

Prevention of a cybersecurity threat in a Connected & Autonomous Vehicle

! beyond ! THE CAR

Aug.26th 2019

Hyundai Motors



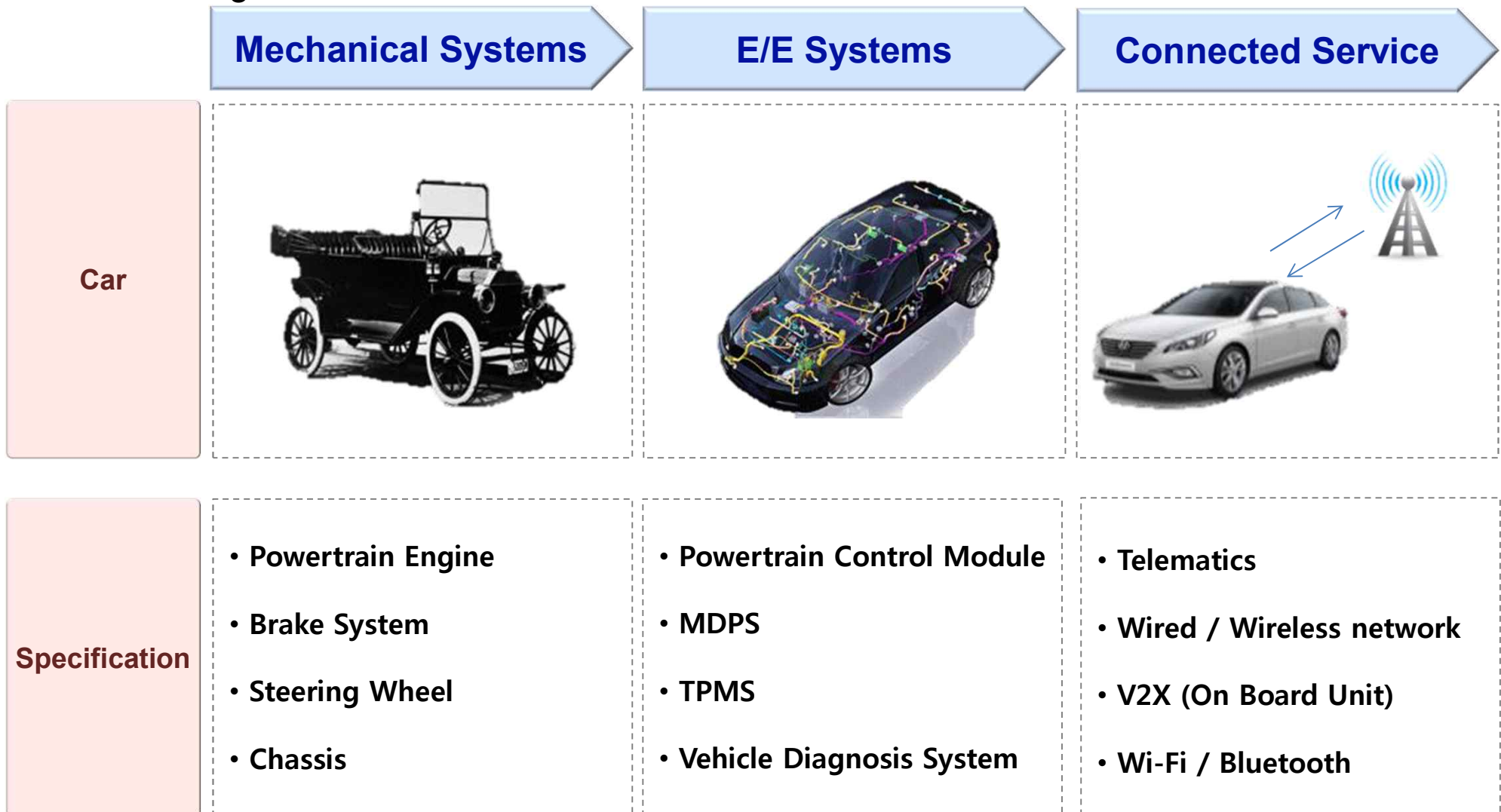
HYUNDAI
MOTOR GROUP

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- II. Cybersecurity Standardization
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- IV. Cybersecurity in Autonomous Vehicles
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Vehicle – Paradigm Shift

