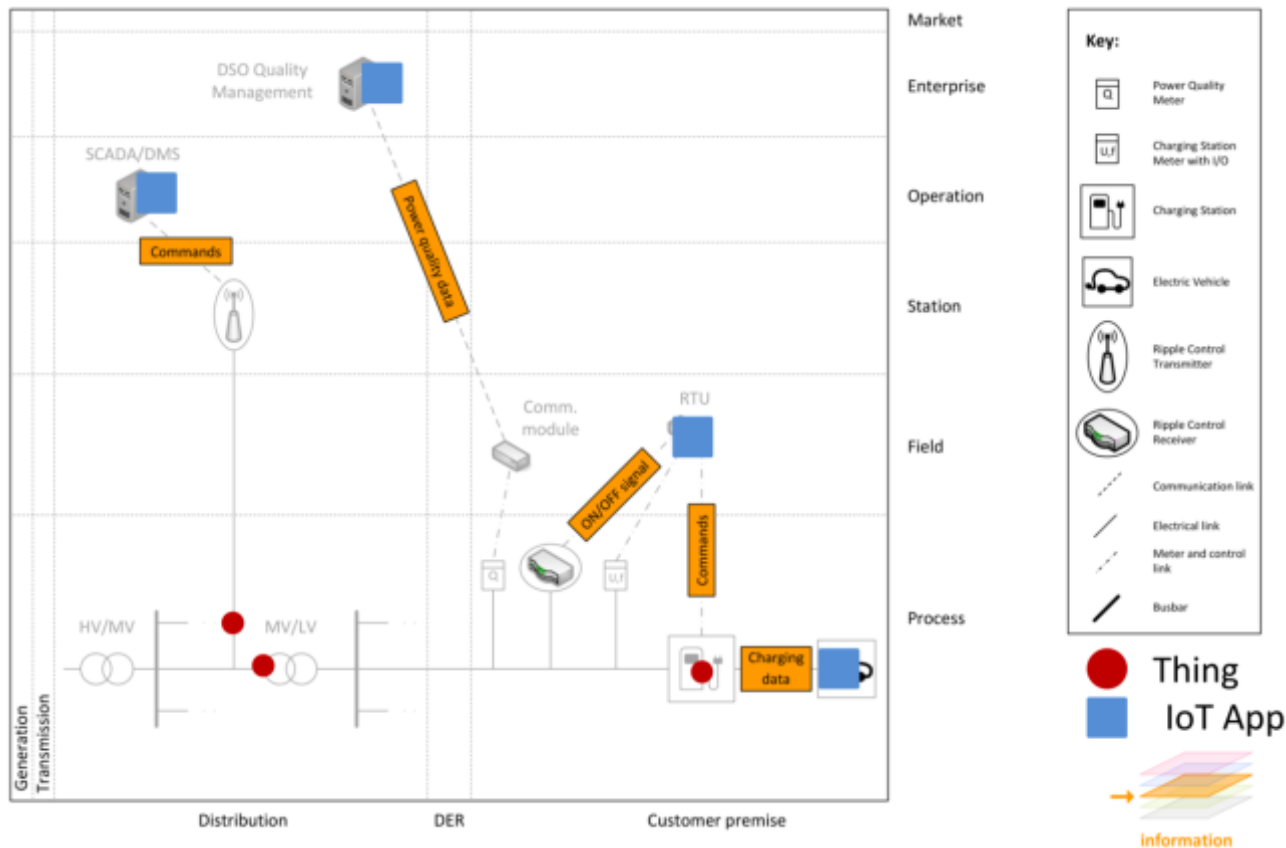


# Example of EV charging (Information Plane)

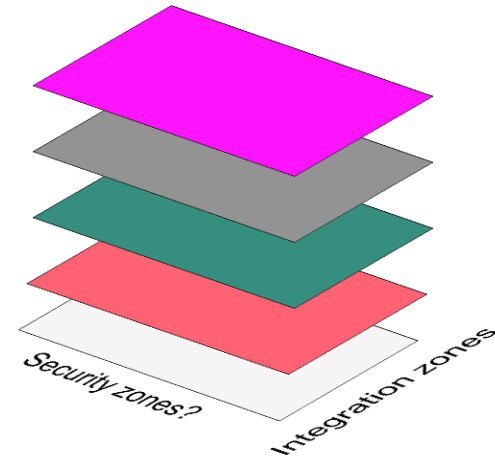
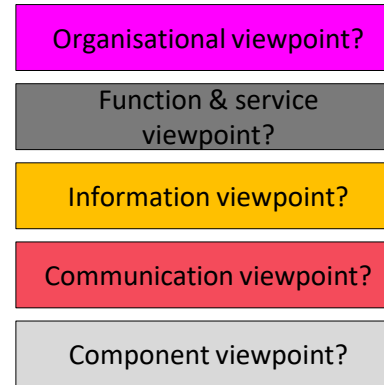




# IoT in the Smart EV charging Information plane



- ◆ Three dimension approach
- ◆ Integration of misuse cases
- ◆ Integration of life cycle
  - ◆ Identify, protect, detect, response, recover
- ◆ Integration of security and safety

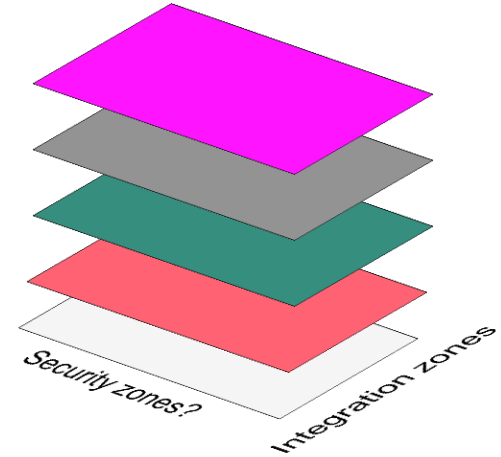
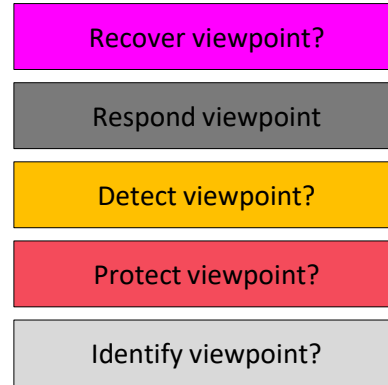




	<b>?</b>	

Uncontrolled zone    Stakeholder Controlled zone    Trusted zone

Market integration  
Business integration  
External Data processing  
Internal Data processing  
Near-field interaction  
Environmental interaction



- ◆ **Investigate several templates**
- ◆ **Describes the same use case for each template**
- ◆ **Align with a common cybersecurity architecture model**



# Thanks

Antonio Kung. [www.trialog.com](http://www.trialog.com)

<http://www.irt-systemx.fr/en/>