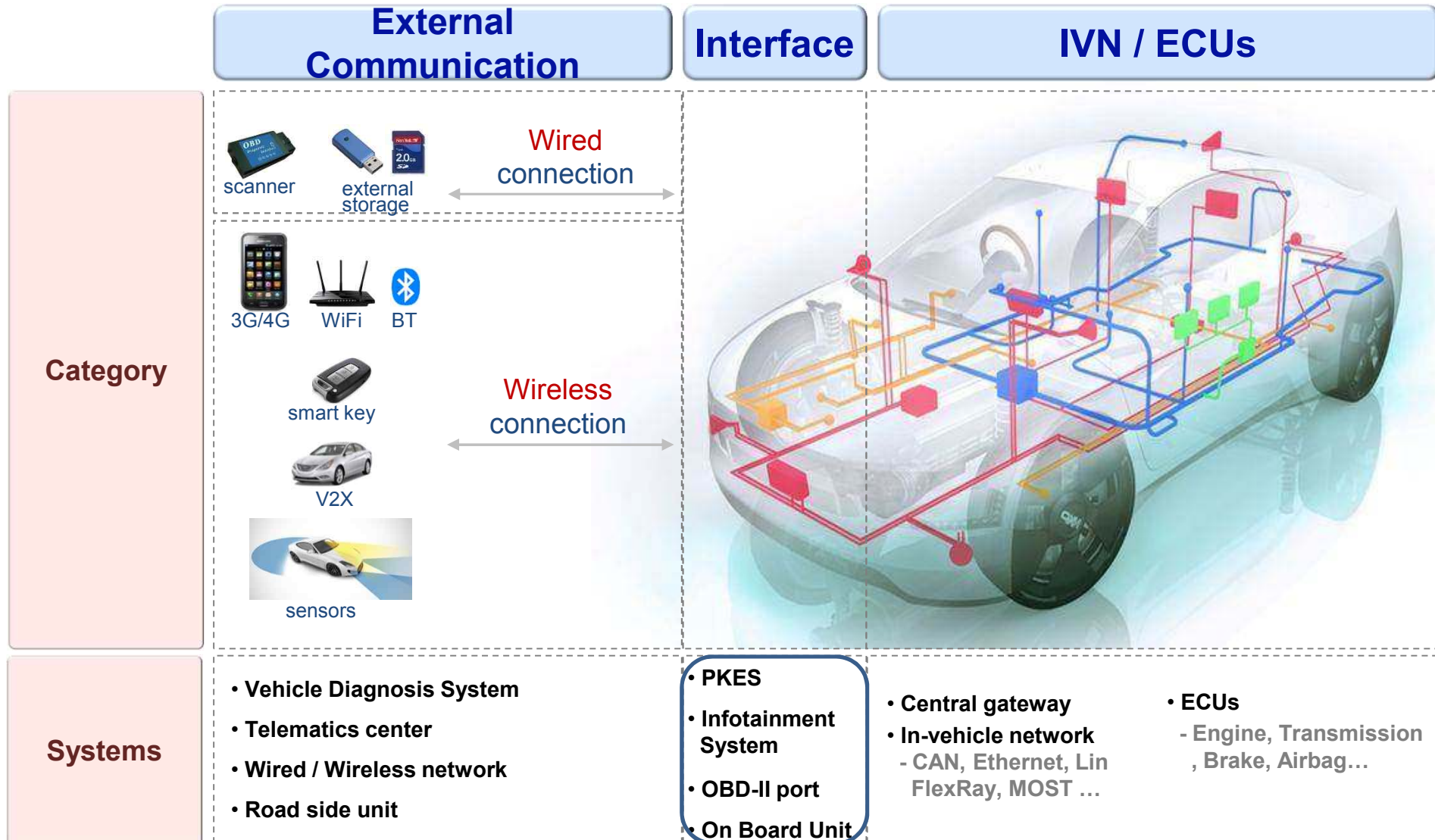
- A Vehicle improves a technology according to becoming an electronic system and connecting with each other



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Vehicle - Attack Surface & Cybersecurity Threat

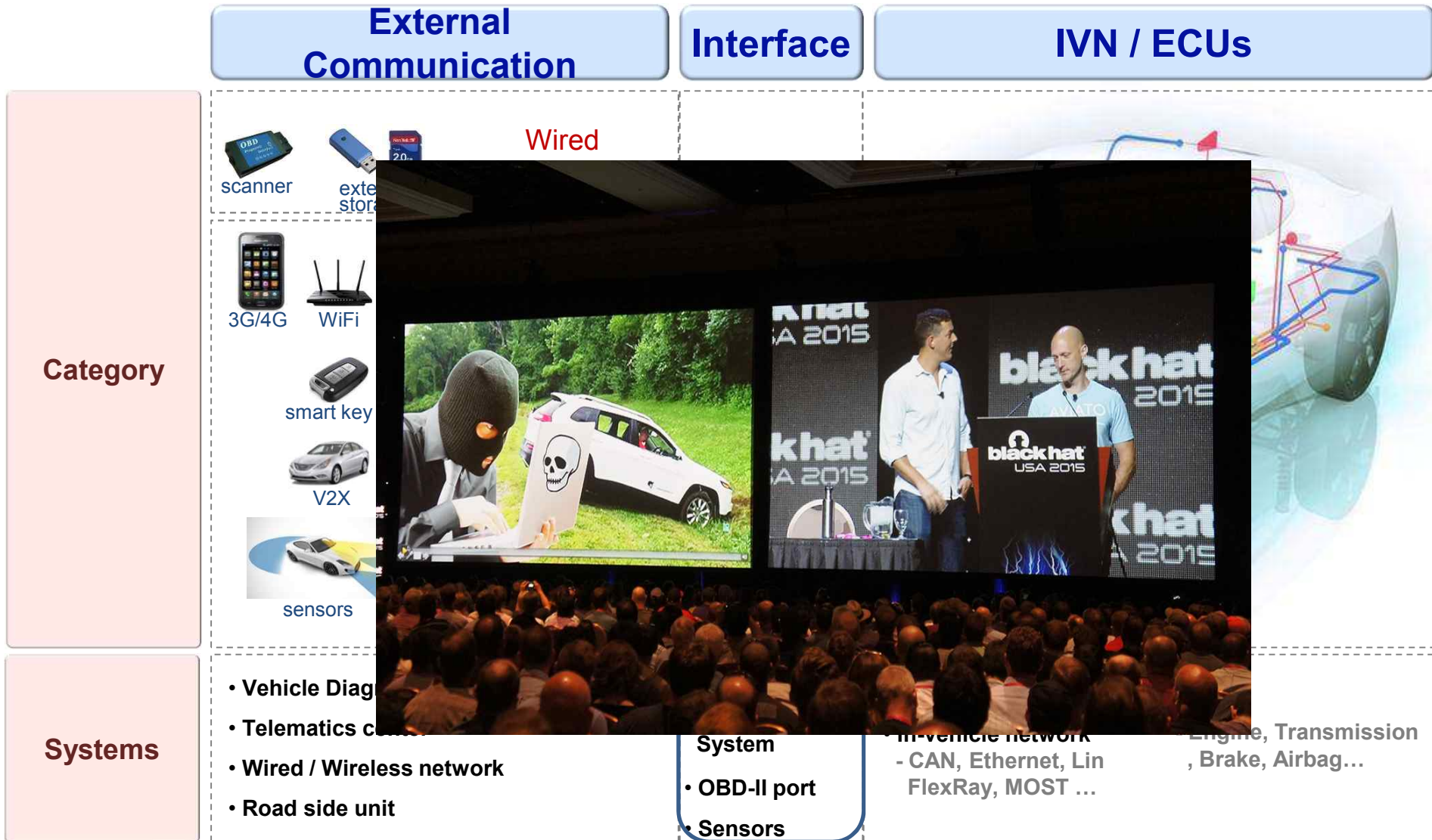
- An Attack Surface is enlarging according to increasing an external communication



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Vehicle - Attack Surface & Cybersecurity Threat

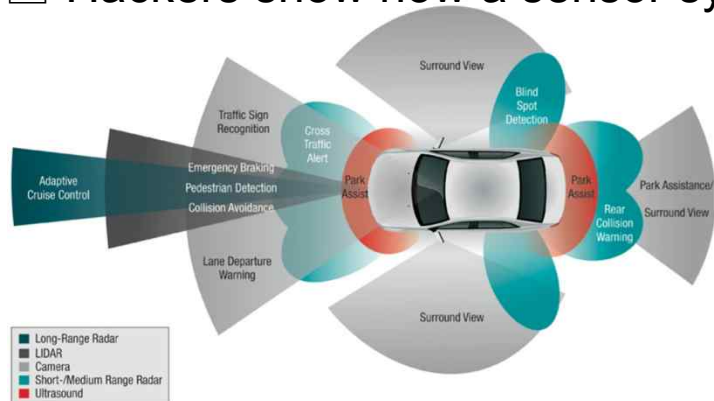
- A Cybersecurity Threat is coming to ours



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Vehicle - Autonomous Driving & Cybersecurity Threat

- An Autonomous Vehicle has a sensor system related to LIDAR and RADAR and Camera and Ultrasonic
- Hackers show how a sensor system can be tricked



Sensor	LIDAR	RADAR	Camera	Ultrasonic
Cost	+++	++	+	+
Size	++	+	++	+
Speed Detection	++	+++	+	+
Robust to weather	++	+++	+++	+++
Robust to day and night	+++	+++	+++	+++
Range	+++	+ / +++ / +++	++	+

+++ : High, ++ : Medium, + : Low



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EVITA project

- EVITA project identifies a cybersecurity requirement for a vehicle on-board network
- This project proposed an E/E Architecture and HSM class for vehicle cybersecurity

Overall



Project acronym: EVITA
Project title: E-safety vehicle intrusion protected applications
Project reference: 224275
Programme: Seventh Research Framework Programme (2007-2013) of the European Community
Objective: ICT-2007.6.2: ICT for cooperative systems
Contract type: Collaborative project
Start date of project: 1 July 2008
Duration: From July 2008 to December 2011 (42 months)

Summary of the EVITA project

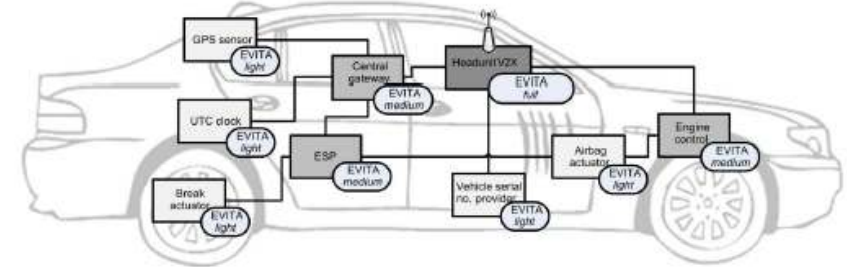
Period covered: from 1 July 2008 to 31 December 2011
Dissemination level: Public

Project coordinator: Fraunhofer Institute for Secure Information Technology (Germany)
Project partners: BMW Research and Technology (Germany)
 Continental Teves AG & Co. oHG (Germany)
 escrypt GmbH (Germany)
 EURECOM (France)
 Fraunhofer Institute for Systems and Innovation Research (Germany)
 Infineon Technologies AG (Germany)
 Institut Télécom (France)
 Katholieke Universiteit Leuven (Belgium)
 MIRA Ltd. (UK)
 Robert Bosch GmbH (Germany)
 TRIALOG (France)
 Fujitsu Semiconductor Europe GmbH (Germany)
 Fujitsu Semiconductor Embedded Solutions Austria GmbH (Austria)

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Project website: <http://evita-project.org>

Description

Proposed Architecture



Secure on-board unit

HSM	EVITA Full	EVITA Medium	EVITA Light
Internal NVM	Yes	Yes	Optional
Internal CPU	Programmable	Programmable	None
HW Crypto algo.	Asymmetric Crypto	Symmetric Crypto	Symmetric Crypto
RNG	TRNG	TRNG	PRNG
Counter	16X64bit	16X64bit	None

Hardware Security Module

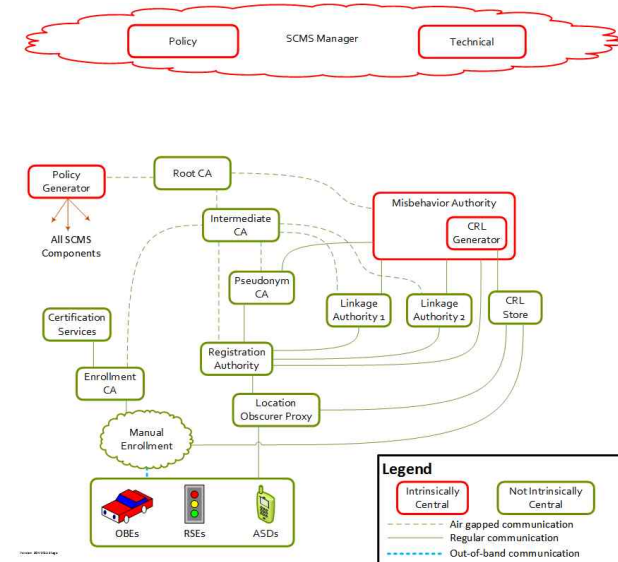


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V2X security – Security Credential Management System

- V2X security defines a specification for a secure communication

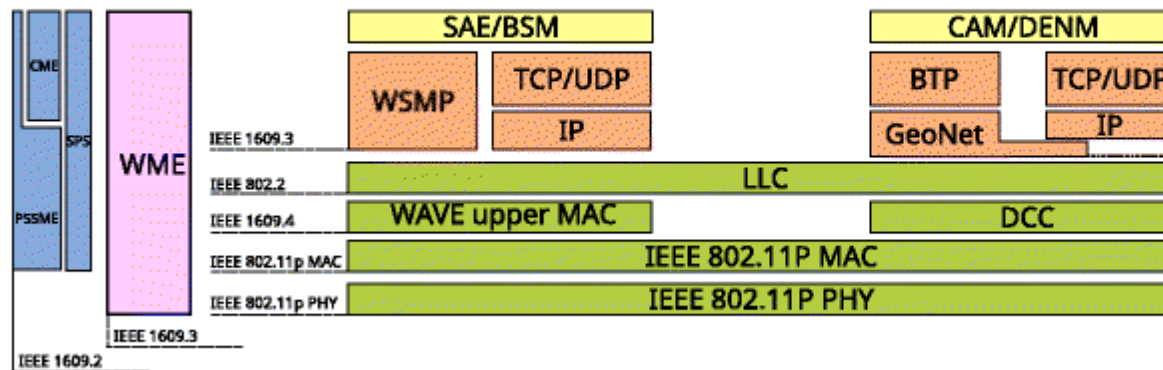
SCMS



V2X Standardization

IEEE WAVE

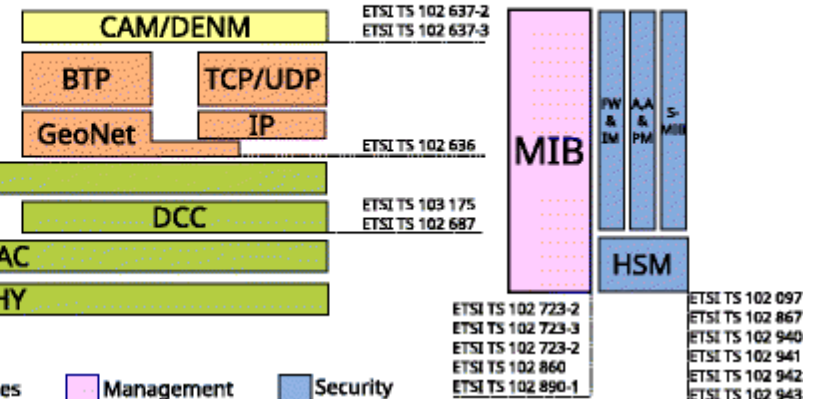
IEEE 1609.0



Access, Networking & Transport, Facilities, Management, Security

ETSI ITS

ETSI EN 302 665



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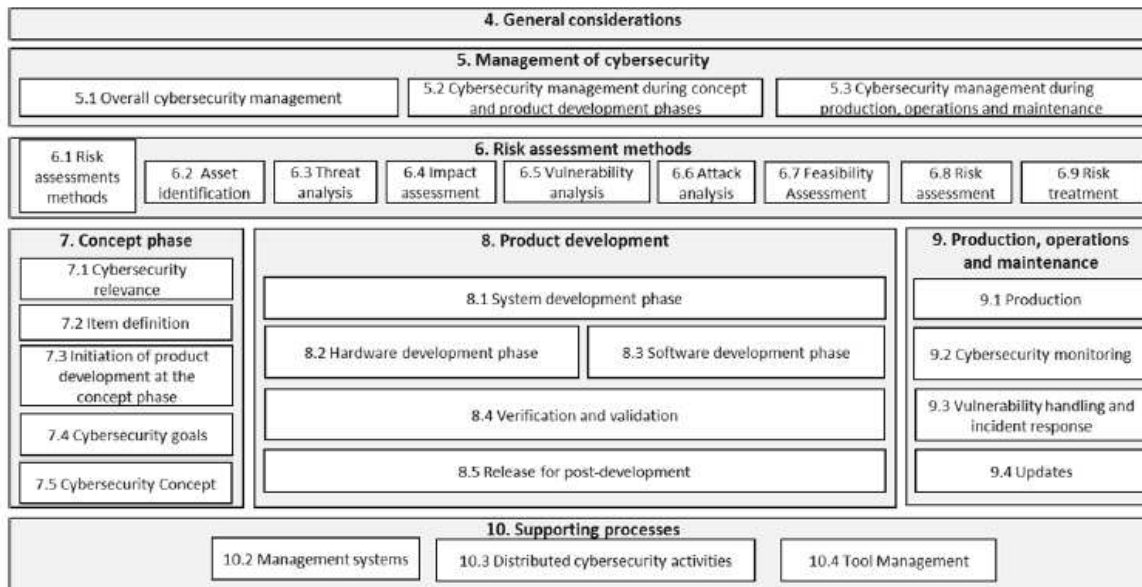
ITU-T SG17 Q13 Standardization

- ITU-T SG 17 Q13 standardization is developing a vehicle cybersecurity solution

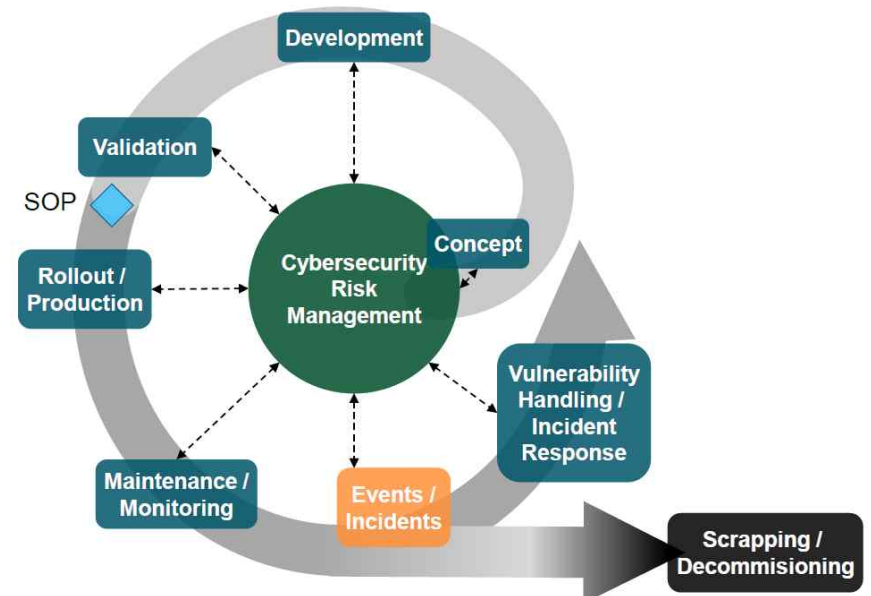
Standards Number	Keyword	Description	Schedule (due to)
X.1373	Secure OTA	Secure software update capability for intelligent transportation system communication devices	September 2020
X.itssec4	Intrusion Detection System	Methodologies for intrusion detection system on in-vehicle systems	??
X.itssec2	V2X Security	Security guidelines for V2X communication systems	??
X.itssec3	External Devices Security	Security requirements for vehicle accessible external devices	??
X.stcv	Security Threats	security threats in connected vehicles	March 2019
X.mdcv	Misbehavior Detection (Security-related)	security-related misbehavior detection mechanism based on big data analysis for connected vehicles	December 2020

ISO/SAE 21434 : Road Vehicles Cybersecurity Engineering

- ISO/SAE 21434 helps to keep a secure vehicle by removing a cybersecurity vulnerability
- ISO/SAE 21434 considers not only a cybersecurity but also a safety



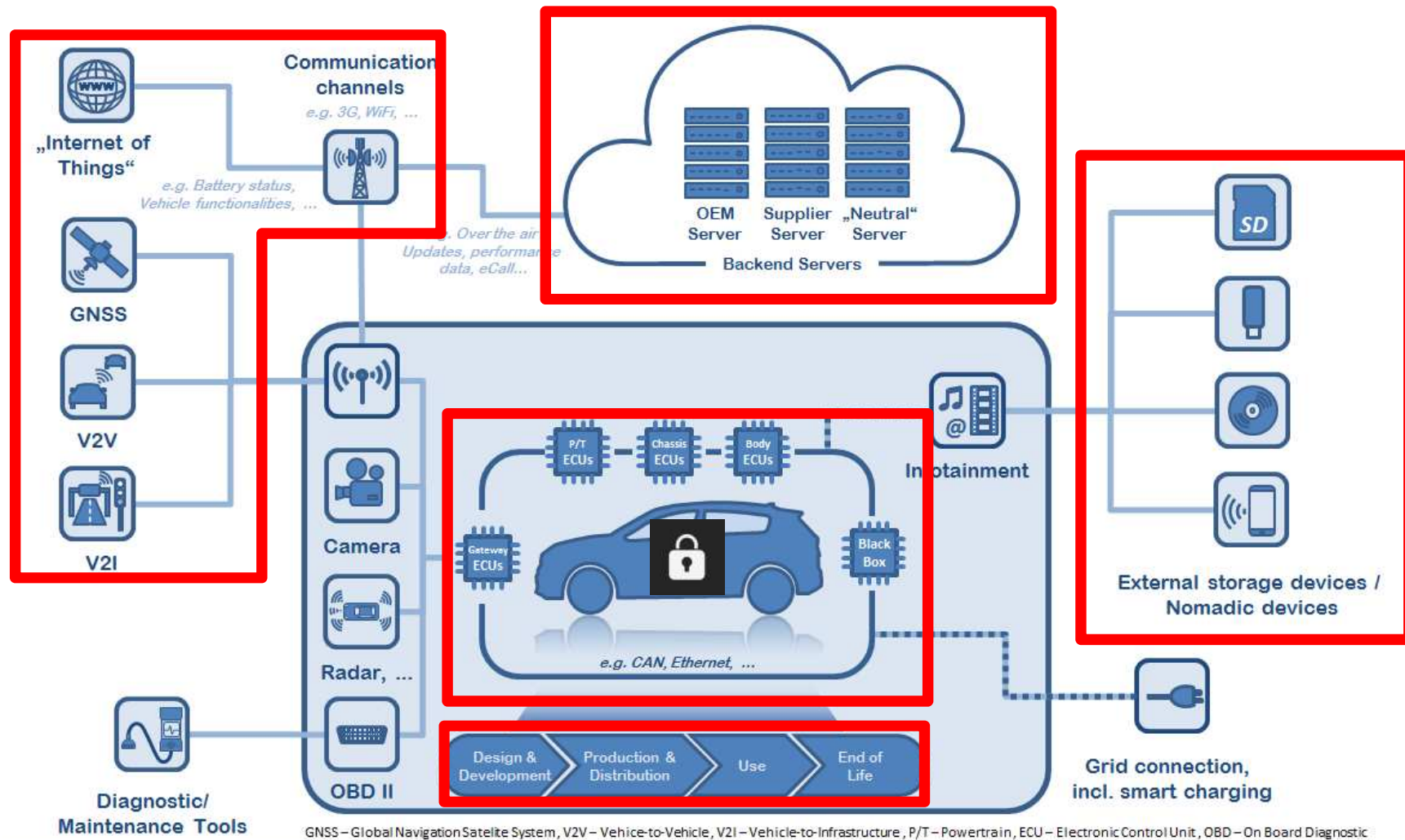
ISO/SAE 21434 overview



Cybersecurity lifecycle

Vehicle Cybersecurity Solution

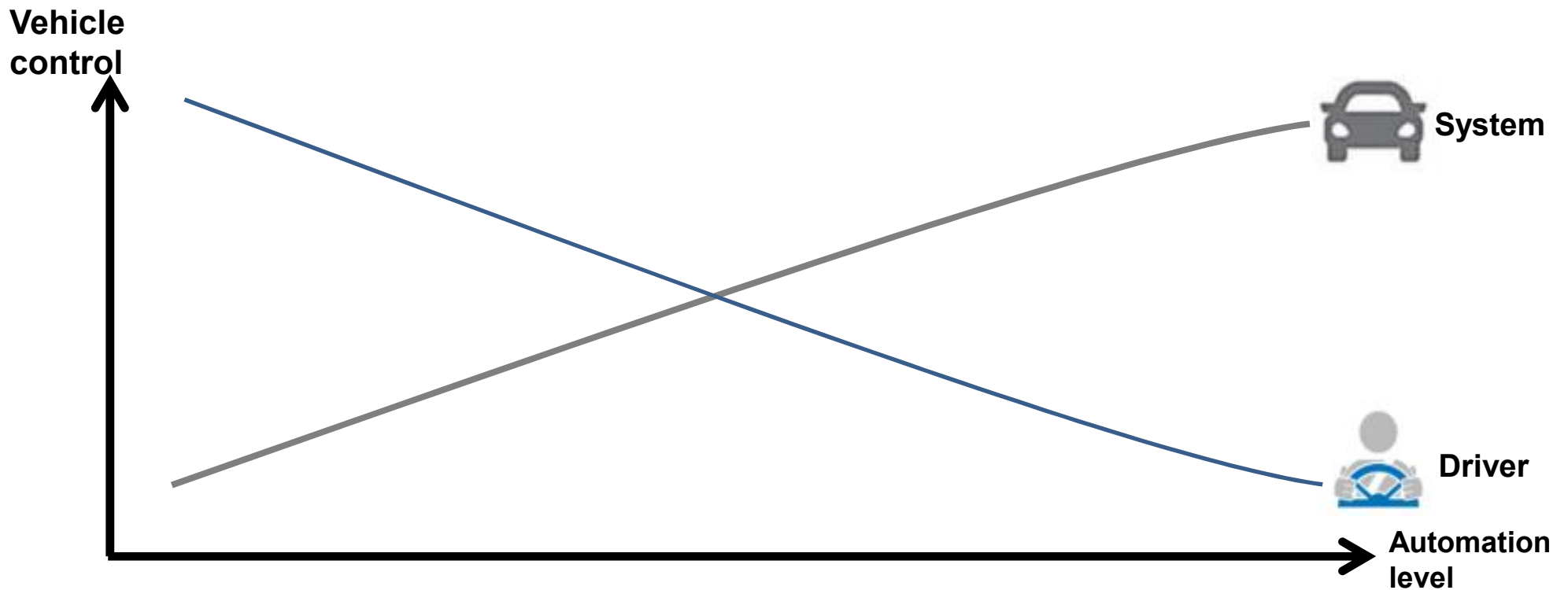
- A Standardization researches IDS, HSM, Secure OTA and V2X Security
- Vehicle Cybersecurity Solutions apply form a server to ECU for a security and safety



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Issues on Autonomous Vehicles

- Due to inherit danger of road vehicle, we need low latency connection with control system
- High & Full Automation Vehicle controls the vehicle dominant over human driver

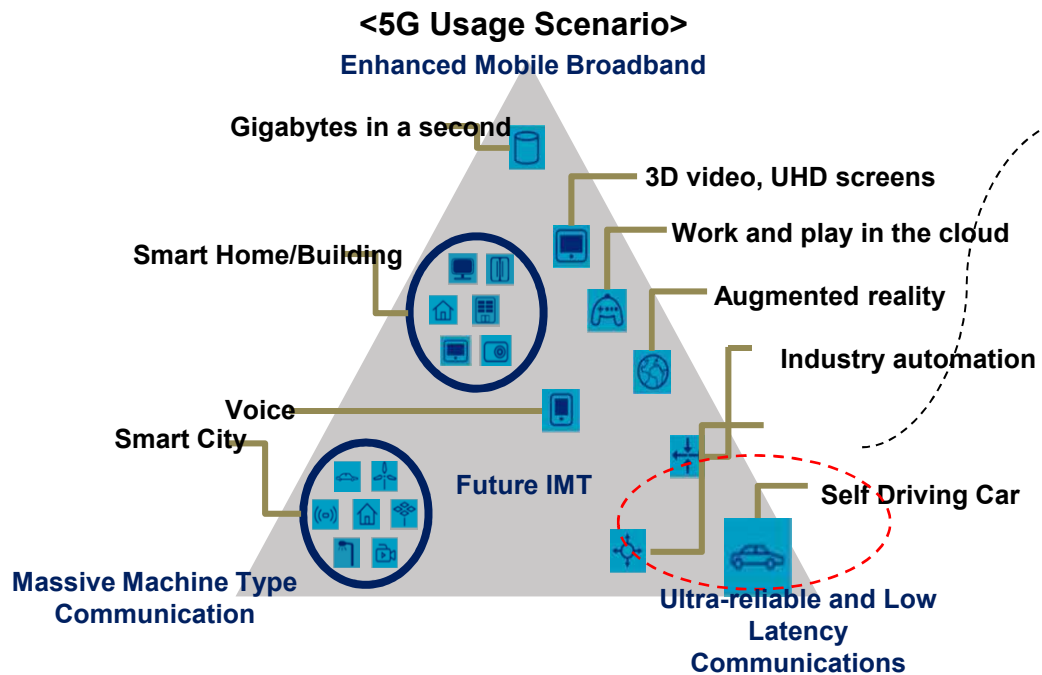


Issues on Autonomous Vehicles

■ 영상

Cybersecurity in Autonomous Vehicle – 5G network

- An Autonomous Vehicle's requirement meets data latency within 1 ms
- High & Full Automation Vehicle requires ultra-reliable and low latency communications



TS 22.186 Requirement for autonomous driving

Service	Required Latency (ms)	Data Rate (Mbps)
Platooning	10	65
Advanced driving	3	53
Extended sensors	3	1000
Remote driving	5	UL:25 DL:1



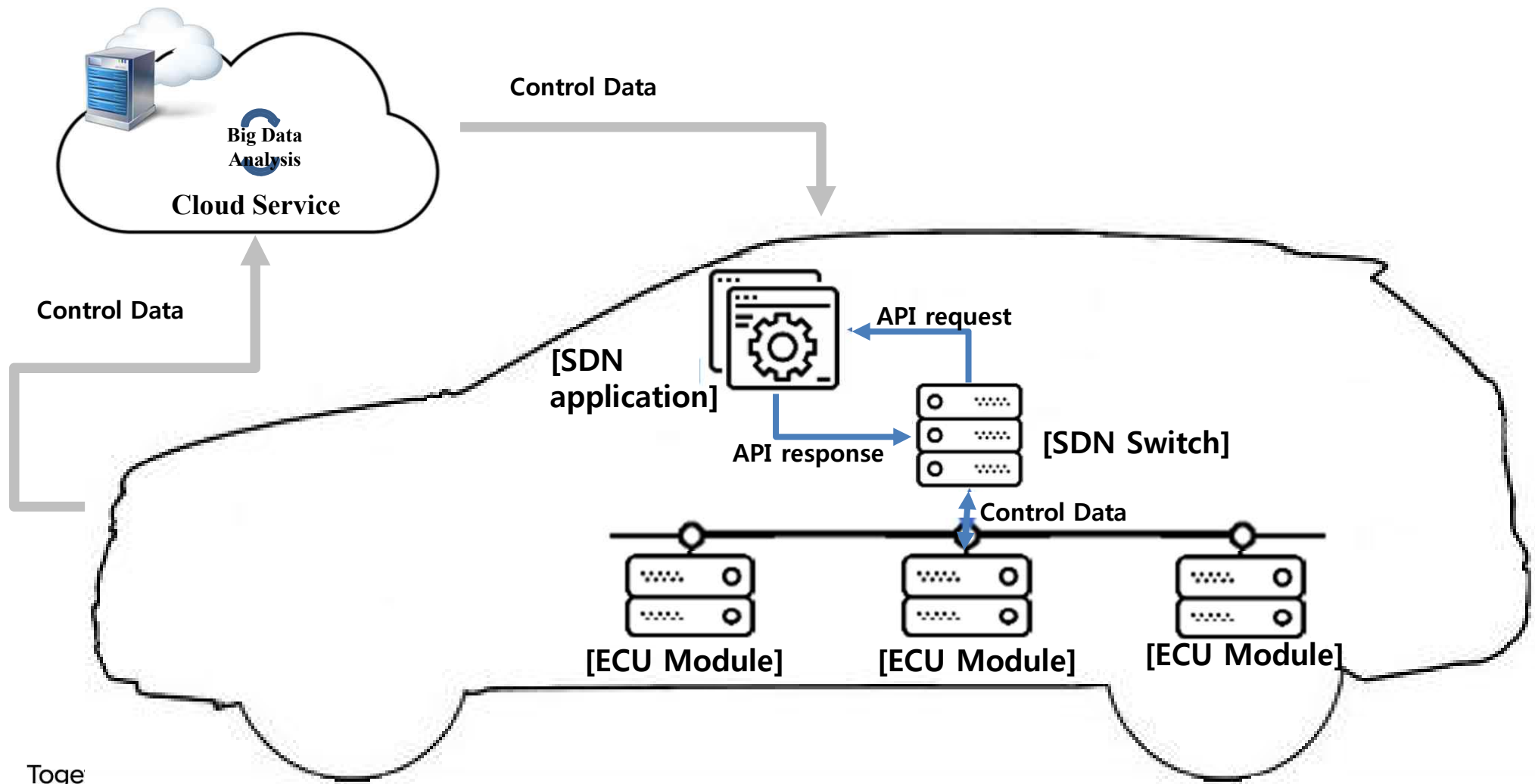
구분	WAVE	LTE (Rel.15)	5G (Rel.16)
Data Rate	>54Mbps	>300Mbps	>20Gbps
Latency	~10ms	20~30ms	~1ms
Coverage	250~300m	Approx. several km	Approx. several km
Mobility	>200km/h	>160km/h	>500km/h

Source : 5G use cases and requirements, NOKIA

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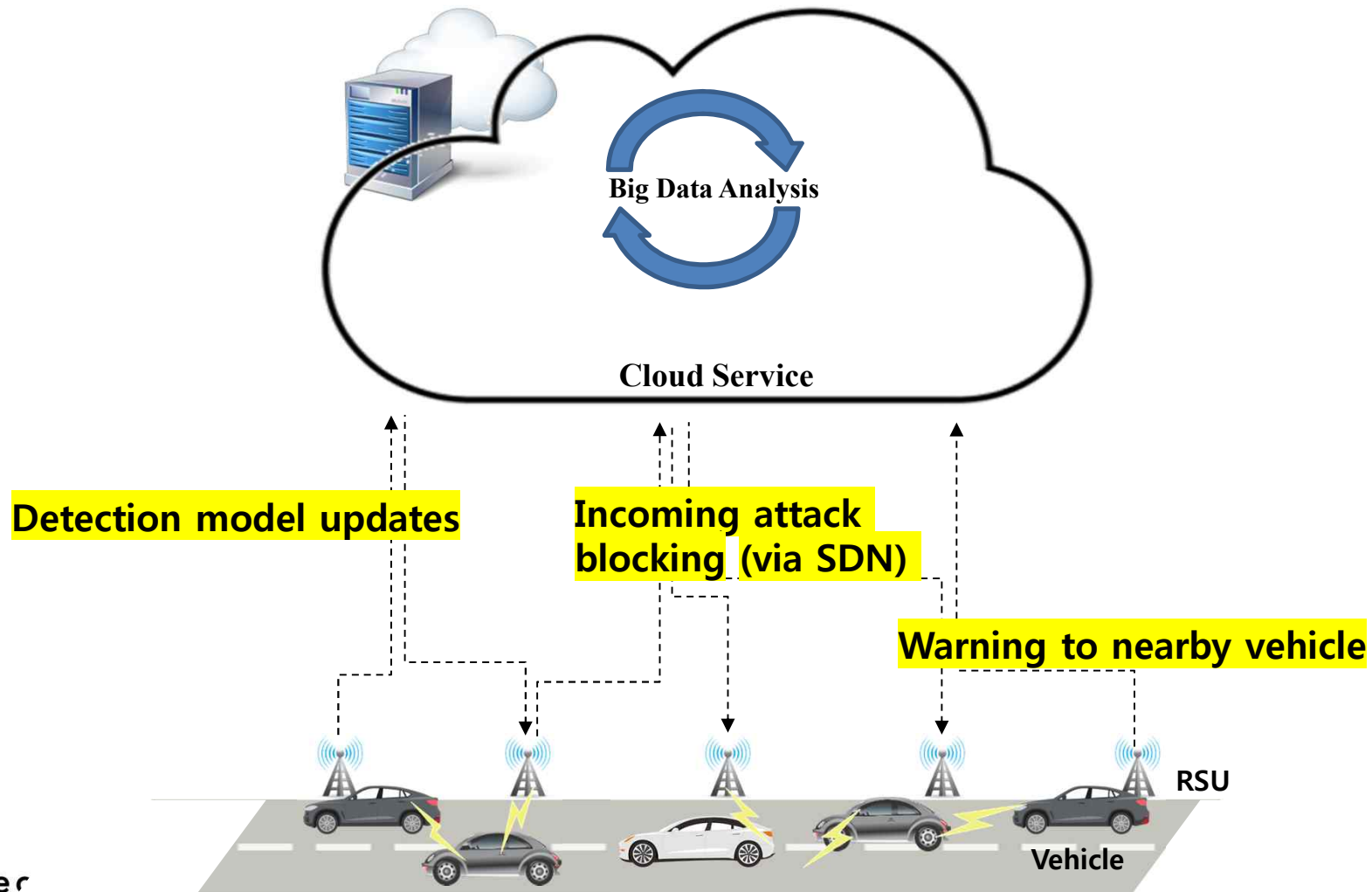
Cybersecurity in Autonomous Vehicle – SDN in-vehicle network

- An Autonomous Vehicle needs to take a reliable and real-time control by system
- A Software Defined Network provides a flexibility, reliability and low-latency



Intrusion Response System for autonomous vehicle

- '5G and SDN' based IRS is optimal solution to block cyber attacks in autonomous vehicles
 - allowing real-time intrusion response from inside and outside attacks
 - quick propagation of warning message in a wide area through 5G Network.



Conclusion

- ✓ **Paradigm Shift in the Automotive Industry**
- ✓ **Increased Cybersecurity Threats**
- ✓ **Standardization for cybersecurity**
- ✓ **Cybersecurity Issues in an Autonomous Vehicle**
- ✓ **A Cybersecurity Solution in an Autonomous Vehicle**